# Mathematical Statistics 

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## Contents

Preface ..... 7
1 Random variables ..... 9
1.1 Introduction ..... 9
1.2 Moments ..... 11
1.3 Quantile function ..... 16
2 Random vectors ..... 19
2.1 Introduction ..... 19
2.2 Variance matrix ..... 20
2.3 Independence ..... 22
2.4 Conditional density ..... 23
2.5 Approximation of random variables ..... 24
2.6 Correlation coefficient ..... 26
2.7 Coefficient of multiple correlation ..... 26
2.8 Coefficient of partial correlation ..... 29
2.9 Multinomial distribution ..... 30
3 Transformations ..... 33
3.1 Transformations of random variables ..... 33
3.2 Transformations of random vectors ..... 34
3.3 Functions of random variables ..... 37
3.3.1 Method of calculation ..... 37
3.3.2 Sum of variables ..... 37
3.3.3 Quotient of random variables ..... 40
3.4 Transformation stabilizing variance ..... 41
4 Random sample ..... 45
4.1 Simple random sample ..... 45
4.2 Ordered random sample ..... 46
4.3 Random sample from the normal distribution ..... 48
5 Estimating theory ..... 51
5.1 Statistics and unbiased estimators ..... 51
5.2 Examples ..... 51
5.3 Consistent estimators ..... 54
5.3.1 Definition ..... 54
5.3.2 Example ..... 55
6 Empirical estimators ..... 57
6.1 Empirical distribution function ..... 57
6.2 Sample quantiles ..... 57
6.3 Sample correlation coefficient ..... 58
6.4 Sample coefficient of multiple correlation ..... 61
6.5 Sample coefficient of partial correlation ..... 62
7 Interval estimators ..... 65
8 Testing hypotheses ..... 67
9 One-sample problem ..... 71
9.1 Descriptive statistics ..... 71
9.1.1 Graphs ..... 71
9.2 One-sample Kolmogorov-Smirnov test ..... 71
9.3 One-sample t test ..... 73
9.4 Variance ..... 75
9.5 Sign test ..... 76
9.6 One-sample Wilcoxon test ..... 77
9.7 Hodges-Lehmann estimator ..... 79
10 Discrete one-sample problem ..... 83
10.1 Confidence intervals and tests for $p$ ..... 83
10.1.1 Tests in binomial distribution ..... 83
10.1.2 Wald confidence interval ..... 84
10.1.3 Wilson confidence interval ..... 84
10.2 Confidence intervals for parameter $\lambda$ ..... 85
10.2.1 Standard confidence interval ..... 85
10.2.2 Score confidence interval ..... 85
10.2.3 Clopper-Pearson confidence interval ..... 86
10.3 Tests $\chi^{2}$ when parameters are known ..... 86
10.4 Tests $\chi^{2}$ when parameters are not known ..... 87
10.5 Test of independence ..... 89
$10.62 \times 2$ tables ..... 92
10.6.1 Test $\chi^{2}$ ..... 92
10.6.2 Odds ratio ..... 93
10.6.3 Fisher's factorial test ..... 96
11 Paired problem ..... 99
11.1 Paired t test ..... 99
11.2 Paired sign test ..... 100
11.3 Paired Wilcoxon test ..... 100
11.4 Spearman correlation coefficient ..... 100
12 Discrete paired problem ..... 103
12.1 McNemar test ..... 103
12.2 Stuart test ..... 105
13 Two-sample problem ..... 107
13.1 Descriptive statistics ..... 107
13.2 Two-sample Kolmogorov-Smirnov test ..... 108
13.3 Two-sample t test ..... 111
13.4 Two-sample Welch test ..... 113
13.5 Test of equality of variances ..... 115
13.6 Two-sample Wilcoxon test ..... 117
14 Discrete two-sample problem ..... 121
14.1 Testing homogeneity of two binomial distributions ..... 121
14.2 Confidence interval for difference of probabilities ..... 124
14.3 Confidence interval for ratio of probabilities ..... 125
14.4 Test of hypothesis $\lambda_{1} / \lambda_{2}=r$ ..... 126
15 Problem of $k$ samples ..... 129
15.1 Linear model ..... 129
15.2 Weighted average ..... 133
15.3 Extrapolation in linear model ..... 134
15.4 Submodel of the linear model ..... 135
15.5 One-way analysis of variance ..... 137
15.6 Tests of homogeneity of variances ..... 143
15.7 Analysis when variances are not equal ..... 145
15.8 Kruskal-Wallis test ..... 146
16 Discrete problem of $k$ samples ..... 151
16.1 Testing homogeneity by method $\chi^{2}$ ..... 151
16.2 Test based on weighted average ..... 152
16.3 Remark on tests ..... 153
16.4 Example ..... 154
17 Calculation of power of test ..... 157
17.1 One-sample test ..... 157
17.2 Paired t-test ..... 158
17.3 Two-sample t-test ..... 159
17.4 Analysis of variance ..... 160
17.5 Test for homogeneity of two binomial distributions ..... 160
18 Linear regression models ..... 163
18.1 Introduction ..... 163
18.2 Basic regression models ..... 163
18.2.1 Line with zero intercept ..... 163
18.2.2 Regression line ..... 164
18.2.3 Quadratic regression ..... 168
18.2.4 Two independent variables ..... 171

References 173
Author Index 176
Topic Index 178

## Preface

Mathematical Statistics I - Statistical Methods is the course in winter semester in the frame $4 / 2$ hours. It is devoted to the students who intend to continue to study probability, mathematical statistics, and econometry.

The course contains also some practical statistical methods and numerical examples. However, their number is very limited, because they will be trained in a special course. We expect that the material will be complemented by programme R.

The end of a proof is denoted by $\square$ and the end of an example by $\diamond$.

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## Chapter 1

## Random variables

### 1.1 Introduction

In our life we frequently meet random events. To work with them mathematically, it is necessary to build a model for them. All possible results of an experiment constitute a space of elementary events $\Omega$. Elements of the space $\Omega$ are denoted by $\omega$. If the space $\Omega$ is too rich, we cannot deal with individual elementary events $\omega$ separately. A useful mathematical model uses only such sets of elementary events which form $\sigma$-algebra. Remember that $\sigma$-algebra is a non-empty system of subsets such that
(i) If $A \in \mathcal{A}$, then $\Omega \backslash A \in \mathcal{A}$.
(ii) If $A_{1} \in \mathcal{A}, A_{2} \in \mathcal{A}, \ldots$, then $\cup A_{i} \in \mathcal{A}$.

Here $\Omega \backslash A=A^{c}$ is the complement of the set $A$. From the definition of $\sigma$-algebra it is possible to derive its further properties, especially:
(iii) $\emptyset \in \mathcal{A}, \Omega \in \mathcal{A}$.
(iv) If $A_{1} \in \mathcal{A}, A_{2} \in \mathcal{A}, \ldots$, then also $\cap A_{i} \in \mathcal{A}$.

The pair $(\Omega, \mathcal{A})$ is called measurable space. Assume now, that to every set $A \in \mathcal{A}$ it is possible to define a number $\mathrm{P}(A)$ such that the following conditions are fulfilled:
(a) $\mathrm{P}(A) \geq 0$ for every $A \in \mathcal{A}$.
(b) If $A_{1}, A_{2}, \ldots$ are disjoint sets belonging to $\mathcal{A}$, then $\mathrm{P}\left(\cup A_{i}\right)=\sum \mathrm{P}\left(A_{i}\right)$.
(c) $\mathrm{P}(\Omega)=1$.

We get function P defined on $\mathcal{A}$, which is called probability measure (shortly probability). Conditions (a)-(c) can be formulated in words that probability is $\sigma$-additive normed set function. The subsets of the space $\Omega$ belonging to $\mathcal{A}$ are called random events.

We can ask why probability is introduced in such a complicated way. Why probability is not defined for every subset of the space $\Omega$ ? Generally, it is not possible and this answer is related to the existence of non-measurable sets.

It is worth to notice that this definition of probability contains no instruction how to calculate it. This problem is, however, solved in other courses of mathematical statistics.

Recall that Borel $\sigma$-algebra $\mathcal{B}_{n}$ of subsets of $n$-dimensional Euclidean space $\mathbb{R}_{n}$ is the minimal $\sigma$-algebra, which contains all open intervals. Instead of $\mathcal{B}_{1}$ we usually write $\mathcal{B}$ and instead of $\mathbb{R}_{1}$ we write $\mathbb{R}$.

We say that $X$ is a measurable mapping of the space $(\Omega, \mathcal{A}, \mathrm{P})$ into $(\mathbb{R}, \mathcal{B})$, if

$$
\{\omega: X(\omega) \in B\} \in \mathcal{A} \quad \text { for every set } \quad B \in \mathcal{B}
$$

A measurable mapping $X$ is called random variable. The random variable $X$ is a function defined on the space $\Omega$ and its values $X(\omega)$ are real numbers. Of course, the definition implies that the function must be measurable.

The distribution function $F$ of the random variable $X$ is defined by the formula

$$
F(x)=\mathrm{P}(X \leq x), \quad x \in \mathbb{R}
$$

More precisely, instead of $\mathrm{P}(X \leq x)$ we should write $\mathrm{P}\{\omega: X(\omega) \leq x\}$, but the argument $\omega$ is usually dropped. On the measurable space $(\mathbb{R}, \mathcal{B})$ there exists a probability measure corresponding to the distribution function P and it is called the distribution of the random variable $X$.

Some distributions have their fixed abbreviations. For example, the normal distribution with parameters $\mu$ and $\sigma^{2}$ is denoted by $\mathbf{N}\left(\mu, \sigma^{2}\right)$. The fact that the random variable $X$ has the distribution $\mathrm{N}\left(\mu, \sigma^{2}\right)$ is written as $X \sim \mathrm{~N}\left(\mu, \sigma^{2}\right)$. Analogous abbreviation is used also in other cases.

The mean value of the random variable $X$ is

$$
\begin{equation*}
\mathrm{E} X=\int_{\Omega} X(\omega) \mathrm{dP}(\omega) \tag{1.1}
\end{equation*}
$$

if this integral exists. The denotation $E$ is abbreviation of the word expectation. Formula (1.1) is starting point for many theoretical considerations but it is not suitable for practical calculations. The reason is that the measure P is only rarely known. It is a good luck that $\mathrm{E} X$ can be also expressed using integral where the measure is described only by distribution function.

Theorem 1.1 We have

$$
\begin{equation*}
\mathrm{E} X=\int_{-\infty}^{\infty} x \mathrm{~d} F(x) \tag{1.2}
\end{equation*}
$$

If $g$ is such a function that $\mathrm{E} g(X)$ exists, then we have

$$
\begin{equation*}
\mathrm{E} g(X)=\int_{-\infty}^{\infty} g(x) \mathrm{d} F(x) \tag{1.3}
\end{equation*}
$$

Proof. See Anděl (2007).
Formula (1.3) is very important. A direct calculation of $\mathrm{E} g(X)$ using only (1.2) would need the following steps. We would define $Y=g(X)$, then from the known distribution function $F$ of the variable $X$ we would have to calculate the distribution function $G$ of the variable $Y$ and finally using(1.2) we would get $\mathrm{E} Y=\int_{-\infty}^{\infty} y \mathrm{~d} G(y)$. However, calculation of $G$ is usually very complicated. Thus theorem that integral $\int y \mathrm{~d} G(y)$ is equal to considerably simpler $\int g(x) \mathrm{d} F(x)$ is really very important.

Practically we use only two families of distribution functions. If there exists such a function $f$, that for every real $x$

$$
\begin{equation*}
F(x)=\int_{-\infty}^{x} f(t) \mathrm{d} t \tag{1.4}
\end{equation*}
$$

holds, then we say that $F$ corresponds to a continuous distribution. The function $f$ is called density of the distribution. Since $F$ is nondecreasing, the density $f$ is nonnegative almost everywhere. Using (1.4) we see that $f(x)=F^{\prime}(x)$ almost everywhere.

The second case arises when $F$ je a step funcion. It means that there exists maximally counted set of numbers $x_{1}, x_{2}, \ldots$, in which $F$ has steps $p_{1}, p_{2}, \ldots$ Otherwise $F$ is constant. So we have $\sum p_{i}=1$. In this case we say that $F$ correspons to a discrete distribution.

Formula (1.3) implies that for the continuous distribution we have

$$
\mathrm{E} g(X)=\int_{-\infty}^{\infty} g(x) f(x) \mathrm{d} x
$$

and for the discrete distribution we have

$$
\mathrm{E} g(X)=\sum_{i} g\left(x_{i}\right) p_{i}
$$

Notice that (1.3) enables to calculate probability $\mathrm{P}(X \in B)$ that $X$ belongs to set $B \in \mathcal{B}$. If we take $g=\chi_{B}$ (the characteristic function of the set $B$ ), then from(1.3) we get

$$
\mathrm{P}(X \in B)=\int_{B} \mathrm{~d} F(x) .
$$

In the continuous case we have

$$
\mathrm{P}(X \in B)=\int_{B} f(x) \mathrm{d} x
$$

and in the discrete case

$$
\mathrm{P}(X \in B)=\sum_{\left\{i: x_{i} \in B\right\}} p_{i}
$$

### 1.2 Moments

Let $X$ be a random variable. Moment of the $k$-th order is

$$
\begin{equation*}
\mu_{k}^{\prime}=\mathrm{E} X^{k}, \quad k=0,1, \ldots \tag{1.5}
\end{equation*}
$$

and central moment of the $k$-th order is

$$
\begin{equation*}
\mu_{k}=\mathrm{E}(X-\mathrm{E} X)^{k}, \quad k=0,1, \ldots \tag{1.6}
\end{equation*}
$$

It is clear that the moments can be defined only in the cases when the integrals (1.5) and (1.6) exist. Further we define absolute moments

$$
\mu_{k}^{\mathrm{abs}}=\mathrm{E}|X|^{k}, \quad k \geq 0
$$

Here $\mu_{1}^{\prime}=\mathrm{E} X$ is expectation and it is shortly denoted by $\mu$. We have $\mu_{0}^{\prime}=1, \mu_{0}=1$, $\mu_{1}=0$. An important moment is $\mu_{2}$. It is called variance and denoted by $\sigma^{2}$. From formula (1.6) we get that

$$
\sigma^{2}=\mathrm{E} X^{2}-(\mathrm{E} X)^{2}
$$

If we want to emphasize that it is the variance of the random variable $X$, we write $\sigma_{X}^{2}$ or $\operatorname{var} X$ instead of $\sigma^{2}$. The parameter $\sigma$ is called standard deviation.

Using binomial theorem we get from (1.6)

$$
\mu_{k}=\sum_{i=0}^{k}\binom{k}{i}(-1)^{i} \mu_{k-i}^{\prime} \mu^{i} .
$$

Thus

$$
\begin{aligned}
& \mu_{3}=\mu_{3}^{\prime}-3 \mu_{2}^{\prime} \mu+2 \mu^{3} \\
& \mu_{4}=\mu_{4}^{\prime}-4 \mu_{3}^{\prime} \mu+6 \mu_{2}^{\prime} \mu^{2}-3 \mu^{4}
\end{aligned}
$$

If $\sigma^{2}>0$ and if the moments $\mu_{3}$ and $\mu_{4}$ exist we define kurtosis $\alpha_{3}$ and skewness $\alpha_{4}$ using formulas

$$
\alpha_{3}=\frac{\mu_{3}}{\sigma^{3}}, \quad \alpha_{4}=\frac{\mu_{4}}{\sigma^{4}}
$$

Theorem 1.2 Define $Y=a+b X$. If $\mathrm{E} X$ exists, then $\mathrm{E} Y=a+b \mathrm{E} X$. If $\mathrm{E} X^{2}<\infty$ then $\operatorname{var} Y=b^{2} \operatorname{var} X$.

Proof. Formulas follow by easy insertion.
Especially for $b=1$ we have $\operatorname{var}(a+X)=\operatorname{var} X$. We see that variance is shift invariant.

Theorem 1.3 Kurtosis and skewness fulfill the inequality

$$
\alpha_{4}-\alpha_{3}^{2} \geq 1
$$

Proof. Let $\mathrm{E} X^{4}<\infty$. Define $Y=X-\mathrm{E} X$. Then $\mathrm{E} Y=0$ and $\mathrm{E} Y^{k}=\mathrm{E}(X-\mathrm{E} X)^{k}$ for every $k$. Choose real numbers $a, b, c$ and introduce the vector $\boldsymbol{u}=(a, b, c)^{\prime}$. Then we have

$$
\begin{aligned}
0 & \leq \mathrm{E}\left(a+b Y+c Y^{2}\right)^{2}=\mathrm{E}\left(a^{2}+2 a b Y+2 a c Y^{2}+b^{2} Y^{2}+2 b c Y^{3}+c^{2} Y^{4}\right) \\
& =a^{2}+2 a c \mu_{2}+b^{2} \mu_{2}+2 b c \mu_{3}+c^{2} \mu_{4}=\boldsymbol{u}^{\prime} \boldsymbol{M} \boldsymbol{u}
\end{aligned}
$$

where

$$
\boldsymbol{M}=\left(\begin{array}{ccc}
1 & 0 & \mu_{2} \\
0 & \mu_{2} & \mu_{3} \\
\mu_{2} & \mu_{3} & \mu_{4}
\end{array}\right)
$$

The matrix $\boldsymbol{M}$ is symmetric. The inequality $\boldsymbol{u}^{\prime} \boldsymbol{M} \boldsymbol{u} \geq 0$ holding for every vector $\boldsymbol{u}$ proves that $\boldsymbol{M}$ is positive semidefinite. Its determinant is thus nonnegative. This implies

$$
0 \leq|\boldsymbol{M}|=\mu_{2} \mu_{4}-\mu_{3}^{2}-\mu_{2}^{3}
$$

which gives

$$
\mu_{2} \mu_{4}-\mu_{3}^{2} \geq \mu_{2}^{3}
$$

We divide the last inequality by $\mu_{2}^{3}$, and this gives the assertion of the theorem.
Some distributions have moments of all orders, e.g. rectangular distribution $\mathrm{R}(0,1)$ with the density

$$
f(x)= \begin{cases}1 & \text { for } x \in(0,1) \\ 0 & \text { for } x \notin(0,1)\end{cases}
$$

We shall quite often work with densities that are nonvanishing only on a set $M$. Then we write only the formula for density $f(x)$ for $x \in M$. If we do not introduce formula for $x \notin M$, then we understand $f(x)=0$ for $x \notin M$. There are distributions where even the moment of the first order does not exist. This is the case of Cauchy distribution $\mathrm{C}(a, b)$ with the density

$$
f(x)=\frac{1}{\pi} \frac{b}{b^{2}+(x-a)^{2}}, \quad x \in \mathbb{R}, \quad b>0 .
$$

Let us mention that this is not the worst case. If we consider absolute moments $\mu_{k}^{\text {abs }}$ for all nonnegative $k$ (not only for nonnegative integers), the distribution $\mathrm{C}(a, b)$ would have finite absolute moments $\mu_{k}^{\text {abs }}$ for $k \in[0,1)$. But the distribution with the density

$$
f(x)=\frac{1}{2|x| \ln ^{2}|x|} \quad \text { for }|x|>\mathrm{e}
$$

has no finite absolute moments of the $k$-th order for $k>0$. (See Stoops, Barr 1971.)
In connection with moments some important problems have been formulated. We can ask, for example, if a distribution having all moments $\mu_{k}^{\prime}(k=0,1, \ldots)$ finite is uniquely determined. The answer is: sometimes yes, sometimes not. Consider the density of the log-normal distribution

$$
p_{1}(x)=\frac{1}{\sqrt{2 \pi} x} \exp \left\{-\frac{1}{2} \ln ^{2} x\right\} \quad \text { for } x>0
$$

and the density defined by the formula

$$
p_{2}(x)=[1+a \sin (2 \pi \ln x)] p_{1}(x) \quad \text { for } x>0,
$$

where $a \in[-1,1]$ is an arbitrary number. Both the densities have the same series of the moments $\mu_{0}^{\prime}, \mu_{1}^{\prime}, \ldots$. This situation is quite unpleasant since the lognormal distribution is frequently used in theory as well as in practical applications. We have shown that this distribution cannot be characterized by its moments.

However, many distributions are determined uniquely by their moments. In many cases the following theorem is used.

Theorem 1.4 Let $\mu_{1}^{\prime}, \mu_{2}^{\prime}, \ldots$ be a sequence of moments. If the series

$$
\sum_{k=1}^{\infty} \frac{\mu_{k}^{\prime}}{k!} t^{k}
$$

for some $t>0$ converges absolutely, then the given series of the moments determines the distribution function uniquely.

Proof. See Rao (1978).
The condition introduced in Theorem 1.4 implies that the normal distribution $\mathbf{N}\left(\mu, \sigma^{2}\right)$ with the density

$$
f(x)=\frac{1}{\sqrt{2 \pi} \sigma} \exp \left\{-\frac{(x-\mu)^{2}}{2 \sigma^{2}}\right\}, \quad x \in \mathbb{R}, \quad \sigma>0
$$

is determined uniquely by its moments. We can see it on the distribution $\mathrm{N}\left(0, \sigma^{2}\right)$, the moments of which are

$$
\mu_{2 k-1}^{\prime}=0, \quad \mu_{2 k}^{\prime}=\frac{(2 k)!\sigma^{2 k}}{k!2^{k}} \quad \text { for } k=1,2, \ldots
$$

Since the distribution $\mathbf{N}\left(0, \sigma^{2}\right)$ has vanishing expectation, the moments $\mu_{k}^{\prime}$ are the same as $\mu_{k}$.

If $\mu=0, \sigma^{2}=1$, we have the standard normal distribution. Its density is

$$
\varphi(x)=\frac{1}{\sqrt{2 \pi}} \mathrm{e}^{-x^{2} / 2}
$$

and the distribution function

$$
\Phi(x)=\int_{-\infty}^{x} \varphi(u) \mathrm{d} u
$$

The function $\varphi$ is even, because $\varphi(-x)=\varphi(x)$. It implies that $\Phi(-x)=1-\Phi(x)$.
We say that a random variable $X$ has a degenerated distribution if X is equal to a constant $\mu$ with probability 1 . It is clear that in this case $\mathrm{E} X=\mu$, $\operatorname{var} X=0$. Thus this degenerated distribution is considered as $\mathbf{N}(\mu, 0)$.

Not every sequence of numbers is a sequence of moments. For example, there exists no distribution with the moments $\mu_{1}^{\prime}=2, \quad \mu_{2}^{\prime}=1$. For such a distribution it would hold

$$
\sigma^{2}=\mu_{2}^{\prime}-\left(\mu_{1}^{\prime}\right)^{2}=1-2^{2}=-3<0 .
$$

This is not possible, because the variance is nonnegative (see its definition). Let us investigate the problem when a finite series of numbers $\mu_{0}^{\prime}=1, \mu_{1}^{\prime}, \ldots, \mu_{2 n}^{\prime}$ is a series of moments. Consider an arbitrary vector $\boldsymbol{c}=\left(c_{0}, \ldots, c_{n}\right)^{\prime}$ with real components. It is easy to verify that

$$
0 \leq \mathrm{E}\left(\sum_{j=0}^{n} c_{j} X^{j}\right)^{2}=\mathrm{E} \sum_{j=0}^{n} \sum_{k=0}^{n} c_{j} c_{k} X^{j+k}=\sum_{j=0}^{n} \sum_{k=0}^{n} c_{j} c_{k} \mu_{j+k}^{\prime}=\boldsymbol{c}^{\prime} \boldsymbol{A} \boldsymbol{c}
$$

where

$$
\boldsymbol{A}=\left(\begin{array}{cccc}
\mu_{0}^{\prime} & \mu_{1}^{\prime} & \cdots & \mu_{n}^{\prime} \\
\mu_{1}^{\prime} & \mu_{2}^{\prime} & \cdots & \mu_{n+1} \\
\cdots & \cdots & \cdots & \cdots \\
\mu_{n}^{\prime} & \mu_{n+1}^{\prime} & \cdots & \mu_{2 n}^{\prime}
\end{array}\right)
$$

It means that the matrix $\boldsymbol{A}$ must be positively semidefinite. It can be proved that it is also a sufficient condition (see Krejn, Nudelman 1973). In the mentioned book it is
proved that an infinite series of numbers $\mu_{0}^{\prime}=1, \mu_{1}^{\prime}, \mu_{2}^{\prime}, \ldots$ is a series of of moments if and only if the infinite quadratic form

$$
\sum_{j=0}^{\infty} \sum_{k=0}^{\infty} c_{j} c_{k} \mu_{j+k}^{\prime}
$$

is positive definite.
The following formulas can be used for calculating moments (see Shao 2005).
Theorem 1.5 Let $F$ be a distribution function and a a real number. Then $\int[F(x+a)-$ $F(x)] \mathrm{d} x=a$.
Dkaz. Assume first that $a>0$. Then using Fubini theorem we get
$\int[F(x+a)-F(x)] \mathrm{d} x=\int\left[\int_{x}^{x+a} \mathrm{~d} F(y)\right] \mathrm{d} x=\int\left(\int_{y-a}^{y} \mathrm{~d} x\right) \mathrm{d} F(y)=\int a \mathrm{~d} F(y)=a$.
The proof is analogous for $a<0$.
Theorem 1.6 Let $X$ be a nonnegative random variable with the distribution function $F$ and with a finite expectation. Then

$$
\mathrm{E} X=\int_{0}^{\infty}[1-F(x)] \mathrm{d} x
$$

Proof. We have

$$
\begin{aligned}
\int_{0}^{\infty}[1-F(x)] \mathrm{d} x & =\int_{0}^{\infty}\left[\int_{x}^{\infty} \mathrm{d} F(y)\right] \mathrm{d} x=\int_{0}^{\infty}\left[\int_{0}^{y} \mathrm{~d} x\right] \mathrm{d} F(y)=\int_{0}^{\infty} y \mathrm{~d} F(y) \\
& =\mathrm{E} X .
\end{aligned}
$$

Theorem 1.7 Let $X$ be a random variable with distribution function $F$ and with a finite expectation. Then

$$
\mathrm{E} X=\int_{0}^{\infty}[1-F(x)] \mathrm{d} x-\int_{-\infty}^{0} F(x) \mathrm{d} x .
$$

Proof. It was proved that

$$
\int_{0}^{\infty}[1-F(x)] \mathrm{d} x=\int_{0}^{\infty} y \mathrm{~d} F(y) .
$$

Further we have

$$
\begin{aligned}
\int_{-\infty}^{0} F(x) \mathrm{d} x & =\int_{-\infty}^{0}\left[\int_{-\infty}^{x} \mathrm{~d} F(y)\right] \mathrm{d} x=\int_{-\infty}^{0}\left[\int_{y}^{0} \mathrm{~d} x\right] \mathrm{d} F(y) \\
& =\int_{-\infty}^{0}(-y) \mathrm{d} F(y)=-\int_{-\infty}^{0} y \mathrm{~d} F(y)
\end{aligned}
$$

Thus

$$
\begin{aligned}
\mathrm{E} X & =\int_{-\infty}^{\infty} y \mathrm{~d} F(y)=\int_{-\infty}^{0} y \mathrm{~d} F(y)+\int_{0}^{\infty} y \mathrm{~d} F(y) \\
& =-\int_{-\infty}^{0} F(x) \mathrm{d} x+\int_{0}^{\infty}[1-F(x)] \mathrm{d} x
\end{aligned}
$$

Theorem 1.8 Let $X$ be a nonnegative random variable with the distribution function $F$. Let $\mathrm{E} X^{2}<\infty$. Then

$$
\mathrm{E} X^{2}=2 \int_{0}^{\infty} x[1-F(x)] \mathrm{d} x
$$

Proof. We have

$$
\begin{aligned}
2 \int_{0}^{\infty} x[1-F(x)] \mathrm{d} x & =2 \int_{0}^{\infty} x\left[\int_{x}^{\infty} \mathrm{d} F(y)\right] \mathrm{d} x=2 \int_{0}^{\infty}\left[\int_{0}^{y} x \mathrm{~d} x\right] \mathrm{d} F(y) \\
& =\int_{0}^{\infty} y^{2} \mathrm{~d} F(y)=\mathrm{E} X^{2} .
\end{aligned}
$$

### 1.3 Quantile function

If a distribution function is given it is often necessary to find its inverse function $F^{-1}(u)$. It is simple when $F(x)$ is increasing and continuous. In the general case so called quantile function $F^{-1}$ is defined by the formula

$$
F^{-1}(u)=\inf \{x: F(x) \geq u\}, \quad 0<u<1 .
$$

Values of the function $F^{-1}(u)$ are called quantiles. E.g. $\alpha$-quantile is the value $F^{-1}(\alpha)$.
An important application of the quantile function is its role in construction of different distributions. It will be demonstrated in theorem 1.11.

The density of the rectangular distribution $\mathrm{R}(0,1)$ was introduced in section 1.2. Its distribution function is

$$
R(u)= \begin{cases}0 & \text { for } u \leq 0  \tag{1.7}\\ u & \text { for } 0<u \leq 1 \\ 1 & \text { for } 1<u\end{cases}
$$

The following theorem will be used in some proofs of forthcoming theorems.
Theorem 1.9 Let a random variable $X$ have the distribution function $F$. Then the relation $\mathrm{P}\{F(X) \leq F(x)\}=F(x)$ holds for every real $x$.

Proof. We have

$$
\{F(X) \leq F(x)\}=[\{F(X) \leq F(x)\} \cap\{X \leq x\}] \cup[\{F(X) \leq F(x)\} \cap\{X>x\}]
$$

Since

$$
\{X \leq x\} \subset\{F(X) \leq F(x)\}, \quad\{X>x\} \cap\{F(X)<F(x)\}=\emptyset
$$

we get

$$
\begin{equation*}
\{F(X) \leq F(x)\}=\{X \leq x\} \cup[\{X>x\} \cap\{F(X)=F(x)\}] . \tag{1.8}
\end{equation*}
$$

Notice that

$$
\mathrm{P}[\{X>x\} \cap\{F(X)=F(x)\}]=0
$$

since in this case $X$ must be in an interval where $F$ is constant. If we calculate probabilities of the left and right hand side of the formula (1.8), we get the assertion.

Theorem 1.10 Let $X$ have a continuous distribution function $F$. Then the random variable $U=F(X)$ has the distribution $\mathrm{R}(0,1)$.

Proof. We prove that $\mathrm{P}(U \leq u)=R(u)$, where the function $R(u)$ is defined in (1.7). If $u<0$ or $1 \leq u$, the assertion is obvious. Let $0<u<1$. Since $F$ is continuous, for a given $u$ there exists such an $x$ that $F(x)=u$. Using theorem 1.9 we obtain $\mathrm{P}(U \leq u)=\mathrm{P}\{F(X) \leq F(x)\}=u$.

If we assume in theorem 1.10 that $F$ is increasing then the proof without using theorem 1.9 would follow from

$$
\mathrm{P}(U \leq u)=\mathrm{P}[F(X) \leq u]=\mathrm{P}\left[X \leq F^{-1}(u)\right]=F\left[F^{-1}(u)\right]=u
$$

Theorem 1.10 says that the rectangular distribution can be obtained using transformation $U=F(X)$ from any other distribution with continuous distribution function.

Theorem 1.11 Let $U \sim \mathrm{R}(0,1)$ and let $F$ be a distribution function. Then the random variable $X=F^{-1}(U)$ has the distribution function $F$.

Proof. Let $u \in(0,1)$ and let $x$ be a number such that $0<F(x)<1$. First we show thet the inequality $F(x) \geq u$ is fulfilled if and only if $x \geq F^{-1}(u)$. Assume that

$$
x \geq F^{-1}(u)=\inf \{y: F(y) \geq u\} .
$$

Since $F$ is nondecreasing and continuous from the right the set $\{y: F(y) \geq u\}$ is an interval containing its left point. Thus we must have $F(x) \geq u$. Now assume that $F(x) \geq u$. But then $x \geq \inf \{y: F(y) \geq u\}=F^{-1}(u)$. Together we have $\mathrm{P}\left\{F^{-1}(U) \leq\right.$ $x\}=\mathrm{P}\{U \leq F(x)\}=F(x)$, which we wanted to prove.

If in theorem 1.11 we add the assumption that $F$ is continuous and increasing, the assertion would simply follow from the fact that

$$
\mathrm{P}(X \leq x)=\mathrm{P}\left[F^{-1}(U) \leq x\right]=\mathrm{P}[U \leq F(x)]=F(x)
$$

The variables with the distribution $R(0,1)$ can be easily generated by computers. Thus theorem 1.11 describes a procedure how to obtain variables with an arbitrary given distribution function $F$. In most cases the calculation if the quantile function is complicated and so to generate large number of such variables can be time consuming. Often instead of direct application of theorem 1.11 special procedures are used.

Let us remark that theorem 1.9 and proofs of the theorems 1.10 and 1.11 follow the paper Angus (1994).

At the end of this chapter we introduce a definition of median which belongs to the distribution with the distribution function $F$. Median $\tilde{\mu}$ is a number which satisfies

$$
F\left(\tilde{\mu}^{-}\right) \leq \frac{1}{2}, \quad F(\tilde{\mu}) \geq \frac{1}{2} .
$$

The symbol $F\left(\tilde{\mu}^{-}\right)$denotes the limit from the left hand side. The median always exists but it is not defined uniquely. Similarly the number $\tilde{\mu}_{p}$ (called $p$-th percentile) for $0<p<1$ is defined by

$$
F\left(\tilde{\mu}_{p}^{-}\right) \leq p, \quad F\left(\tilde{\mu}_{p}\right) \geq p
$$

Theorem 1.12 Let a distribution with the distribution function $F$ have expectation $\mu$ and a finite standard deviation $\sigma$. Then we have for (an arbitrary) median $\tilde{\mu}$

$$
|\mu-\tilde{\mu}| \leq \sigma
$$

and for (an arbitrary) percentile $\tilde{\mu}_{p}$ we have

$$
\left|\mu-\tilde{\mu}_{p}\right| \leq \sigma \max \left(\sqrt{\frac{1-p}{p}}, \sqrt{\frac{p}{1-p}}\right) .
$$

Proof. See O'Cinneide (1990).

## Chapter 2

## Random vectors

### 2.1 Introduction

Let random variables $X_{1}, \ldots, X_{n}$ be defined on the same probability space $(\Omega, \mathcal{A}, \mathrm{P})$. Then $\boldsymbol{X}=\left(X_{1}, \ldots, X_{n}\right)^{\prime}$ is called random vector. If the random variables $X_{i j}(i=1, \ldots, n ; j=$ $1, \ldots, m)$ are defined on the same probability space, then $\boldsymbol{X}=\left(X_{i j}\right)$ is random matrix. The expectation of the random vector is the vector $\mathbf{E} \boldsymbol{X}=\left(\mathbf{E} X_{1}, \ldots, \mathrm{E} X_{n}\right)^{\prime}$; similarly we define expectation of the random matrix by $\mathbf{E} \boldsymbol{X}=\left(\mathbf{E} X_{i j}\right)$. The function

$$
F\left(x_{1}, \ldots, x_{n}\right)=\mathrm{P}\left(X_{1} \leq x_{1}, \ldots, X_{n} \leq x_{n}\right)
$$

is called distribution function of the random vector $\boldsymbol{X}$. Sometimes it is called simultaneous distribution function of the random variables $X_{1}, \ldots, X_{n}$. If there exists a function $f$ such that

$$
\begin{equation*}
F\left(x_{1}, \ldots, x_{n}\right)=\int_{-\infty}^{x_{1}} \cdots \int_{-\infty}^{x_{n}} f\left(u_{1}, \ldots, u_{n}\right) \mathrm{d} u_{1} \ldots \mathrm{~d} u_{n} \tag{2.1}
\end{equation*}
$$

then we say that the vector $\boldsymbol{X}$ has continuous distribution and that $f$ is its simultaneous density. In view of (2.1) we have

$$
\begin{equation*}
f\left(x_{1}, \ldots, x_{n}\right)=\frac{\partial^{n} F\left(x_{1}, \ldots, x_{n}\right)}{\partial x_{1} \ldots \partial x_{n}} \quad \text { almost everywhere. } \tag{2.2}
\end{equation*}
$$

If $g\left(x_{1}, \ldots, x_{n}\right)$ is borel measurable function, then it can be proved that

$$
\begin{equation*}
\mathrm{E} g\left(X_{1}, \ldots, X_{n}\right)=\int \ldots \int g\left(x_{1}, \ldots, x_{n}\right) \mathrm{d} F\left(x_{1}, \ldots, x_{n}\right) \tag{2.3}
\end{equation*}
$$

If only some of the variables $X_{1}, \ldots, X_{n}$ are investigated then their distribution function is called marginal and eventual corresponding density is also marginal.

If there exists the simultaneous density then all the marginal densities also exist; the reversed assertion does not hold.

To illustrate the situation, we shall deal for a while only with two random variables $X_{1}$ and $X_{2}$. Their simultaneous density is $F\left(x_{1}, x_{2}\right)=\mathrm{P}\left(X_{1} \leq x_{1}, X_{2} \leq x_{2}\right)$. It is obvious that the marginal distribution function $F_{1}\left(x_{1}\right)=\mathrm{P}\left(X_{1} \leq x_{1}\right)$ of the random variable $X_{1}$ satisfies

$$
F_{1}\left(x_{1}\right)=F\left(x_{1}, \infty\right)
$$

where

$$
F\left(x_{1}, \infty\right)=\lim _{x_{2} \rightarrow \infty} F\left(x_{1}, x_{2}\right)
$$

If $X_{1}, X_{2}$ have the simultaneous density $f\left(x_{1}, x_{2}\right)$, then using (2.1) we have

$$
F\left(x_{1}, \infty\right)=\int_{-\infty}^{x_{1}} \int_{-\infty}^{\infty} f\left(u_{1}, u_{2}\right) \mathrm{d} u_{1} \mathrm{~d} u_{2}
$$

In view of (2.2) we have that the density $f_{1}\left(x_{1}\right)$ of the variable $X_{1}$ is

$$
f_{1}\left(x_{1}\right)=\frac{\mathrm{d} F_{1}\left(x_{1}\right)}{\mathrm{d} x_{1}}=\frac{\mathrm{d} F\left(x_{1}, \infty\right)}{\mathrm{d} x_{1}}=\int_{-\infty}^{\infty} f\left(x_{1}, u_{2}\right) \mathrm{d} u_{2}
$$

Analogous formulas can be easily derived also for larger number of random variables. The result is formulated in the sentence that the marginal density can be obtained from the simultaneous density integrating superfluous variables.

### 2.2 Variance matrix

Let the variables $X_{1}, \ldots, X_{n}$ have finite second moments. Covariance $\operatorname{cov}\left(X_{i}, X_{j}\right)$ of random variables $X_{i}, X_{j}$ is

$$
\operatorname{cov}\left(X_{i}, X_{j}\right)=\mathrm{E}\left(X_{i}-\mathrm{E} X_{i}\right)\left(X_{j}-\mathrm{E} X_{j}\right)
$$

Equivalently, we obtain

$$
\operatorname{cov}\left(X_{i}, X_{j}\right)=\mathrm{E} X_{i} X_{j}-\mathrm{E} X_{i} \mathrm{E} X_{j}
$$

This last expression is suitable for practical calculations. We can see that $\operatorname{cov}\left(X_{i}, X_{i}\right)=$ $\operatorname{var} X_{i}$. Denote

$$
F_{i j}\left(x_{i}, x_{j}\right)=\mathrm{P}\left(X_{i} \leq x_{i}, X_{j} \leq x_{j}\right)
$$

the distribution function of the vector $\left(X_{i}, X_{j}\right)$. Let $F_{i}(x)=\mathrm{P}\left(X_{i} \leq x\right)$ for $i=1, \ldots, n$ be the marginal distribution functions of the individual components of the vector $\boldsymbol{X}$. It follows from (2.3) that

$$
\begin{aligned}
\operatorname{cov}\left(X_{i}, X_{j}\right) & =\iint\left[x_{i}-\int x \mathrm{~d} F_{i}(x)\right]\left[x_{j}-\int x \mathrm{~d} F_{j}(x)\right] \mathrm{d} F_{i j}\left(x_{i}, x_{j}\right) \\
& =\iint x_{i} x_{j} \mathrm{~d} F_{i j}\left(x_{i}, x_{j}\right)-\left[\int x \mathrm{~d} F_{i}(x)\right]\left[\int x d F_{j}(x)\right]
\end{aligned}
$$

If a two-dimensional vector $\left(X_{i}, X_{j}\right)$ has a continuous distribution with the density $f_{i j}\left(x_{i}, x_{j}\right)$ then

$$
\iint x_{i} x_{j} \mathrm{~d} F_{i j}\left(x_{i}, x_{j}\right)=\iint x_{i} x_{j} f_{i j}\left(x_{i}, x_{j}\right) \mathrm{d} x_{i} \mathrm{~d} x_{j} .
$$

Instead of $\operatorname{cov}\left(X_{i}, X_{j}\right)$ it is written $\sigma_{X_{i} X_{j}}$ or shortly $\sigma_{i j}$. We know already that $\sigma_{i i}=\sigma_{i}^{2}$ is the variance of the variable $X_{i}$. If we write $\operatorname{cov}\left(X_{i}, X_{j}\right)$ as the elements of the matrix, we get the variance matrix $\boldsymbol{V}=\left(\sigma_{i j}\right)$. The matrix $\boldsymbol{V}$ is often written as var $\boldsymbol{X}$.

Theorem 2.1 The variance matrix can be written in the form

$$
\begin{equation*}
\boldsymbol{V}=\mathrm{E}(\boldsymbol{X}-\mathrm{E} \boldsymbol{X})(\boldsymbol{X}-\mathrm{E} \boldsymbol{X})^{\prime} \tag{2.4}
\end{equation*}
$$

and in the form

$$
\boldsymbol{V}=\mathrm{E} \boldsymbol{X} \boldsymbol{X}^{\prime}-(\mathrm{E} \boldsymbol{X})(\mathrm{E} \boldsymbol{X})^{\prime}
$$

Proof. The first formula can be proved componentwise. The second formula follows from the first one by an easy derivation.

Theorem 2.2 Let $\boldsymbol{a}$ be an $m \times 1$ vector and $\boldsymbol{B}$ an $m \times n$ matrix. Define $\boldsymbol{Y}=\boldsymbol{a}+\boldsymbol{B} \boldsymbol{X}$. If $\mathrm{E} \boldsymbol{X}$ exists then $\mathrm{E} \boldsymbol{Y}=\boldsymbol{a}+\boldsymbol{B} \mathrm{E} \boldsymbol{X}$. If $\boldsymbol{X}$ has components with finite second moments, then

$$
\begin{equation*}
\operatorname{var} \boldsymbol{Y}=\boldsymbol{B} \boldsymbol{V} \boldsymbol{B}^{\prime} \tag{2.5}
\end{equation*}
$$

Proof. The first assertion can be proved componentwise. The second one follows from (2.4).

It follows from definition as well as from theorem 2.2 that the variance matrix is symmetric.

Theorem 2.3 Variance matrix is positive semidefinite.

Proof. Choose an arbitrary vector $\boldsymbol{c}=\left(c_{1}, \ldots, c_{n}\right)^{\prime}$. Since the variance of any random variable is nonnegative also the variance of $\boldsymbol{c}^{\prime} \boldsymbol{X}$ is nonnegative. Using formula (2.5) we obtain

$$
0 \leq \operatorname{var} \boldsymbol{c}^{\prime} \boldsymbol{X}=\boldsymbol{c}^{\prime} \boldsymbol{V} \boldsymbol{c}
$$

Let $\boldsymbol{Y}=\left(Y_{1}, \ldots, Y_{m}\right)^{\prime}$ and $\boldsymbol{Z}=\left(Z_{1}, \ldots, Z_{n}\right)^{\prime}$ be random vectors with finite second moments. Then the covariance matrix of the vectors $\boldsymbol{Y}$ and $\boldsymbol{Z}$ is the matrix

$$
\operatorname{cov}(\boldsymbol{Y}, \boldsymbol{Z})=\left(\operatorname{cov}\left(Y_{i}, Z_{j}\right)\right)
$$

It is easy to check that

$$
\operatorname{cov}(\boldsymbol{Y}, \boldsymbol{Z})=\mathrm{E}(\boldsymbol{Y}-\mathrm{E} \boldsymbol{Y})(\boldsymbol{Z}-\mathrm{E} \boldsymbol{Z})^{\prime}
$$

and that

$$
\operatorname{cov}(\boldsymbol{Y}, \boldsymbol{Z})=\mathrm{E} \boldsymbol{Y} \boldsymbol{Z}^{\prime}-(\mathrm{E} \boldsymbol{Y})(\mathrm{E} \boldsymbol{Z})^{\prime}
$$

From the definition it follows that

$$
\operatorname{cov}(\boldsymbol{Z}, \boldsymbol{Y})=[\operatorname{cov}(\boldsymbol{Y}, \boldsymbol{Z})]^{\prime}
$$

Notice that the variance matrix is a special case of the covariance matrix, since

$$
\operatorname{cov}(\boldsymbol{X}, \boldsymbol{X})=\operatorname{var} \boldsymbol{X}
$$

The covariance matrices are used in the following theorem.

Theorem 2.4 Let random vectors $\boldsymbol{X}=\left(X_{1}, \ldots, X_{n}\right)^{\prime}$ and $\boldsymbol{Y}=\left(Y_{1}, \ldots, Y_{n}\right)^{\prime}$ have finite second moments. Then

$$
\operatorname{var}(\boldsymbol{X}+\boldsymbol{Y})=\operatorname{var} \boldsymbol{X}+\operatorname{cov}(\boldsymbol{X}, \boldsymbol{Y})+\operatorname{cov}(\boldsymbol{Y}, \boldsymbol{X})+\operatorname{var} \boldsymbol{Y}
$$

Proof. The assertion follows from formula (2.4).
Theorem 2.5 Let $\boldsymbol{Y}=\left(Y_{1}, \ldots, Y_{m}\right)^{\prime}$ and $\boldsymbol{Z}=\left(Z_{1}, \ldots, Z_{n}\right)^{\prime}$ be random vectors with finite second moments. If $\boldsymbol{a}$ is an $r \times 1$ vector, $\boldsymbol{c}$ an $s \times 1$ vector, $\boldsymbol{B}$ an $r \times m$ matrix and $\boldsymbol{D}$ an $s \times n$ matrix, then

$$
\operatorname{cov}(\boldsymbol{a}+\boldsymbol{B} \boldsymbol{Y}, \boldsymbol{c}+\boldsymbol{D} \boldsymbol{Z})=\boldsymbol{B} \operatorname{cov}(\boldsymbol{Y}, \boldsymbol{Z}) \boldsymbol{D}^{\prime}
$$

Proof. The result follows from the formula for covariance.

### 2.3 Independence

Let us return to the model for random events which was introduced in section 2.1. We say that two events $A_{1} \in \mathcal{A}, A_{2} \in \mathcal{A}$ are independent, if

$$
\mathrm{P}\left(A_{1} \cap A_{2}\right)=\mathrm{P}\left(A_{1}\right) P\left(A_{2}\right) .
$$

This is a mathematical definition of the notion independence which is used in everyday language. If $\mathrm{P}\left(A_{2}\right)>0$ then we define the conditional probability of the event $A_{1}$ given $A_{2}$ as

$$
\begin{equation*}
\mathrm{P}\left(A_{1} \mid A_{2}\right)=\frac{\mathrm{P}\left(A_{1} \cap A_{2}\right)}{\mathrm{P}\left(A_{2}\right)} . \tag{2.6}
\end{equation*}
$$

Consider a random vector $\boldsymbol{X}=\left(X_{1}, \ldots, X_{n}\right)^{\prime}$. Let $F\left(x_{1}, \ldots, x_{n}\right)$ be its simultaneous distribution function

Let $\boldsymbol{X}=\left(X_{1}, \ldots, X_{n}\right)^{\prime}$ be a random vector, $F\left(x_{1}, \ldots, x_{n}\right)$ its simultaneous distribution function and $F_{i}\left(x_{i}\right)$ marginal distribution of $X_{i}, i=1, \ldots, n$. We say that $X_{1}, \ldots, X_{n}$ are independent random variables, if we have for all real $x_{1}, \ldots, x_{n}$

$$
\begin{equation*}
F\left(x_{1}, x_{2}, \ldots, x_{n}\right)=F_{1}\left(x_{1}\right) F_{2}\left(x_{2}\right) \ldots F_{n}\left(x_{n}\right) . \tag{2.7}
\end{equation*}
$$

Theorem 2.6 Let a random vector $\boldsymbol{X}$ have simultaneous density $f\left(x_{1}, \ldots, x_{n}\right)$. Denote $f_{i}\left(x_{i}\right)$ the marginal density of the variable $X_{i}, i=1, \ldots, n$. Then variables $X_{1}, \ldots, X_{n}$ are independent if and only if

$$
f\left(x_{1}, \ldots, x_{n}\right)=f_{1}\left(x_{1}\right) \ldots f_{n}\left(x_{n}\right) \quad \text { almost everywhere. }
$$

Proof. The assertion follows from definition (2.7) and from the formula (2.2).
The independence of random vectors is defined similarly as the independence of random variables. We say that $\boldsymbol{Y}$ and $\boldsymbol{Z}$ are independent random vectors, if their simultaneous distribution function is equal to the product of the distribution function of vector $\boldsymbol{Y}$ and the distribution function of vector $\boldsymbol{Z}$. If the simultaneous distribution of the vector $\left(\boldsymbol{Y}^{\prime}, \boldsymbol{Z}^{\prime}\right)^{\prime}$ is continuous then the vectors $\boldsymbol{Y}$ and $\boldsymbol{Z}$ are independent if and only if their simultaneous density is equal to the product of marginal densities of the vectors $\boldsymbol{Y}$ a $\boldsymbol{Z}$.

Theorem 2.7 Let $X_{1}, \ldots, X_{n}$ be independent random variables with finite first moments. Then

$$
\mathrm{E}\left(X_{1} \ldots X_{n}\right)=\left(\mathrm{E} X_{1}\right) \ldots\left(\mathrm{E} X_{n}\right)
$$

Proof. Let $F$ be the simultaneous distribution function of the vector $\boldsymbol{X}=\left(X_{1}, \ldots, X_{n}\right)^{\prime}$ and $F_{i}$ the distribution function of the random variable $X_{i}, i=1, \ldots, n$. It follows from (2.3), (2.7) and from Fubini theorem that

$$
\begin{aligned}
\mathrm{E}\left(X_{1} \ldots X_{n}\right) & =\int \cdots \int x_{1} \ldots x_{n} \mathrm{~d} F\left(x_{1}, \ldots, x_{n}\right) \\
& =\int \cdots \int x_{1} \ldots x_{n} \mathrm{~d} F_{1}\left(x_{1}\right) \ldots \mathrm{d} F_{n}\left(x_{n}\right) \\
& =\left[\int x_{1} \mathrm{~d} F_{1}\left(x_{1}\right)\right] \ldots\left[\int x_{n} \mathrm{~d} F_{n}\left(x_{n}\right)\right]=\left(\mathrm{E} X_{1}\right) \ldots\left(\mathrm{E} X_{n}\right) .
\end{aligned}
$$

A statistician must frequently decide if two random variables are independent or not. Their simultaneous distribution function is usually not known. Some procedures are based on the following assertion.

Theorem 2.8 Let $X$ and $Y$ be independent random variables with finite second moments. Then we have $\operatorname{cov}(X, Y)=0$.

Proof. If $X$ and $Y$ are independent, then the variables $X-\mathrm{E} X$ and $Y-\mathrm{E} Y$ are also independent. From the definition of covariance and from theorem 2.7 we obtain

$$
\operatorname{cov}(X, Y)=\mathrm{E}(X-\mathrm{E} X)(Y-\mathrm{E} Y)=\mathrm{E}(X-\mathrm{E} X) \mathrm{E}(Y-\mathrm{E} Y)=0
$$

The covariance itself as a measure of independence is not used but after some normalization we get correlation coefficient. We shall consider it in section 2.6.

If $\operatorname{cov}(X, Y)=0$, then we say that $X$ and $Y$ are uncorrelated variables. Unfortunately, examples show that uncorrelated variables may not be necessarily independent.

### 2.4 Conditional density

The main idea will be demonstrated on a random vector $\boldsymbol{X}=(Y, Z)^{\prime}$ with two components. Let $\boldsymbol{X}$ have the density $p(y, z)$. Denote $q(z)=\int p(y, z) \mathrm{d} y$ the marginal density of the variable $Z$. First we define the conditional distribution function of the variable $Y$ given $Z=z$, which we denote $F(y \mid z)=\mathrm{P}(Y \leq y \mid Z=z)$. We cannot use formula (2.6), because $\mathrm{P}(Z=z)=0$ since $Z$ has a continuous distribution. Choose points $z_{1}, z_{2}$ in such a way that $z_{1}<z<z_{2}$ and assume that $\mathrm{P}\left(z_{1}<Z<z_{2}\right)>0$ for such points $z_{1}, z_{2}$. Using(2.6) we get

$$
\begin{aligned}
\mathrm{P}\left(Y \leq y \mid z_{1}<Z<z_{2}\right) & =\frac{\mathrm{P}\left(Y \leq y, z_{1}<Z<z_{2}\right)}{\mathrm{P}\left(z_{1}<Z<z_{2}\right)} \\
& =\frac{\int_{-\infty}^{y} \int_{z_{1}}^{z_{2}} p(u, v) \mathrm{d} v \mathrm{~d} u}{\int_{z_{1}}^{z_{2}} q(v) \mathrm{d} v}
\end{aligned}
$$

If $p$ is a smooth function then according to the mean value theorem for every $u$ there exists a point $z_{u} \in\left(z_{1}, z_{2}\right)$ such that

$$
\int_{z_{1}}^{z_{2}} p(u, v) \mathrm{d} v=\left(z_{2}-z_{1}\right) p\left(u, z_{u}\right) .
$$

If $q$ is a smooth function, then analogously there exists a point $z^{*} \in\left(z_{1}, z_{2}\right)$ such that

$$
\int_{z_{1}}^{z_{2}} q(v) \mathrm{d} v=\left(z_{2}-z_{1}\right) q\left(z^{*}\right)
$$

Thus

$$
\mathrm{P}\left(Y \leq y \mid z_{1}<Z<z_{2}\right)=\frac{\int_{-\infty}^{y} p\left(u, z_{u}\right) \mathrm{d} u}{q\left(z^{*}\right)} .
$$

If $z_{1} \rightarrow z^{-}, z_{2} \rightarrow z^{+}$, then also $z_{u} \rightarrow z, z^{*} \rightarrow z$ and because of assumed smoothness of functions $p$ and $q$ we will have $p\left(u, z_{u}\right) \rightarrow p(u, z), q\left(z^{*}\right) \rightarrow q(z)$. If we may change limit and integral, we obtain

$$
\lim _{\substack{z_{1} \rightarrow z^{-} \\ z_{2} \rightarrow z^{+}}} \mathrm{P}\left(Y \leq y \mid z_{1}<Z<z_{2}\right)=\int_{-\infty}^{y} \frac{p(u, z) \mathrm{d} u}{q(z)}
$$

It is natural to define the conditional distribution function $F(y \mid z)$ as the limit of the probability $\mathrm{P}\left(Y \leq y \mid z_{1}<Z<z_{2}\right)$ when $z_{1} \rightarrow z^{-}, z_{2} \rightarrow z^{+}$. Thus we obtained

$$
F(y \mid z)=\int_{-\infty}^{y} \frac{p(u, z)}{q(z)} \mathrm{d} u
$$

Now we can introduce the conditional density as the derivative of the conditional distribution function analogously as in formula (1.4), which describes connection between the common distribution function and the common density. The result is that the conditional density $r$ of the variable $Y$ given $Z=z$ is

$$
\begin{equation*}
r(y \mid z)=\frac{p(y, z)}{q(z)} \tag{2.8}
\end{equation*}
$$

In our derivation it was necessary to use many mathematical assumptions. However, it can be proved (see Anděl 2007), that conditional density is always given by formula (2.8), if $q(z) \neq 0$. In the case $q(z)=0$ we define $r(y \mid z)=0$.

### 2.5 Approximation of random variables

Consider a random variable $Y$ and a random vector $\boldsymbol{X}=\left(X_{1}, \ldots, X_{n}\right)^{\prime}$. Assume that $Y$ and $\boldsymbol{X}$ have finite second moments. It happens that it is necessary to predict the variable $Y$ using the known vector $\boldsymbol{X}$. We can have several reasons for it. Sometimes the measurement of $Y$ is very difficult, hardly accessible or expensive. In other cases we obtain information about $Y$ after many years whereas the vector $\boldsymbol{X}$ is known immediately.

We restrict ourselves to find an approximation of the variable $Y$ using a linear function $\hat{Y}=\alpha+\beta_{1} X_{1}+\cdots+\beta_{n} X_{n}$. Our problem is to find the coefficients $\alpha, \beta_{1}, \ldots, \beta_{n}$ so that the difference between $Y$ and $\hat{Y}$ is as small as possible. The criterion is $\mathrm{E}(Y-\hat{Y})^{2}$.

Theorem 2.9 Let $\boldsymbol{V}=$ var $\boldsymbol{X}$ be a regular matrix. Then

$$
\mathrm{E}(Y-\hat{Y})^{2} \geq \operatorname{var} Y-\operatorname{cov}(Y, \boldsymbol{X}) \boldsymbol{V}^{-1} \operatorname{cov}(\boldsymbol{X}, Y)
$$

and left hand side is equal to right hand side if and only if

$$
\begin{equation*}
\boldsymbol{\beta}=\boldsymbol{V}^{-1} \operatorname{cov}(\boldsymbol{X}, Y), \quad \alpha=\mathrm{E} Y-\boldsymbol{\beta}^{\prime} \mathrm{E} \boldsymbol{X} \tag{2.9}
\end{equation*}
$$

Proof. If a random variable $Z$ has a finite second moment, it fulfills $\mathrm{E} Z^{2}=\operatorname{var} Z+(\mathrm{E} Z)^{2}$. Thus $\mathrm{E} Z^{2} \geq \operatorname{var} Z$ and we have equality if and only if $\mathrm{E} Z=0$. Define $Z=Y-\hat{Y}=$ $Y-\alpha-\boldsymbol{\beta}^{\prime} \boldsymbol{X}$. Then

$$
\mathrm{E}(Y-\hat{Y})^{2} \geq \operatorname{var}\left(Y-\alpha-\boldsymbol{\beta}^{\prime} \boldsymbol{X}\right)
$$

The equality holds if and only if $\mathrm{E}\left(Y-\alpha-\boldsymbol{\beta}^{\prime} \boldsymbol{X}\right)=0$, i. e. in the case

$$
\alpha=\mathrm{E} Y-\boldsymbol{\beta}^{\prime} \mathrm{E} \boldsymbol{X}
$$

We know that the variance does not depend on the shift, and so

$$
\operatorname{var}\left(Y-\alpha-\boldsymbol{\beta}^{\prime} \boldsymbol{X}\right)=\operatorname{var}\left(Y-\boldsymbol{\beta}^{\prime} \boldsymbol{X}\right)
$$

Using theorems 2.4 and 2.5 we get

$$
\begin{aligned}
\operatorname{var}\left(Y-\boldsymbol{\beta}^{\prime} \boldsymbol{X}\right)= & \operatorname{var} Y-\boldsymbol{\beta}^{\prime} \operatorname{cov}(\boldsymbol{X}, Y)-\operatorname{cov}(Y, \boldsymbol{X}) \boldsymbol{\beta}+\boldsymbol{\beta}^{\prime} \boldsymbol{V} \boldsymbol{\beta} \\
= & {\left[\boldsymbol{\beta}-\boldsymbol{V}^{-1} \operatorname{cov}(\boldsymbol{X}, Y)\right]^{\prime} \boldsymbol{V}\left[\boldsymbol{\beta}-\boldsymbol{V}^{-1} \operatorname{cov}(\boldsymbol{X}, Y)\right] } \\
& +\operatorname{var} Y-\operatorname{cov}(Y, \boldsymbol{X}) \boldsymbol{V}^{-1} \operatorname{cov}(\boldsymbol{X}, Y) .
\end{aligned}
$$

Since $\boldsymbol{V}$ is a variance matrix, it is positively semidefinite according to theorem 2.3. Moreover, now we assume that $\boldsymbol{V}$ is regular. Thus $\boldsymbol{V}$ is positively definite and

$$
\left[\boldsymbol{\beta}-\boldsymbol{V}^{-1} \operatorname{cov}(\boldsymbol{X}, Y)\right]^{\prime} \boldsymbol{V}\left[\boldsymbol{\beta}-\boldsymbol{V}^{-1} \operatorname{cov}(\boldsymbol{X}, Y)\right] \geq 0
$$

The equality holds if and only if

$$
\boldsymbol{\beta}-\boldsymbol{V}^{-1} \operatorname{cov}(\boldsymbol{X}, Y)=0
$$

The assertion is proved.
The expression

$$
\sigma_{Y \cdot \boldsymbol{X}}^{2}=\operatorname{var} Y-\operatorname{cov}(Y, \boldsymbol{X}) \boldsymbol{V}^{-1} \operatorname{cov}(\boldsymbol{X}, Y)
$$

is called residual variance. In view of (2.9) it also holds

$$
\begin{equation*}
\sigma_{Y \cdot \boldsymbol{X}}^{2}=\operatorname{var} Y-\boldsymbol{\beta}^{\prime} \boldsymbol{V} \boldsymbol{\beta} \tag{2.10}
\end{equation*}
$$

If we apply the formula for determinant of the matrix divided into the blocks we obtain another formula

$$
\sigma_{Y . \boldsymbol{X}}^{2}=\frac{\left|\operatorname{var}\left(Y, X_{1}, \ldots, X_{n}\right)\right|}{|\boldsymbol{V}|}
$$

### 2.6 Correlation coefficient

Let $X$ and $Y$ be random variables with finite second moments. We denote $\sigma_{X}^{2}=\operatorname{var} X$, $\sigma_{Y}^{2}=\operatorname{var} Y, \sigma_{X Y}=\operatorname{cov}(X, Y)$. If $\sigma_{X}^{2}>0$ and $\sigma_{Y}^{2}>0$, then we define correlation coefficient

$$
\begin{equation*}
\rho=\frac{\sigma_{X Y}}{\sqrt{\sigma_{X}^{2} \sigma_{Y}^{2}}} \tag{2.11}
\end{equation*}
$$

Instead of $\rho$ one writes $\rho_{X Y}$ to indicate the variables for which the coefficient is calculated. It follows from theorem 2.8 that $\rho=0$ when the variables $X$ and $Y$ are independent. It can be easily verified that

$$
\begin{equation*}
\rho_{X X}=1 . \tag{2.12}
\end{equation*}
$$

Theorem 2.10 Let $a, b, c, d$ be such numbers that $b d \neq 0$. If $b d>0$, then $\rho_{a+b X, c+d Y}=$ $\rho_{X Y} ;$ if $b d<0$, then $\rho_{a+b X, c+d Y}=-\rho_{X Y}$.

Proof. The assertion follows from theorem (2.11).

Theorem 2.11 We have $-1 \leq \rho \leq 1$. If $b>0$ then the equality $\rho=1$ holds if and only if $Y=a+b X$ with probability 1. Similarly, if $b<0$ then $\rho=-1$ holds if and only if $Y=a+b X$ with probability 1 .

Proof. From Schwarz inequality we get

$$
|\mathrm{E}(X-\mathrm{E} X)(Y-\mathrm{E} Y)|^{2} \leq \mathrm{E}(X-\mathrm{E} X)^{2} \mathrm{E}(Y-\mathrm{E} Y)^{2}
$$

It implies that $-1 \leq \rho \leq 1$. The equality is reached either in the case that $X-\mathrm{E} X=0$ with probability 1 , or in the case that $Y-\mathrm{E} Y=b(X-\mathrm{E} X)$ with probability 1. The first case cannot be realized since the variable $X$ would have vanishing variance and the correlation coefficient would not be defined. From the same reason in the second case the value $b=0$ must be excluded. If $b>0$, then theorem 2.11 gives $\rho=1$; if $b<0$, then $\rho=-1$.

The correlation matrix is introduced similarly as the variance and covariance matrices. Consider a random vector $\boldsymbol{X}=\left(X_{1}, \ldots, X_{n}\right)^{\prime}$ with finite second moments and positive variances. Then the correlation matrix of the vector $\boldsymbol{X}$ is the matrix $\boldsymbol{P}=\left(\rho_{i j}\right)$ of type $n \times n$, where $\rho_{i j}=\rho_{X_{i}, X_{j}}$. It follows from (2.12) that the matrix $\boldsymbol{P}$ has ones on the diagonal and is symmetric.

Let $\boldsymbol{Y}=\left(Y_{1}, \ldots, Y_{m}\right)^{\prime}$ and $\boldsymbol{Z}=\left(Z_{1}, \ldots, Z_{n}\right)^{\prime}$ be random vectors with finite second moments and positive variances. Then the correlation matrix of these vectors is $\operatorname{cor}(\boldsymbol{Y}, \boldsymbol{Z})=\left(\rho_{Y_{i} Z_{j}}\right)$ and has the type $m \times n$.

### 2.7 Coefficient of multiple correlation

Classical correlation coefficient $\rho$ measures dependence between two random variables. Very often it is necessary to describe dependence between a random variable $Y$ and a random vector $\boldsymbol{X}=\left(X_{1}, \ldots, X_{n}\right)^{\prime}$. Let $\boldsymbol{V}=\operatorname{var} \boldsymbol{X}$ be a regular matrix. According theorem 2.9 the variable $\hat{Y}=\alpha+\boldsymbol{\beta}^{\prime} \boldsymbol{X}$ is the best linear approximation. Here $\alpha$ a $\boldsymbol{\beta}$ are
introduced in formula (2.9). The coefficient of multiple correlation $\rho_{Y, \boldsymbol{X}}$ is defined as the usual correlation coefficient between the variables $Y$ and $\hat{Y}$. The definition is

$$
\rho_{Y, \boldsymbol{X}}=\rho_{Y, \alpha+\boldsymbol{\beta}^{\prime} \boldsymbol{X}}
$$

In the case $\boldsymbol{\beta}=\mathbf{0}$ we define $\rho_{Y, \boldsymbol{X}}=0$.
Theorem 2.12 Coefficient of multiple correlation is given by the formula

$$
\begin{equation*}
\rho_{Y, \boldsymbol{X}}^{2}=\frac{\boldsymbol{\beta}^{\prime} \boldsymbol{V} \boldsymbol{\beta}}{\sigma_{Y}^{2}} \tag{2.13}
\end{equation*}
$$

Proof. If $\boldsymbol{\beta}=\mathbf{0}$, the assertion is valid. Let $\boldsymbol{\beta} \neq \mathbf{0}$. According to the definition we have

$$
\rho_{Y, \boldsymbol{X}}^{2}=\frac{\left[\operatorname{cov}\left(Y, \alpha+\boldsymbol{\beta}^{\prime} \boldsymbol{X}\right)\right]^{2}}{\sigma_{Y}^{2} \operatorname{var}\left(\alpha+\boldsymbol{\beta}^{\prime} \boldsymbol{X}\right)}
$$

It follows from (2.9) that $\operatorname{cov}(\boldsymbol{X}, Y)=\boldsymbol{V} \boldsymbol{\beta}$, and thus

$$
\begin{equation*}
\operatorname{cov}(Y, \boldsymbol{X})=\boldsymbol{\beta}^{\prime} \boldsymbol{V} \tag{2.14}
\end{equation*}
$$

This gives

$$
\begin{equation*}
\operatorname{cov}\left(Y, \alpha+\boldsymbol{\beta}^{\prime} \boldsymbol{X}\right)=\operatorname{cov}\left(Y, \boldsymbol{\beta}^{\prime} \boldsymbol{X}\right)=\operatorname{cov}(Y, \boldsymbol{X}) \boldsymbol{\beta}=\boldsymbol{\beta}^{\prime} \boldsymbol{V} \boldsymbol{\beta} \tag{2.15}
\end{equation*}
$$

and similarly

$$
\begin{equation*}
\operatorname{var}\left(\alpha+\boldsymbol{\beta}^{\prime} \boldsymbol{X}\right)=\boldsymbol{\beta}^{\prime} \boldsymbol{V} \boldsymbol{\beta} \tag{2.16}
\end{equation*}
$$

The assertion is proved.
Theorem 2.13 Coefficient of multiple correlation satisfies $0 \leq \rho_{Y, \boldsymbol{X}} \leq 1$.
Proof. In the case $\boldsymbol{\beta}=\mathbf{0}$ the assertion is valid. Otherwise $\rho_{Y, \boldsymbol{X}}$ is equal to the correlation coefficient between $Y$ a $\hat{Y}$, which is smaller or equal 1 according to theorem 2.11. For $\boldsymbol{\beta} \neq \mathbf{0}$ from (2.15) and (2.16) we get

$$
\rho_{Y, \alpha+\boldsymbol{\beta}^{\prime} \boldsymbol{X}}=\frac{\operatorname{cov}\left(Y, \alpha+\boldsymbol{\beta}^{\prime} \boldsymbol{X}\right)}{\sqrt{\sigma_{Y}^{2} \operatorname{var}\left(\alpha+\boldsymbol{\beta}^{\prime} \boldsymbol{X}\right)}}=\frac{\boldsymbol{\beta}^{\prime} \boldsymbol{V} \boldsymbol{\beta}}{\sqrt{\sigma_{Y}^{2} \boldsymbol{\beta}^{\prime} \boldsymbol{V} \boldsymbol{\beta}}}
$$

This expression is positive since $\boldsymbol{V}$ is the positive definite matrix.
Theorem 2.14 Coefficient of multiple correlation satisfies $\rho_{Y, \boldsymbol{X}}$ and residual variance $\sigma_{Y . X}^{2}$ satisfy the relation

$$
\begin{equation*}
\rho_{Y, \boldsymbol{X}}^{2}=1-\frac{\sigma_{Y, \boldsymbol{X}}^{2}}{\sigma_{Y}^{2}} \tag{2.17}
\end{equation*}
$$

Proof. Assertion follows from formulas (2.10) a (2.13).
Formula (2.17) can be also written in the form

$$
\sigma_{Y, \boldsymbol{X}}^{2}=\sigma_{Y}^{2}\left(1-\rho_{Y, \boldsymbol{X}}^{2}\right)
$$

Here we can see that for increasing value of the coefficient of multiple correlation the residual variance $\sigma_{Y . X}^{2}$ decreases.

Theorem 2.15 Coefficient of multiple correlation $\rho_{Y, \boldsymbol{X}}$ is the largest one from all correlation coefficients between $Y$ and an arbitrary linear function of the vector $\boldsymbol{X}$, which is not constant.

Proof. The assertion is obvious if $\boldsymbol{\beta}=\mathbf{0}$; in this case $\rho_{Y, \boldsymbol{X}}=0$ and also $\rho_{Y, a+b^{\prime} \boldsymbol{X}}=0$ for an arbitrary vector $\boldsymbol{b} \neq \mathbf{0}$. In the case $\boldsymbol{b}=\mathbf{0}$ the correlation coefficient is not defined. So assume that $\boldsymbol{\beta} \neq \mathbf{0}$. We prove that then $\rho_{Y, a+\boldsymbol{b}^{\prime} \boldsymbol{X}}^{2} \leq \rho_{Y, \alpha+\boldsymbol{\beta}^{\prime} \boldsymbol{X}}^{2}$ for an arbitrary vector $\boldsymbol{b} \neq \mathbf{0}$. Since numbers $a$ and $\alpha$ have no influence on the correlation coefficients it suffices to prove the inequality $\rho_{Y, \boldsymbol{b}^{\prime} \boldsymbol{X}}^{2} \leq \rho_{Y, \boldsymbol{\beta}^{\prime} \boldsymbol{X}}^{2}$. We have

$$
\rho_{Y, b^{\prime} \boldsymbol{X}}^{2}=\frac{\left[\operatorname{cov}\left(Y, \boldsymbol{b}^{\prime} \boldsymbol{X}\right)\right]^{2}}{\sigma_{Y}^{2} \operatorname{var} \boldsymbol{b}^{\prime} \boldsymbol{X}}=\frac{[\operatorname{cov}(Y, \boldsymbol{X}) \boldsymbol{b}]^{2}}{\sigma_{Y}^{2} \boldsymbol{b}^{\prime} \boldsymbol{V} \boldsymbol{b}}
$$

From (2.14) we have

$$
[\operatorname{cov}(Y, \boldsymbol{X}) \boldsymbol{b}]^{2}=\left(\boldsymbol{\beta}^{\prime} \boldsymbol{V} \boldsymbol{b}\right)^{2}
$$

Matrix $\boldsymbol{V}$ is positive definite. Thus there exists a matrix $\boldsymbol{V}^{1 / 2}$, which is symmetric, positive definite and which fulfills $\boldsymbol{V}^{1 / 2} \boldsymbol{V}^{1 / 2}=\boldsymbol{V}$. Using Schwarz inequality we get

$$
\begin{aligned}
\left(\boldsymbol{\beta}^{\prime} \boldsymbol{V} \boldsymbol{b}\right)^{2} & =\left(\boldsymbol{\beta}^{\prime} \boldsymbol{V}^{1 / 2} \boldsymbol{V}^{1 / 2} \boldsymbol{b}\right)^{2}=\left[\left(\boldsymbol{V}^{1 / 2} \boldsymbol{\beta}\right)^{\prime}\left(\boldsymbol{V}^{1 / 2} \boldsymbol{b}\right)\right]^{2} \\
& =\leq\left(\boldsymbol{V}^{1 / 2} \boldsymbol{\beta}\right)^{\prime}\left(\boldsymbol{V}^{1 / 2} \boldsymbol{\beta}\right) \cdot\left(\boldsymbol{V}^{1 / 2} \boldsymbol{b}\right)^{\prime}\left(\boldsymbol{V}^{1 / 2} \boldsymbol{b}\right)=\left(\boldsymbol{\beta}^{\prime} \boldsymbol{V} \boldsymbol{\beta}\right)\left(\boldsymbol{b}^{\prime} \boldsymbol{V} \boldsymbol{b}\right)
\end{aligned}
$$

Thus

$$
\rho_{Y, b^{\prime} \boldsymbol{X}}^{2} \leq \frac{\left(\boldsymbol{\beta}^{\prime} \boldsymbol{V} \boldsymbol{\beta}\right)\left(\boldsymbol{b}^{\prime} \boldsymbol{V} \boldsymbol{b}\right)}{\sigma_{Y}^{2} \boldsymbol{b}^{\prime} \boldsymbol{V} \boldsymbol{b}}=\frac{\boldsymbol{\beta}^{\prime} \boldsymbol{V} \boldsymbol{\beta}}{\sigma_{Y}^{2}}=\rho_{Y, \boldsymbol{X}}^{2}
$$

The last equality is ensured by formula (2.13).
Theorem 2.15 guarantees that the coefficient $\rho_{Y, \boldsymbol{X}}$ is never smaller than the absolute value of any correlation coefficient $\rho_{Y, X_{i}}, i=1, \ldots, n$. This result is sometimes used for checking the calculations.

Theorem 2.16 We have

$$
\begin{equation*}
\rho_{Y, \boldsymbol{X}}^{2}=\operatorname{cor}(Y, \boldsymbol{X}) \boldsymbol{P}^{-1} \operatorname{cor}(\boldsymbol{X}, Y), \tag{2.18}
\end{equation*}
$$

where $\boldsymbol{P}=\operatorname{cor} \boldsymbol{X}$.
Proof. The assertion follows from formula (2.13). For details see Anděl (2007).
Very often we have the case when the vector $\boldsymbol{X}$ has two components. To simplify notation we write $X_{0}=Y$. Then $\rho_{i j}, i, j=0,1,2$ is the correlation coefficient between $X_{i}$ and $X_{j}$ and instead of $\rho_{Y, \boldsymbol{X}}$ we write $\rho_{0.1,2}$. Inserting into (2.18) one gets

$$
\begin{equation*}
\rho_{0.1,2}^{2}=\frac{\rho_{01}^{2}+\rho_{02}^{2}-2 \rho_{01} \rho_{02} \rho_{12}}{1-\rho_{12}^{2}} \tag{2.19}
\end{equation*}
$$

The coefficient $\rho_{0.1,2}$ measures the total dependence of the variable $Y$ on the complete vector $\left(X_{1}, X_{2}\right)^{\prime}$. This dependence can be very large even when the dependence of $Y$ on every component $X_{1}, X_{2}$ is quite small. We demonstrate it on an example.

Example 2.17 Let $\rho_{01}=0$ and $\rho_{02} \neq 0$. Then (2.19) gives

$$
\rho_{0.1,2}^{2}=\frac{\rho_{02}^{2}}{1-\rho_{12}^{2}} .
$$

Theorem 2.13 ensures that the fraction $\rho_{02}^{2} /\left(1-\rho_{12}^{2}\right)$ is never larger than 1 . But the number $\rho_{0.1,2}^{2}$ can be arbitrary close to one if $\rho_{12}^{2}$ is sufficiently large. The explanation can be the following one. Let $Y$ and $X_{1}$ be independent variables. Define $X_{2}=Y-X_{1}$. Denote $\operatorname{var} Y=\sigma_{0}^{2}, \operatorname{var} X_{1}=\sigma_{1}^{2}$. An easy calculation gives $\rho_{01}=0, \rho_{02}=\left(\sigma_{0}^{2}+\sigma_{1}^{2}\right)^{-1 / 2} \sigma_{0}$, $\rho_{12}=-\left(\sigma_{0}^{2}+\sigma_{1}^{2}\right)^{-1 / 2} \sigma_{1}, \rho_{0.1,2}^{2}=1$. Choosing $\sigma_{0}$ sufficiently small and $\sigma_{1}$ sufficiently large, the correlation coefficient $\rho_{02}$ will have arbitrary small value. The variable $Y$ is not correlated with $X_{1}$, its correlation with $X_{2}$ is very small, but both the variables simultaneously define it uniquely since $Y=X_{1}+X_{2}$.

### 2.8 Coefficient of partial correlation

Coefficient of partial correlation measures dependence of two random variables. The dependence may not be causal, it can arise under the influence of other confounding factors. Consider two random variables $Y$ and $Z$ and a random vector $\boldsymbol{X}=\left(X_{1}, \ldots, X_{n}\right)^{\prime}$. Assume that $\boldsymbol{X}$ may have influence on both $Y$ and $Z$. We want to ask how large would be dependence between $Y$ and $Z$ without influence of $\boldsymbol{X}$. One possibility how to investigate it is to create such situation that the vector $\boldsymbol{X}$ remains constant. In most cases it is not possible and so it is necessary to find a mathematical solution.

We know from theorem 2.9 that the best linear approximation of the variable $Y$ is $\hat{Y}=\alpha+\boldsymbol{\beta}^{\prime} \boldsymbol{X}$, where $\alpha$ and $\boldsymbol{\beta}$ are introduced in (2.9). From this reason we can interprete $Y-\hat{Y}$ as such a part of variable $Y$ which is cleared from influence of the vector $\boldsymbol{X}$. Similarly, let $\hat{Z}=\gamma+\boldsymbol{\delta}^{\prime} \boldsymbol{X}$ be the best linear approximation of variable $Z$ based on $\boldsymbol{X}$. It follows from (2.9) that

$$
\begin{equation*}
\boldsymbol{\delta}=\boldsymbol{V}^{-1} \operatorname{cov}(\boldsymbol{X}, Z), \quad \gamma=\mathrm{E} Z-\boldsymbol{\delta}^{\prime} \mathrm{E} \boldsymbol{X} \tag{2.20}
\end{equation*}
$$

The part of variable $Z$ which is not explained by the vector $\boldsymbol{X}$ can be interpreted as $Z-\hat{Z}$. From this reason the dependence between $Y$ a $Z$ after elimination of influence of vector $\boldsymbol{X}$ is measured by the correlation coefficient between $Y-\hat{Y}$ and $Z-\hat{Z}$. It is called partial correlation coefficient between $Y$ and $Z$ given $\boldsymbol{X}$. It is denoted by $\rho_{Y, Z \cdot \boldsymbol{X}}$.

Theorem 2.18 Let random variables $Y, Z, X_{1}, \ldots, X_{n}$ have finite second moments and the regular variance matrix. Denote $\boldsymbol{P}=\operatorname{cor} \boldsymbol{X}$. Then it holds

$$
\rho_{Y, Z . \boldsymbol{X}}=\frac{\rho_{Y Z}-\operatorname{cor}(Y, \boldsymbol{X}) \boldsymbol{P}^{-1} \operatorname{cor}(\boldsymbol{X}, Z)}{\sqrt{\left[1-\operatorname{cor}(Y, \boldsymbol{X}) \boldsymbol{P}^{-1} \operatorname{cor}(\boldsymbol{X}, Y)\right]\left[1-\operatorname{cor}(Z, \boldsymbol{X}) \boldsymbol{P}^{-1} \operatorname{cor}(\boldsymbol{X}, Z)\right]}} .
$$

Proof. Theorem follows from the formula for the correlation coefficient between $Y-\alpha-$ $\boldsymbol{\beta}^{\prime} \boldsymbol{X}$ and $Z-\gamma-\boldsymbol{\delta}^{\prime} \boldsymbol{X}$. Using (2.9) and (2.20) we obtain the result.

For the coefficient of partial correlation we have no such inequalities like in case of the correlation of multiple correlation. From this reason $\rho_{Y, Z . X}$ may be sometimes smaller and sometimes greater than $\rho_{Y Z}$.

Let $n=1$, so that the vector $\boldsymbol{X}$ has only one component. Then we get from theorem 2.18 that

$$
\rho_{Y, Z . X}=\frac{\rho_{Y Z}-\rho_{X Y} \rho_{X Z}}{\sqrt{\left(1-\rho_{X Y}^{2}\right)\left(1-\rho_{X Z}^{2}\right)}}
$$

Example 2.19 In England investigated how the harvest of hay (variable $Y$ ) depends on temperature (variable $Z$, which is equal to the sum of temperaturs larger than $42{ }^{\circ} \mathrm{F}$ $\doteq 5,6^{\circ} \mathrm{C}$ in individual days of the considered spring season). It was found that $\rho_{Y Z}=$ -0.40 . The negative correlation does not correspond our experience that the gras grows faster if the weather is warmer. Then the calculation included precipitation (variable $X)$ and the other correlation coefficients were calculated. The result was $\rho_{X Y}=0.80$, $\rho_{X Z}=-0.56$. If it rains, more gras grows, but it is colder. The result is $\rho_{Y, Z . X}=0.10$. The details can be found in Hooker (1907) and in Yule, Kendall (1950).

### 2.9 Multinomial distribution

Assume that in an experiment one of the events $A_{1}, \ldots, A_{k}$ can be realized. Let the events be disjoint and one of them must be realized. We denote their probabilities $p_{i}=\mathrm{P}\left(A_{i}\right)$, $i=1, \ldots, k$. Our assumptions imply that $p_{1}+\cdots+p_{k}=1$. Moreover, let all probabilities $p_{i}$ be positive.

Consider the case that the experiments are $n$-times independently repeated. Let $X_{i}$ be number of realizations of the event $A_{i}$ in such series of experiments. Then we have

$$
\begin{equation*}
\mathrm{P}\left(X_{1}=x_{1}, \ldots, X_{k}=x_{k}\right)=\frac{n!}{x_{1}!\ldots x_{k}!} p_{1}^{x_{1}} \ldots p_{k}^{x_{k}} \tag{2.21}
\end{equation*}
$$

for nonnegative integers $x_{1}, \ldots, x_{k}$ the sum of which equals to $n$. In any other case this probability is zero. The distribution defined by formula (2.21) is called multinomial.

In the special case $k=2$ we can the event $A_{1}$ call the success and the event $A_{2}$ failure. Then (2.21) will be the binomial distribution. However, this situation can arise also for general $k$, if we introduce events $A=A_{1}$ and $B=A_{2} \cup \cdots \cup A_{k}$. Thus the marginal distribution of the random variable $X_{1}$ is $\operatorname{Bi}\left(n, p_{1}\right)$ and similarly $X_{i} \sim \operatorname{Bi}\left(n, p_{i}\right)$ also for other values $i$.

Theorem 2.20 In multinomial distribution we have

$$
\begin{equation*}
\mathrm{E} X_{i}=n p_{i}, \quad \operatorname{var} X_{i}=n p_{i}\left(1-p_{i}\right) \quad \text { for } i=1, \ldots, k \tag{2.22}
\end{equation*}
$$

and

$$
\begin{equation*}
\operatorname{cov}\left(X_{i}, X_{j}\right)=-n p_{i} p_{j} \quad \text { for } i \neq j \tag{2.23}
\end{equation*}
$$

Proof. Formula (2.22) follows from $X_{i} \sim \operatorname{Bi}\left(n, p_{i}\right)$. We are going to prove (2.23). We introduce random variables $\xi_{h i}$ in the following way. Define $\xi_{h i}=1$ if in the $h$-th experiment the event $A_{i}$ appeared and $\xi_{h i}=0$ in other cases. The experiments are independent and so

$$
\begin{equation*}
\operatorname{cov}\left(\xi_{h i}, \xi_{m j}\right)=0 \quad \text { for } h \neq m \tag{2.24}
\end{equation*}
$$

We can see that

$$
\begin{equation*}
\xi_{h i} \xi_{h j}=0 \quad \text { for } i \neq j \tag{2.25}
\end{equation*}
$$

since in the $h$-th experiment the events $A_{i}$ and $A_{j}$ could not appear simultaneously. An easy calculation gives $\mathrm{E} \xi_{h i}=p_{i}$. Since

$$
\begin{equation*}
X_{i}=\sum_{h=1}^{n} \xi_{h i}, \tag{2.26}
\end{equation*}
$$

using (2.26), (2.24) and (2.25) for $i \neq j$ we get

$$
\begin{aligned}
\operatorname{cov}\left(X_{i}, X_{j}\right) & =\operatorname{cov}\left(\sum_{h=1}^{n} \xi_{h i}, \sum_{m=1}^{n} \xi_{m j}\right)=\sum_{h=1}^{n} \sum_{m=1}^{n} \operatorname{cov}\left(\xi_{h i}, \xi_{m j}\right) \\
& =\sum_{h=1}^{n} \operatorname{cov}\left(\xi_{h i}, \xi_{h j}\right)=\sum_{h=1}^{n}\left(\mathrm{E} \xi_{h i} \xi_{h j}-\mathrm{E} \xi_{h i} \mathrm{E} \xi_{h j}\right) \\
& =-\sum_{h=1}^{n} p_{i} p_{j}=-n p_{i} p_{j} .
\end{aligned}
$$

A matrix $\boldsymbol{A}$ is called idempotent if it is a square matrix and if $\boldsymbol{A}^{2}=\boldsymbol{A}$ holds.
Theorem 2.21 Denote

$$
\boldsymbol{u}=\left(\sqrt{p_{1}}, \ldots, \sqrt{p_{k}}\right)^{\prime}, \quad \boldsymbol{Q}=\boldsymbol{I}-\boldsymbol{u} \boldsymbol{u}^{\prime}, \quad \boldsymbol{D}=\operatorname{Diag}\left\{\sqrt{n p_{1}}, \ldots, \sqrt{n p_{k}}\right\}
$$

Then the matrix $\boldsymbol{Q}$ is idempotent and its rank is $k-1$. Variance matrix $\boldsymbol{V}$ of the random vector $\boldsymbol{X}=\left(X_{1}, \ldots, X_{k}\right)^{\prime}$ with multinomial distribution is $\boldsymbol{V}=\boldsymbol{D} \boldsymbol{Q} \boldsymbol{D}$.

Proof. It can be easily checked that the matrix $\boldsymbol{Q}$ is idempotent. The rank of the matrix $\boldsymbol{Q}$ is equal to its trace and it is $k-1$. Elements of the matrix $\boldsymbol{V}$ were calculated in Theorem 2.20, and thus the relation $\boldsymbol{V}=\boldsymbol{D} \boldsymbol{Q} \boldsymbol{D}$ can be easily verified.

Define $\boldsymbol{Y}=\boldsymbol{D}^{-1} \boldsymbol{X}$. We can see that

$$
\boldsymbol{Y}=\left(\begin{array}{c}
\frac{X_{1}}{\sqrt{n p_{1}}} \\
\vdots \\
\frac{X_{k}}{\sqrt{n p_{k}}}
\end{array}\right), \quad \mathrm{E} \boldsymbol{Y}=\left(\begin{array}{c}
\sqrt{n p_{1}} \\
\vdots \\
\sqrt{n p_{k}}
\end{array}\right)
$$

and an easy calculation gives

$$
\operatorname{var} \boldsymbol{Y}=\boldsymbol{D}^{-1} \boldsymbol{V} \boldsymbol{D}^{-1}=\boldsymbol{D}^{-1} \boldsymbol{D} \boldsymbol{Q} \boldsymbol{D} \boldsymbol{D}^{-1}=\boldsymbol{Q}
$$

Define $\chi^{2}=(\boldsymbol{Y}-\mathbf{E} \boldsymbol{Y})^{\prime}(\boldsymbol{Y}-\mathbf{E} \boldsymbol{Y})$. This expression can be written in the form

$$
\chi^{2}=\sum_{i=1}^{n}\left(Y_{i}-\mathrm{E} Y_{i}\right)^{2}=\sum_{i=1}^{n}\left(\frac{X_{i}}{\sqrt{n p_{i}}}-\sqrt{n p_{i}}\right)^{2}=\sum_{i=1}^{n} \frac{\left(X_{i}-n p_{i}\right)^{2}}{n p_{i}}
$$

## Chapter 3

## Transformations

### 3.1 Transformations of random variables

Let $X$ be a random variable and $t$ a measurable function. If $Y=t(X)$, then we say that the variable $Y$ is the transformation of the variable $X$. Our task is to derive statistical characteristics of the variable $Y$ from the known characteristics of the variable $X$. We met two important cases already in section 1.3 (see theorems 1.10 and 1.11). Now, we are going to investigate general cases.

Theorem 3.1 Let $X$ have a continuous distribution function $F$. Let $F^{\prime}(x)=f(x)$ exist everywhere with exception maximally finite number of points. Let $t$ be a monotonous function that has everywhere a nonvanishing derivative. Let $\tau$ be the inverse function to $t$. Then the random variable $Y=t(X)$ has the density

$$
g(y)=f[\tau(y)]\left|\tau^{\prime}(y)\right| .
$$

Proof. Assume first that $t$ is increasing. Then the distribution function $G$ of the random variable $Y$ is equal to

$$
G(y)=\mathrm{P}(Y \leq y)=\mathrm{P}[t(X) \leq y]=\mathrm{P}[X \leq \tau(y)]=F[\tau(y)] .
$$

The assumptions of theorem ensure that $G$ is continuous and differentiable everywhere except maximally in finite many points. From this reason the density $g(y)$ of the variable $Y$ is equal to

$$
g(y)=G^{\prime}(y)=f[\tau(y)] \tau^{\prime}(y) .
$$

Since $t$ is increasing, $\tau$ is also increasing and $\tau^{\prime}(y)=\left|\tau^{\prime}(y)\right|$. If $t$ is decreasing, the proof is similar.

The proof of theorem 3.1 was very simple. In many cases we can derive distribution of $Y=t(X)$, even if the mapping $t$ is not monotonous.

Example 3.2 Let $X \sim \mathrm{~N}(0,1)$. As introduced in section 1.2, the density of $X$ is denoted $\varphi$ and its distribution function $\Phi$. Define $Y=X^{2}$. Let $G$ denote the distribution function of variable $Y$. It is clear that $G(y)=0$ if $y \leq 0$. In the case $y>0$ we get

$$
G(y)=\mathrm{P}(Y<y)=\mathrm{P}\left(X^{2}<y\right)=\mathrm{P}(-\sqrt{y}<X<\sqrt{y})=\Phi(\sqrt{y})-\Phi(-\sqrt{y}) .
$$

Since $\Phi(-x)=1-\Phi(x)$, we have together

$$
G(y)=2 \Phi(\sqrt{y})-1
$$

It implies that the density $g$ of the variable $Y$ vanishes on the interval $(-\infty, 0]$. If $y>0$ then

$$
g(y)=G^{\prime}(y)=\frac{1}{\sqrt{y}} \varphi(\sqrt{y})=\frac{1}{\sqrt{2 \pi y}} \mathrm{e}^{-y / 2} .
$$

The distribution of the random variable $Y$ with the density $g$ is called chi-square distribution with one degree of freedom and it is denoted $\chi_{1}^{2}$. The expectation of this distribution is $\mu=\mathrm{E} Y=\mathrm{E} X^{2}=1$, the variance is $\sigma^{2}=\operatorname{var} Y=\mathrm{E} Y^{2}-(\mathrm{E} Y)^{2}=$ $\mathrm{E} X^{4}-\left(\mathrm{E} X^{2}\right)^{2}=3-1^{2}=2$ 。

### 3.2 Transformations of random vectors

Theorem 3.3 Assume that the random vector $\boldsymbol{X}=\left(X_{1}, \ldots, X_{n}\right)^{\prime}$ has the density $f(\boldsymbol{x})$, where $\boldsymbol{x}=\left(x_{1}, \ldots, x_{n}\right)^{\prime}$. Let $t$ be a regular one-to-one mapping from $\mathbb{R}_{n}$ onto $\mathbb{R}_{n}$. Denote $\tau$ the inverse mapping to $t$. Then the random vector $\boldsymbol{Y}=t(\boldsymbol{X})$ has the density

$$
g(\boldsymbol{y})=f[\tau(\boldsymbol{y})]\left|D_{\tau}(\boldsymbol{y})\right|
$$

where

$$
D_{\tau}(\boldsymbol{y})=\left|\begin{array}{ccc}
\frac{\partial \tau_{1}}{\partial y_{1}} & \cdots & \frac{\partial \tau_{1}}{\partial y_{n}} \\
\cdots \cdots & \cdots & \cdots \\
\frac{\partial \tau_{n}}{\partial y_{1}} & \cdots & \frac{\partial \tau_{n}}{\partial y_{n}}
\end{array}\right|
$$

is the jacobi determinant of the mapping $\tau$.
Proof. Let $B \in \mathcal{B}_{n}$ be an arbitrary borel set. Substitution theorem in multiple integrals gives

$$
\begin{align*}
\mathrm{P}(\boldsymbol{Y} \in B) & =\mathrm{P}[t(\boldsymbol{X}) \in B]=\mathrm{P}[\boldsymbol{X} \in \tau(B)] \\
& =\int_{\tau(B)} f(\boldsymbol{x}) \mathrm{d} \boldsymbol{x}=\int_{B} f[\tau(\boldsymbol{y})]\left|D_{\tau}(\boldsymbol{y})\right| \mathrm{d} \boldsymbol{y}=\int_{B} g(\boldsymbol{y}) \mathrm{d} \boldsymbol{y} . \tag{3.1}
\end{align*}
$$

It suffices to choose

$$
B=\left(-\infty, x_{1}\right] \times \cdots \times\left(-\infty, x_{n}\right]
$$

so that $\mathrm{P}(\boldsymbol{Y} \in B)$ is the value of the distribution function of the random vector $\boldsymbol{Y}$ in point $\boldsymbol{x}$. Formula (3.1) makes sure that $g$ is the density corresponding to this distribution function.

Let $X_{1}, \ldots, X_{n}$ be independent random variables with distribution $\mathrm{N}(0,1)$. Define $\boldsymbol{X}=\left(X_{1}, \ldots, X_{n}\right)^{\prime}$. Then $\mathbf{E} \boldsymbol{X}=\mathbf{0}$, var $\boldsymbol{X}=\boldsymbol{I}$. We say that $\boldsymbol{X} \sim \mathbf{N}(\mathbf{0}, \boldsymbol{I})$. The density of the vector $\boldsymbol{X}$ is

$$
f(\boldsymbol{x})=\prod_{i=1}^{n} \frac{1}{\sqrt{2 \pi}} \exp \left\{-\frac{1}{2} x_{i}^{2}\right\}=\frac{1}{(2 \pi)^{n / 2}} \exp \left\{-\frac{1}{2} \boldsymbol{x}^{\prime} \boldsymbol{x}\right\} .
$$

Let $\boldsymbol{\mu} \in \mathbb{R}_{n}$ and let $\boldsymbol{V}$ be a positive definite matrix. Denote $\boldsymbol{B}=\boldsymbol{V}^{1 / 2}$ and introduce the vector $\boldsymbol{Y}=\boldsymbol{\mu}+\boldsymbol{B} \boldsymbol{X}$. Obviously $\mathrm{E} \boldsymbol{Y}=\boldsymbol{\mu}, \operatorname{var} \boldsymbol{Y}=\boldsymbol{B I} \boldsymbol{B}^{\prime}=\boldsymbol{V}$. The inverse transformation is $\boldsymbol{X}=\boldsymbol{B}^{-1} \boldsymbol{Y}-\boldsymbol{B}^{-1} \boldsymbol{\mu}$ and its jacobian is det $\boldsymbol{B}^{-1}$. The simultaneous density of the vector $\boldsymbol{Y}$ is

$$
g(\boldsymbol{y})=\frac{1}{(2 \pi)^{n / 2}} \exp \left\{-\frac{1}{2}\left[\boldsymbol{B}^{-1}(\boldsymbol{y}-\boldsymbol{\mu})\right]^{\prime}\left[\boldsymbol{B}^{-1}(\boldsymbol{y}-\boldsymbol{\mu})\right]\right\}\left|\operatorname{det} \boldsymbol{B}^{-1}\right|
$$

Since $\left|\operatorname{det} \boldsymbol{B}^{-1}\right|=|\boldsymbol{V}|^{-1 / 2}$, we get

$$
g(\boldsymbol{y})=\frac{1}{(2 \pi)^{n / 2}|\boldsymbol{V}|^{1 / 2}} \exp \left\{-\frac{1}{2}(\boldsymbol{y}-\boldsymbol{\mu})^{\prime}\left(\boldsymbol{B}^{-1}\right)^{\prime} \boldsymbol{B}^{-1}(\boldsymbol{y}-\boldsymbol{\mu})\right\} .
$$

In view of $\left(\boldsymbol{B}^{-1}\right)^{\prime} \boldsymbol{B}^{-1}=\boldsymbol{V}^{-1}$, we have

$$
\begin{equation*}
g(\boldsymbol{y})=\frac{1}{(2 \pi)^{n / 2}|\boldsymbol{V}|^{1 / 2}} \exp \left\{-\frac{1}{2}(\boldsymbol{y}-\boldsymbol{\mu})^{\prime} \boldsymbol{V}^{-1}(\boldsymbol{y}-\boldsymbol{\mu})\right\} . \tag{3.2}
\end{equation*}
$$

We say that $\boldsymbol{Y} \sim \mathrm{N}(\boldsymbol{\mu}, \boldsymbol{V})$. The density of the vector $\boldsymbol{Y}$ is given by formula (3.2). Because the matrix $\boldsymbol{V}$ is regular, the distribution $\mathrm{N}(\boldsymbol{\mu}, \boldsymbol{V})$ is called regular normal distribution.

Let $\boldsymbol{a} \in \mathbb{R}_{n}$ and let $\boldsymbol{C}$ be a $n \times n$ regular matix. Define $\boldsymbol{Z}=\boldsymbol{a}+\boldsymbol{C} \boldsymbol{Y}$. It is clear that $\mathrm{E} \boldsymbol{Z}=\boldsymbol{a}+\boldsymbol{C} \boldsymbol{\mu}$ and $\operatorname{var} \boldsymbol{Z}=\boldsymbol{C V} \boldsymbol{C}^{\prime}$. Theorem about transformation gives that the density of the vector $\boldsymbol{Z}$ is

$$
h(\boldsymbol{z})=\frac{1}{(2 \pi)^{n / 2}\left|\boldsymbol{C} \boldsymbol{V} \boldsymbol{C}^{\prime}\right|^{1 / 2}} \exp \left\{-\frac{1}{2}(\boldsymbol{z}-\boldsymbol{a}-\boldsymbol{C} \boldsymbol{\mu})^{\prime}\left(\boldsymbol{C} \boldsymbol{V} \boldsymbol{C}^{\prime}\right)^{-1}(\boldsymbol{z}-\boldsymbol{a}-\boldsymbol{C} \boldsymbol{\mu})\right\} .
$$

We see that $\boldsymbol{Z} \sim \mathrm{N}\left(\boldsymbol{a}+\boldsymbol{C} \boldsymbol{\mu}, \boldsymbol{C V} \boldsymbol{C}^{\prime}\right)$.
We inform without proof that this result is true also in the case when $\boldsymbol{a}$ is a vector with $m$ components and $\boldsymbol{C}$ is a $m \times n$ matrix. If the rank of the matrix $\boldsymbol{C} \boldsymbol{V} \boldsymbol{C}^{\prime}$ is smaller than $m$, the vector $\boldsymbol{Y}=\boldsymbol{a}+\boldsymbol{C X}$ has the singular normal distribution.

We divide $\boldsymbol{X}$ into two blocks so that $\boldsymbol{X}=\left(\boldsymbol{Y}^{\prime}, \boldsymbol{Z}^{\prime}\right)^{\prime}$, where $\boldsymbol{Y}$ contains first $k$ components of the vector $\boldsymbol{X}$ and $\boldsymbol{Z}$ remaining $n-k$ components. The matrix $\boldsymbol{V}$ and vector $\boldsymbol{\mu}$ are divided analogously. We have

$$
\boldsymbol{\mu}=\binom{\boldsymbol{\nu}}{\boldsymbol{\tau}}, \quad \boldsymbol{V}=\left(\begin{array}{ll}
\boldsymbol{V}_{11} & \boldsymbol{V}_{12} \\
\boldsymbol{V}_{21} & \boldsymbol{V}_{22}
\end{array}\right)
$$

where $\boldsymbol{\nu}$ has $k$ components, $\boldsymbol{\tau}$ has $n-k$ components, $\boldsymbol{V}_{11}$ is $k \times k$ matrix and $\boldsymbol{V}_{22}$ is a $(n-k) \times(n-k)$ matrix.

It can be proved that $\boldsymbol{Y} \sim \mathrm{N}\left(\boldsymbol{\nu}, \boldsymbol{V}_{11}\right)$ and that $\boldsymbol{Z} \sim \mathrm{N}\left(\boldsymbol{\tau}, \boldsymbol{V}_{22}\right)$. All the marginal distributions in multidimensional normal distribution are also normal. Marginal distribution of the variable $X_{i}$ is $\mathrm{N}\left(\mu_{i}, \sigma_{i}^{2}\right)$, where $\sigma_{i}^{2}=\sigma_{i i}$.

If $\boldsymbol{V}_{12}=\mathbf{0}$, then the vectors $\boldsymbol{Y}$ and $\boldsymbol{Z}$ are uncorrelated. Since $\boldsymbol{V}_{21}=\boldsymbol{V}_{12}^{\prime}=\mathbf{0}$, the density of the vector $\boldsymbol{X}$ can be written in the form of the product of vectors $\boldsymbol{Y}$ and $\boldsymbol{Z}$. This proves that under assumption of normal distribution of the vector $\boldsymbol{X}$ uncorrelated vectors $\boldsymbol{Y}$ and $\boldsymbol{Z}$ are independent.

Frequently we deal with the case $n=2, k=1$. Then $\boldsymbol{X}=\left(X_{1}, X_{2}\right)^{\prime}$. Variance matrix $\boldsymbol{V}$ has the form

$$
\boldsymbol{V}=\left(\begin{array}{cc}
\sigma_{1}^{2} & \rho \sigma_{1} \sigma_{2} \\
\rho \sigma_{1} \sigma_{2} & \sigma_{2}^{2}
\end{array}\right)
$$

where $\rho$ is the correlation coefficient of the variables $X_{1}$ and $X_{2}$. If $\sigma_{1}^{2}>0, \sigma_{2}^{2}>0$, and $\rho \in(-1,1)$, then inserting into (3.2) we get the density of the two-dimensional normal distribution

$$
\begin{aligned}
& f\left(x_{1}, x_{2}\right)=\frac{1}{2 \pi \sigma_{1} \sigma_{2} \sqrt{1-\rho^{2}}} \\
& \quad \times \exp \left\{-\frac{1}{2\left(1-\rho^{2}\right)}\left[\frac{\left(x_{1}-\mu_{1}\right)^{2}}{\sigma_{1}^{2}}-2 \rho \frac{\left(x_{1}-\mu_{1}\right)\left(x_{2}-\mu_{2}\right)}{\sigma_{1} \sigma_{2}}+\frac{\left(x_{2}-\mu_{2}\right)^{2}}{\sigma_{2}^{2}}\right]\right\}
\end{aligned}
$$

Since the marginal density of the variable $X_{2}$ is

$$
q\left(x_{2}\right)=\frac{1}{\sqrt{2 \pi} \sigma_{2}} \exp \left[-\frac{\left(x_{2}-\mu_{2}\right)^{2}}{2 \sigma_{2}^{2}}\right]
$$

according to the section 2.4 we get the conditioned density of the variable $X_{1}$ given $X_{2}=x_{2}$ as

$$
r\left(x_{1} \mid x_{2}\right)=f\left(x_{1}, x_{2}\right) / q\left(x_{2}\right)
$$

We can see that $r\left(x_{1} \mid x_{2}\right)$ is the density of the distribution

$$
\mathrm{N}\left[\mu_{1}+\rho \frac{\sigma_{1}}{\sigma_{2}}\left(x_{2}-\mu_{2}\right), \sigma_{1}^{2}\left(1-\rho^{2}\right)\right] .
$$

Theorems 3.1 and 3.3 have rather restrictive assumptions. We have made them to simplify the proofs and they can be removed.

Theorem 3.4 Assume that the random vector $\boldsymbol{X}=\left(X_{1}, \ldots, X_{n}\right)^{\prime}$ has the density $f(\boldsymbol{x})$, where $\boldsymbol{x}=\left(x_{1}, \ldots, x_{n}\right)^{\prime}$. Let $t$ be a mapping from $\mathbb{R}_{n}$ into $\mathbb{R}_{n}$, which is regular and one-to-one on such disjoint open sets $G_{1}, G_{2}, \ldots$, that for $G=\cup G_{i}$ we have

$$
\begin{equation*}
\int_{G} f(\boldsymbol{x}) \mathrm{d} \boldsymbol{x}=1 \tag{3.3}
\end{equation*}
$$

Let $\tau_{j}$ be the inverse mapping to $t: G_{j} \rightarrow t\left(G_{j}\right)$. Then the random vector $\boldsymbol{Y}=t(\boldsymbol{X})$ has the density

$$
g(\boldsymbol{y})=\sum_{j=1}^{\infty} g_{j}(\boldsymbol{y})
$$

where

$$
g_{j}(\boldsymbol{y})= \begin{cases}f\left[\tau_{j}(\boldsymbol{y})\right]\left|D_{\tau_{j}}(\boldsymbol{y})\right| & \text { for } \boldsymbol{y} \in t\left(G_{j}\right) \\ 0 & \text { for } \boldsymbol{y} \notin t\left(G_{j}\right)\end{cases}
$$

### 3.3 Functions of random variables

### 3.3.1 Method of calculation

Consider a random vector $\boldsymbol{X}=\left(X_{1}, \ldots, X_{n}\right)^{\prime}$ which has density $f(\boldsymbol{x})$. We must determine the density of a function $T_{1}=t_{1}\left(X_{1}, \ldots, X_{n}\right)$. Usually, the calculation is made in two steps.
(i) We look for a mapping $\boldsymbol{T}=t(\boldsymbol{X})$ such that $\boldsymbol{T}=\left(T_{1}, \ldots, T_{n}\right)^{\prime}$ and such that the assumptions of theorem 3.3 or theorem 3.4 are fulfilled. The first component of the vector $\boldsymbol{T}$ is the same as the function $t_{1}\left(X_{1}, \ldots, X_{n}\right)$, the distribution of which we are looking for. From this we determine the simultaneous density $g\left(t_{1}, \ldots, t_{n}\right)$ of the vector $\boldsymbol{T}$.
(ii) Marginal density $g_{1}$ of the variable $T_{1}$ can be calculated using formula

$$
g_{1}\left(t_{1}\right)=\int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} g\left(t_{1}, \ldots, t_{n}\right) \mathrm{d} t_{2} \ldots \mathrm{~d} t_{n}
$$

(see section 2.1).
In practical calculations the choice of the mapping $t$ in the first step is very important. If the procedure is not suitable, it may be difficult to calculate $g$ or integral which defines $g_{1}$.

### 3.3.2 Sum of variables

Theorem 3.5 (convolution theorem) Let $X_{1}$ and $X_{2}$ be independent random variables. Assume that $X_{1}$ has the density $f_{1}$ and $X_{2}$ has the density $f_{2}$. Then the random variable $Y=X_{1}+X_{2}$ has the density

$$
\begin{equation*}
h(y)=\int f_{1}(z) f_{2}(y-z) \mathrm{d} z \tag{3.4}
\end{equation*}
$$

Proof. Introduce the vector $\boldsymbol{X}=\left(X_{1}, X_{2}\right)^{\prime}$. It follows from theorem 2.6 that the variables $X_{1}, X_{2}$ have the simultaneous density $f\left(x_{1}, x_{2}\right)=f_{1}\left(x_{1}\right) f_{2}\left(x_{2}\right)$. Define

$$
\boldsymbol{T}=\binom{X_{1}+X_{2}}{X_{1}}=\binom{Y}{Z} .
$$

The inverse mapping is $X_{1}=Z, X_{2}=Y-Z$. Absolute value of jacobian is 1 and thus the simultaneous density $g(y, z)$ of the vector $\boldsymbol{T}$ is $g(y, z)=f_{1}(z) f_{2}(y-z)$. Marginal density of $Y$ is $h(y)=\int g(y, z) \mathrm{d} z$. The formula 3.4) is proved.

The formula

$$
h(y)=\int f_{1}(y-z) f_{2}(z) \mathrm{d} z
$$

can be proved analogously. This result also follows from the fact that $X_{1}+X_{2}=X_{2}+X_{1}$. We say that the density $h$ is the convolution of densities $f_{1}$ and $f_{2}$.

Let $X_{1} \sim \mathrm{~N}\left(\mu_{1}, \sigma_{1}^{2}\right), X_{2} \sim \mathrm{~N}\left(\mu_{2}, \sigma_{2}^{2}\right)$ be independent random variables with normal distribution. We prove that $X_{1}+X_{2} \sim N\left(\mu_{1}+\mu_{2}, \sigma_{1}^{2}+\sigma_{2}^{2}\right)$. If $\sigma_{1}^{2}=0$ or $\sigma_{2}^{2}=0$, the assertion is clear. If $\sigma_{1}^{2}>0, \sigma_{2}^{2}>0$, then the assertion follows from theorem 3.5.

Let $X_{1}, \ldots, X_{n}$ be independent random variables with normal distribution $\mathrm{N}(0,1)$. We define $Y=X_{1}^{2}+\cdots+X_{n}^{2}$. The density of the variable $Y$ will be denoted $f_{n}(y)$. It was already proved that

$$
f_{1}(y)=\frac{1}{\sqrt{2 \pi y}} \mathrm{e}^{-y / 2} \quad \text { for } y>0
$$

We prove that

$$
\begin{equation*}
f_{n}(y)=\frac{1}{2^{n / 2} \Gamma(n / 2)} y^{\frac{n}{2}-1} \mathrm{e}^{-y / 2} \quad \text { for } y>0 \tag{3.5}
\end{equation*}
$$

The formula is valid if $n=1$. For $n>1$ it will be proved by complete induction. Assume that it is valid for all $n \leq k$. Convolution theorem gives

$$
f_{k+1}(y)=\int f_{k}(z) f_{1}(y-z) \mathrm{d} z
$$

After some calculations we obtain formula 3.5), where $n=k+1$.
Function $f_{n}(y)$ is the density of chi-squared distribution with $n$ degrees of freedom, which is denoted as $\chi_{n}^{2}$. We already know that $\mathrm{E} X_{i}^{2}=1$, $\operatorname{var} X_{i}^{2}=2$ for all $i$. Thus $\mu=\mathrm{E} Y=n, \sigma^{2}=\operatorname{var} Y=2 n$. The expectation of $\chi_{n}^{2}$ distribution is equal to the number of degrees of freedom, variance is twice so much.

Notice that $f_{n}(y)$ is density for all real $n>0$, not only for integers.
Theorem 3.6 Let $X_{1}$ and $X_{2}$ be independent random variables such that $X_{1} \sim \chi_{m}^{2}$, $X_{2} \sim \chi_{n}^{2}$. Then $X_{1}+X_{2} \sim \chi_{m+n}^{2}$.

Proof. Using convolution theorem the density of $Y=X_{1}+X_{2}$ is

$$
h(y)=\int f_{m}(z) f_{n}(y-z) \mathrm{d} z
$$

After some calculations we get $h(y)=f_{m+n}(y)$.
Analyzing $\chi^{2}$ distribution we introduce a few theorems which are not connected directly with convolution.

Theorem 3.7 Let the random vector $\boldsymbol{X}=\left(X_{1}, \ldots, X_{n}\right)^{\prime}$ have the $n$-dimensional normal distribution $\mathrm{N}(\boldsymbol{\mu}, \boldsymbol{V})$ with the density (3.2). Then the random variable

$$
Y=(\boldsymbol{X}-\boldsymbol{\mu})^{\prime} \boldsymbol{V}^{-1}(\boldsymbol{X}-\boldsymbol{\mu})
$$

has the $\chi_{n}^{2}$ distribution.
Proof. Introduce the vector $\boldsymbol{Z}=\boldsymbol{V}^{-1 / 2}(\boldsymbol{X}-\boldsymbol{\mu})$. Then it can be proved that $\boldsymbol{Z} \sim \mathrm{N}(\mathbf{0}, \boldsymbol{I})$ and the density of $\boldsymbol{Z}$ is

$$
g(\boldsymbol{z})=\frac{1}{(2 \pi)^{n / 2}} \mathrm{e}^{-\boldsymbol{z}^{\prime} \boldsymbol{z} / 2}=\prod_{i=1}^{n}\left[\frac{1}{\sqrt{2 \pi}} \exp \left\{-\frac{1}{2} z_{i}^{2}\right\}\right] .
$$

Theorem 2.6 gives that the components $Z_{1}, \ldots, Z_{n}$ are independent random variables and each of them has $N(0,1)$ distribution. Since

$$
\boldsymbol{Z}^{\prime} \boldsymbol{Z}=Z_{1}^{2}+\cdots+Z_{n}^{2} \sim \chi_{n}^{2},
$$

we also have

$$
Y=(\boldsymbol{X}-\boldsymbol{\mu})^{\prime} \boldsymbol{V}^{-1}(\boldsymbol{X}-\boldsymbol{\mu})=\boldsymbol{Z}^{\prime} \boldsymbol{Z} \sim \chi_{n}^{2} .
$$

Theorem 3.8 Let $\boldsymbol{X} \sim \mathbf{N}(\mathbf{0}, \boldsymbol{V})$, where $\boldsymbol{V}$ is an idempotent matrix of rank $r \geq 1$. Then $\boldsymbol{X}^{\prime} \boldsymbol{X} \sim \chi_{r}^{2}$.

Proof. Every symmetric matrix $\boldsymbol{V}$ can be written in the form $\boldsymbol{V}=\boldsymbol{U} \boldsymbol{D} \boldsymbol{U}^{\prime}$, where $\boldsymbol{U} \boldsymbol{U}^{\prime}=\boldsymbol{I}$ is the unit matrix and $\boldsymbol{D}$ is a diagonal matrix having eigenvalues of the matrix $\boldsymbol{V}$ on the diagonal.

First we show that the eigenvalues of an idempotent matrix are only zeroes and ones. Indeed, $\lambda$ is an eigenvalue of the matrix $\boldsymbol{V}$ if and only if there exists a vector $\boldsymbol{x} \neq \mathbf{0}$ such that $\boldsymbol{V} \boldsymbol{x}=\lambda \boldsymbol{x}$. We multiply this equality by $\boldsymbol{V}$ from the left and we apply the fact that $\boldsymbol{V}$ is idempotent. This gives $\boldsymbol{V}^{2} \boldsymbol{x}=\lambda \boldsymbol{V} \boldsymbol{x}$, so that $\boldsymbol{V} \boldsymbol{x}=\lambda^{2} \boldsymbol{x}$. Thus $\lambda \boldsymbol{x}=\lambda^{2} \boldsymbol{x}$. Since $\boldsymbol{x} \neq \mathbf{0}$, we must have $\lambda=0$ or $\lambda=1$.

We can see that $h(\boldsymbol{V})=r$ and that $\boldsymbol{U}$ is regular. Thus $\boldsymbol{D}$ has rank $r$. Since $\boldsymbol{D}$ is diagonal and there are only 0 and 1 on the diagonal, without loss of generality we can assume that $\boldsymbol{D}=\operatorname{Diag}\{1, \ldots, 1,0, \ldots, 0\}$; number of 1 is $r$.

Define $\boldsymbol{Y}=\boldsymbol{U}^{\prime} \boldsymbol{X}$. We know that $\boldsymbol{Y} \sim \mathrm{N}\left(\mathbf{0}, \boldsymbol{U}^{\prime} \boldsymbol{V} \boldsymbol{U}\right)$. But $\boldsymbol{U}^{\prime} \boldsymbol{V} \boldsymbol{U}=\boldsymbol{U}^{\prime} \boldsymbol{U} \boldsymbol{D} \boldsymbol{U}^{\prime} \boldsymbol{U}=\boldsymbol{D}$. Matrix $\boldsymbol{D}$ is diagonal, and so all the components of the vector $\boldsymbol{Y}$ are uncorrelated. The vector $\boldsymbol{Y}$ has normal distribution and so its components are independent. Vector $\boldsymbol{Y}$ has vanishing expectation; $r$ of its components have unit variance, other components have vanishing variances. Thus $n-r$ components of the vector $\boldsymbol{Y}$ are zeros almost surely. The form of $\boldsymbol{D}$ ensures that these zeros are the last variables $Y_{r+1}, \ldots, Y_{n}$. Finally, we have

$$
\boldsymbol{X}^{\prime} \boldsymbol{X}=\boldsymbol{X}^{\prime} \boldsymbol{U} \boldsymbol{U}^{\prime} \boldsymbol{X}=\boldsymbol{Y}^{\prime} \boldsymbol{Y}=Y_{1}^{2}+\cdots+Y_{r}^{2} \sim \chi_{r}^{2}
$$

Theorem 3.9 Let $\boldsymbol{X} \sim \mathrm{N}(\mathbf{0}, \boldsymbol{I})$ and let $\boldsymbol{A}$ be a symmetric idempotent matrix of rank $r \geq 1$. Then $\boldsymbol{X}^{\prime} \boldsymbol{A} \boldsymbol{X} \sim \chi_{r}^{2}$.

Proof. We write $\boldsymbol{A}$ in the form $\boldsymbol{A}=\boldsymbol{U} \boldsymbol{D} \boldsymbol{U}^{\prime}$, where $\boldsymbol{U}$ fulfills the condition $\boldsymbol{U} \boldsymbol{U}^{\prime}=$ $\boldsymbol{U}^{\prime} \boldsymbol{U}=\boldsymbol{I}$ and $\boldsymbol{D}=\operatorname{Diag}\{1, \ldots, 1,0, \ldots, 0\}$ with $r$ ones on the diagonal. We define $\boldsymbol{Y}=\left(Y_{1}, \ldots, Y_{n}\right)^{\prime}=\boldsymbol{U}^{\prime} \boldsymbol{X}$, so that $\boldsymbol{Y} \sim \mathbf{N}(\mathbf{0}, \boldsymbol{I})$. Then we have

$$
\boldsymbol{X}^{\prime} \boldsymbol{A} \boldsymbol{X}=\boldsymbol{X}^{\prime} \boldsymbol{U} \boldsymbol{D} \boldsymbol{U}^{\prime} \boldsymbol{X}=\boldsymbol{Y}^{\prime} \boldsymbol{D} \boldsymbol{Y}=Y_{1}^{2}+\cdots+Y_{r}^{2}
$$

Since $Y_{1}, \ldots, Y_{r}$ are independent $\mathrm{N}(0,1)$ variables, the theorem is proved.

### 3.3.3 Quotient of random variables

Theorem 3.10 Let $X$ and $Z$ be independent random variables such that $X \sim N(0,1)$ and $Z \sim \chi_{k}^{2}$. Then the random variable

$$
T=\frac{X}{\sqrt{Z / k}}
$$

has Student t distribution with $k$ degrees of freedom, which is denoted $\mathrm{t}_{k}$ and has the density

$$
h_{k}(t)=\frac{\Gamma\left(\frac{k+1}{2}\right)}{\Gamma\left(\frac{k}{2}\right) \sqrt{\pi k}}\left(1+\frac{t^{2}}{k}\right)^{-(k+1) / 2} .
$$

Proof. Since $X$ a $Z$ are independent variables, their simultaneous density $g(x, z)$ is equal to product of their marginal densities

$$
g(x, z)=\frac{1}{\sqrt{2 \pi}} \mathrm{e}^{-x^{2} / 2} \frac{1}{2^{k / 2} \Gamma(k / 2)} z^{\frac{k}{2}-1} \mathrm{e}^{-z / 2} \quad \text { for } z>0
$$

We use the transform

$$
T=\frac{X}{\sqrt{Z / k}}, \quad U=Z
$$

The inverse transformation is $X=T \sqrt{U / k}, Z=U$, and absolute value of jacobian is $\sqrt{u / k}$. Then the simultaneous density of the variables $T$ and $U$ is

$$
p(t, u)=\frac{1}{\sqrt{2 \pi k} 2^{k / 2} \Gamma(k / 2)} u^{(k-1) / 2} \exp \left\{-\frac{u}{2}\left(1+\frac{t^{2}}{k}\right)\right\} .
$$

From here we obtain the marginal density $T$ using the formula $h_{k}(t)=\int p(t, u) \mathrm{d} u$.
In the case $k=1$ we obtain $h_{1}(t)=1 /\left[\pi\left(1+t^{2}\right)\right]$. It is the density of Cauchy distribution $\mathrm{C}(0,1)$. If we use Stirling formula for $\Gamma$ function, then we get $\lim _{k \rightarrow \infty} h_{k}(t)=$ $\varphi(t)$. Densities of the Student distribution converge to the density of $\mathrm{N}(0,1)$. If $k=1$, then $\mathrm{E} T$ does not exist, for $k>1$ we have $\mathrm{E} T=0$. Similarly, variance exists for $k>2$; then $\operatorname{var} T=k /(k-2)$.

Let $X$ and $Z$ be independent random variables such that $X \sim \mathrm{~N}(\delta, 1)$ and $Z \sim \chi_{k}^{2}$. Then the random variable $T=\frac{X}{\sqrt{Z / k}}$ has Student non-central t distribution with $k$ degrees of freedom with non-centrality parameter $\delta$. This distribution is denoted as $\mathrm{t}_{k, \delta}$.

Theorem 3.11 Let $X$ and $Y$ be independent random variables such that $X \sim \chi_{m}^{2}, Y \sim$ $\chi_{n}^{2}$. Then the random variable

$$
Z=\frac{X / m}{Y / n}
$$

has Fisher-Snedecor F distribution with $m$ and $n$ degrees of freedom, which is denoted as $\mathrm{F}_{m, n}$ and the density of which is

$$
f_{m, n}(z)=\frac{\Gamma\left(\frac{m+n}{2}\right)}{\Gamma\left(\frac{m}{2}\right) \Gamma\left(\frac{n}{2}\right)}\left(\frac{m}{n}\right)^{m / 2} z^{\frac{m}{2}-1}\left(1+\frac{m}{n} z\right)^{-(m+n) / 2} \quad \text { for } z>0
$$

Proof. The simultaneous density of the variables $X$ and $Y$ is

$$
p(x, y)=\frac{1}{2^{(m+n) / 2} \Gamma(m / 2) \Gamma(n / 2)} x^{\frac{m}{2}-1} y^{\frac{n}{2}-1} \mathrm{e}^{-(x+y) / 2}
$$

for $x>0, y>0$. We make the transform

$$
Z=\frac{X / m}{Y / n}, \quad U=Y
$$

The inverse transform is $X=m Z U / n, Y=U$ and absolute value of its jacobian is $m u / n$. Inserting for $x$ a $y$ into $p(x, y)$ and multiplying $m u / n$ we get simultaneous density $g(z, y)$ of the variables $Z$ and $Y$. Integrating with respect to $y$ we get marginal density of variable $Z$, which is introduced in theorem.

Moments of $\mathrm{F}_{m, n}$ distribution are

$$
\begin{aligned}
\mathrm{E} Z & =\frac{n}{n-2} & \text { for } n>2, \\
\operatorname{var} Z & =\frac{2 n^{2}(m+n-2)}{m(n-2)^{2}(n-4)} & \text { for } n>4
\end{aligned}
$$

For $n \leq 2$ the expectation is not finite and for $n \leq 4$ the second moment is not finite.

### 3.4 Transformation stabilizing variance

Assume that a random variable $X$ has a distribution which depends on a parameter $\theta$. The parameter is chosen in such a way that $\mathrm{E} X=\theta$. In many cases the variance of variable $X$ also depends on $\theta$ and we can write $\operatorname{var} X=\sigma^{2}(\theta)$. Usually, $\sigma(\theta)$ is a smooth function of $\theta$. We can ask the question if it is possible to find such a non-trivial function $g$ that the random variable $Y=g(X)$ has the variance independent of $\theta$. We excluded constant functions $g$ which would lead to variables with vanishing variance. Generally, this problem has no solution. However, some approximations are useful. Taylor formula gives

$$
g(X) \doteq g(\theta)+(X-\theta) g^{\prime}(\theta)
$$

so that

$$
\begin{equation*}
\mathrm{E} g(X) \doteq g(\theta), \quad \operatorname{var} g(X) \doteq\left[g^{\prime}(\theta)\right]^{2} \sigma^{2}(\theta) \tag{3.6}
\end{equation*}
$$

The expression $\left[g^{\prime}(\theta)\right]^{2} \sigma^{2}(\theta)$ will not depend on $\theta$, if we ensure

$$
g^{\prime}(\theta) \sigma(\theta)=c,
$$

where $c$ is a constant. From this condition we have the solution

$$
\begin{equation*}
g(\theta)=c \int \frac{\mathrm{~d} \theta}{\sigma(\theta)} \tag{3.7}
\end{equation*}
$$

The constant $c$ is chosen so that the function $g$ calculated from (3.7) has a nice form. We get $\operatorname{var} g(X) \doteq c^{2}$.

It was shown that the function $g$ calculated from (3.7) stabilizes variance and var $g(X)$ depends on $\theta$ only a little, but at the same time the distribution of the random variable $Y=g(X)$ is nearly normal.

We apply this method to some special cases.

Example 3.12 Let the random variable $X$ have Poisson distribution with parameter $\lambda>0$. It means that

$$
\mathrm{P}(X=k)=\frac{\lambda^{k}}{k!} \mathrm{e}^{-\lambda}, \quad k=0,1,2, \ldots
$$

We write shortly $X \sim \operatorname{Po}(\lambda)$. Since it holds

$$
\mathrm{E} X=\lambda, \quad \operatorname{var} X=\lambda
$$

instead of parameter $\theta$ we have the parameter $\lambda$ and $\sigma^{2}(\lambda)=\lambda$. From (3.7) we get

$$
g(\lambda)=c \int \frac{\mathrm{~d} \lambda}{\sqrt{\lambda}}=2 c \sqrt{\lambda}
$$

Usually, we choose $c=\frac{1}{2}$, and we deal with the function $g(\lambda)=\sqrt{\lambda}$. It is the well-known square-root transformation. In view of (3.6) we have

$$
\mathrm{E} \sqrt{X} \doteq \sqrt{\lambda}, \quad \operatorname{var} \sqrt{X} \doteq \frac{1}{4}
$$

Example 3.13 Let $\xi$ have the binomial distribution $\operatorname{Bi}(n, p)$, so that $\xi$ can be only $0,1, \ldots, n$ and the corresponding probabilities are

$$
\mathrm{P}(\xi=k)=\binom{n}{k} p^{k}(1-p)^{n-k}, \quad k=0,1, \ldots, n .
$$

It is assumed that $p \in(0,1)$ and that $n$ is a natural number. The variable $\xi$ can represent number of successes in $n$ independent experiments when in every experiment probability of success is $p$. A simple calculation gives

$$
\mathrm{E} \xi=n p, \quad \operatorname{var} \xi=n p(1-p)
$$

The parameter $p$ is estimated using the variable $X=\xi / n$. Thus we have

$$
\mathrm{E} X=p, \quad \operatorname{var} X=\frac{p(1-p)}{n}
$$

Instead of $\theta$ we have in our case $p$ a $\sigma^{2}(p)=p(1-p) / n$. According (3.7) we get

$$
g(p)=c \sqrt{n} \int \frac{\mathrm{~d} p}{\sqrt{p(1-p)}}=2 c \sqrt{n} \arcsin \sqrt{p}
$$

Usually, one chooses $c=1 /(2 \sqrt{n})$, so that finally

$$
g(p)=\arcsin \sqrt{p} .
$$

From (3.6) we calculate

$$
\mathrm{E} \arcsin \sqrt{X} \doteq \arcsin \sqrt{p}, \quad \text { var } \arcsin \sqrt{X} \doteq \frac{1}{4 n}
$$

Example 3.14 Sample correlation coefficient $r$ calculated from a sample of size $n$ from two-dimensional normal distribution having theoretical correlation coefficient $\rho \in(-1,1)$, fulfills

$$
\mathrm{E} r \doteq \rho, \quad \operatorname{var} r \doteq \frac{\left(1-\rho^{2}\right)^{2}}{n}
$$

Since $\sigma(\rho) \doteq n^{-1 / 2}\left(1-\rho^{2}\right)$, we have

$$
g(\rho) \doteq c \sqrt{n} \int \frac{\mathrm{~d} \rho}{1-\rho^{2}}=\frac{1}{2} c \sqrt{n} \ln \frac{1+\rho}{1-\rho} .
$$

If $c=1 / \sqrt{n}$ then

$$
g(\rho)=\frac{1}{2} \ln \frac{1+\rho}{1-\rho},
$$

or $g(\rho)=\operatorname{arctgh} \rho$. If we define

$$
Z=\frac{1}{2} \ln \frac{1+r}{1-r},
$$

then we get Fisher $z$-transformation. Using (3.6) we have

$$
\mathrm{E} Z \doteq \frac{1}{2} \ln \frac{1+\rho}{1-\rho}, \quad \operatorname{var} Z \doteq \frac{1}{n}
$$

More detailed calculation gives

$$
\mathrm{E} Z \doteq \frac{1}{2} \ln \frac{1+\rho}{1-\rho}+\frac{\rho}{2(n-1)}, \quad \text { var } Z \doteq \frac{1}{n-3}
$$

In practical computations the approximations

$$
\mathrm{E} Z \doteq \frac{1}{2} \ln \frac{1+\rho}{1-\rho}, \quad \operatorname{var} Z \doteq \frac{1}{n-3}
$$

are used. See Winterbottom (1979).
Example 3.15 Let $X \sim \chi_{n}^{2}$. If we write $\theta$ instead of $n$ then $\mathrm{E} X=\theta$, var $X=2 \theta$ and

$$
g(\theta)=c \int \frac{\mathrm{~d} \theta}{\sqrt{2 \theta}}=c \sqrt{2 \theta}
$$

Usually, $c=1$ is chosen. Then $g(\theta)=\sqrt{2 \theta}, Y=\sqrt{2 X}$ and $\mathrm{E} Y \doteq \sqrt{2 n}$, var $Y \doteq 1$.
R. A. Fisher recommended to use transformation $Y=\sqrt{2 X}-\sqrt{2 n-1}$, because its distribution tends to the normal distribution $\mathrm{N}(0,1)$ rather quickly. Today, WilsonHilferty transformation is used, i.e.

$$
U=3 \sqrt{\frac{n}{2}}\left(\sqrt[3]{\frac{X}{n}}+\frac{2}{9 n}-1\right)
$$

and its distribution converges to $\mathbf{N}(0,1)$ even quicker. (See Kendall, Stuart 1969 I, Rao 1978, Wilson, Hilferty 1931.)

Normalization transformations for other types of distributions are given in Konishi (1981).

## Chapter 4

## Random sample

### 4.1 Simple random sample

A series of independent identically distributed random variables $X_{1}, \ldots, X_{n}$ is called $a$ simple random sample. Number $n$ is size of the sample. Introduce variables

$$
\bar{X}=\frac{1}{n} \sum_{i=1}^{n} X_{i}, \quad S^{2}=\frac{1}{n-1} \sum_{i=1}^{n}\left(X_{i}-\bar{X}\right)^{2} .
$$

The variable $\bar{X}$ is sample mean. Variable $S^{2}$ is defined only for $n \geq 2$.
Theorem 4.1 Let $X_{1}, \ldots, X_{n}$ be the random sample from the distribution with expectation $\mu$ and a finite variance $\sigma^{2}$. Then it holds

$$
\mathrm{E} \bar{X}=\mu, \quad \operatorname{var} \bar{X}=\frac{\sigma^{2}}{n}, \quad \mathrm{E} S^{2}=\sigma^{2}
$$

Proof. First, we calculate

$$
\mathrm{E} \bar{X}=\frac{1}{n} \sum_{i=1}^{n} \mathrm{E} X_{i}=\frac{1}{n} n \mu=\mu
$$

Using theorems 2.4 and 2.8 we get

$$
\operatorname{var}\left(X_{1}+\cdots+X_{n}\right)=\operatorname{var} X_{1}+\cdots+\operatorname{var} X_{n}=n \sigma^{2} .
$$

Thus var $\bar{X}=n^{-2} n \sigma^{2}=\sigma^{2} / n$. Further

$$
\sum_{i=1}^{n}\left(X_{i}-\bar{X}\right)^{2}=\sum_{i=1}^{n}\left[\left(X_{i}-\mu\right)-(\bar{X}-\mu)\right]^{2}=\sum_{i=1}^{n}\left(X_{i}-\mu\right)^{2}-n(\bar{X}-\mu)^{2}
$$

so that

$$
\mathrm{E} \sum_{i=1}^{n}\left(X_{i}-\bar{X}\right)^{2}=\sum_{i=1}^{n} \mathrm{E}\left(X_{i}-\mu\right)^{2}-n \mathrm{E}(\bar{X}-\mu)^{2}=n \sigma^{2}-\sigma^{2}=(n-1) \sigma^{2}
$$

This gives the last assertion.

Because $\mathrm{E} \bar{X}=\mu$ we say that $\bar{X}$ is unbiased estimator of the parameter $\mu$. Similarly, $S^{2}$ is an unbiased estimator of the parameter $\sigma^{2}$, since $\mathrm{E} S^{2}=\sigma^{2}$. In the general case we have the following definition. Let $\left(X_{1}, \ldots, X_{n}\right)^{\prime}$ be a random vector, the distribution of which depends on a parameter $\theta$. Let $g\left(x_{1}, \ldots, x_{n}\right)$ be a borel measurable function which does not depend on $\theta$. We say that $T=g\left(X_{1}, \ldots, X_{n}\right)$ is an estimator of the parameter $\theta$. If $\mathrm{E} T=\theta$ holds for every $\theta$ then the estimator $T$ is unbiased.

In the multidimensional case the simple random sample is a series $\boldsymbol{X}_{1}, \ldots, \boldsymbol{X}_{n}$ of independent identically distributed random vectors. This sample is characterized by means of

$$
\overline{\boldsymbol{X}}=\frac{1}{n} \sum_{i=1}^{n} \boldsymbol{X}_{i}, \quad \boldsymbol{S}=\frac{1}{n-1} \sum_{i=1}^{n}\left(\boldsymbol{X}_{i}-\overline{\boldsymbol{X}}\right)\left(\boldsymbol{X}_{i}-\overline{\boldsymbol{X}}\right)^{\prime} .
$$

Theorem 4.2 Let $\boldsymbol{X}_{1}, \ldots, \boldsymbol{X}_{n}$ be a sample from distribution with expectation $\boldsymbol{\mu}$ and $a$ variance matrix $\boldsymbol{V}$. Then we have

$$
\mathrm{E} \overline{\boldsymbol{X}}=\boldsymbol{\mu}, \quad \operatorname{var} \overline{\boldsymbol{X}}=\frac{1}{n} \boldsymbol{V}, \quad \mathrm{E} \boldsymbol{S}=\boldsymbol{V}
$$

Proof is similar as in Theorem 4.1.

### 4.2 Ordered random sample

Let $X_{1}, \ldots, X_{n}$ be a random sample from a distribution having the distribution function $F$. Random variables $X_{1}, \ldots, X_{n}$ will be ordered and the smallest will be denoted $X_{(1)}$, the second smallest $X_{(2)}$, and finally the largest $X_{(n)}$. We have

$$
X_{(1)} \leq X_{(2)} \leq \cdots \leq X_{(n)}
$$

The variables $X_{(1)}, \ldots, X_{(n)}$ are called ordered random sample.
Theorem 4.3 Let $r \in\{1,2, \ldots, n\}$. Then the distribution function $G_{r}$ of the random variable $X_{(r)}$ is

$$
\begin{equation*}
G_{r}(x)=\sum_{i=r}^{n}\binom{n}{i} F^{i}(x)[1-F(x)]^{n-i} . \tag{4.1}
\end{equation*}
$$

Proof. Probability that there will be $i$ variables among $X_{1}, \ldots, X_{n}$ such that their values are smaller or equal $x$, is

$$
\binom{n}{i} F^{i}(x)[1-F(x)]^{n-i},
$$

because the number of such variables has the binomial distribution. The variable $X_{(r)}$ will be smaller than $x$ if among $X_{1}, \ldots, X_{n}$ either $r$, or $r+1$, etc. or $n$ variables smaller than $x$ will be found. These cases are disjoint and so the resulting probability is equal to sum of their probabilities.

Formulas for distribution functions of the smallest and the largest member of ordered random sample follow from formula (4.1) as special cases. The results are

$$
G_{1}(x)=1-[1-F(x)]^{n}, \quad G_{n}(x)=F^{n}(x)
$$

Both the formulas can be also derived directly without using theorem 4.3.
If $n$ is large, formula (4.1) contains many members. Calculations containing $G_{r}(x)$ may be rather complex. If the distribution function $F$ has a density $f$, then also the density $g_{r}$ exists and its formula is quite simple.

Theorem 4.4 Let $F$ be distribution function of a continuous distribution with the density $f$. Then the density $g_{r}$ of the variable $X_{(r)}$ also exists and for $n \geq 2$ we have

$$
\begin{equation*}
g_{r}(x)=n\binom{n-1}{r-1} f(x) F^{r-1}(x)[1-F(x)]^{n-r} . \tag{4.2}
\end{equation*}
$$

Proof. We start with formula $g_{r}(x)=G_{r}^{\prime}(x)$ and insert (4.1). Then all members disappear except for one which is equal to (4.2).

Especially,

$$
g_{1}(x)=n f(x)[1-F(x)]^{n-1}, \quad g_{n}(x)=n f(x) F^{n-1}(x)
$$

It is possible to derive simultaneous distribution function and simultaneous density of several members of ordered random sample. Here we restrict to two members.

Theorem 4.5 Let $F$ be the distribution function of the continuous distribution with the density $f$. If $n \geq 2$ and if $1 \leq r<s \leq n$, then the simultaneous density $g_{r, s}$ of the variables $X_{(r)}, X_{(s)}$ exists and equals to

$$
\begin{aligned}
g_{r, s}(x, y)= & \frac{n!}{(r-1)!(s-r-1)!(n-s)!} \\
& \times f(x) f(y) F^{r-1}(x)[F(y)-F(x)]^{s-r-1}[1-F(y)]^{n-s},
\end{aligned}
$$

if $x<y$. In the case $x \geq y$ we have $g_{r, s}(x, y)=0$.
Proof. The proof is similar to that of theorem 4.4.
Theorem is often used for $r=1, s=n$. Then the simultaneous density of variables $X=X_{(1)}$ and $Y=X_{(n)}$ is

$$
g_{1 n}(x, y)=n(n-1) f(x) f(y)[F(y)-F(x)]^{n-2} .
$$

An important characteristic is the range $R=Y-X$. We derive a formula for the density $h$ and for the distribution function $H$ of the variable $R$. We start with the density $g_{1 n}(x, y)$. Consider the transform $R=Y-X, T=X$. The inverse transform is $X=T, Y=R+T$ and the corresponding jacobian is

$$
\left|\begin{array}{ll}
\frac{\partial x}{\partial r} & \frac{\partial x}{\partial t} \\
\frac{\partial y}{\partial r} & \frac{\partial y}{\partial t}
\end{array}\right|=\left|\begin{array}{ll}
0 & 1 \\
1 & 1
\end{array}\right|=-1
$$

Thus the simultaneous density of the variables $R$ and $T$ is

$$
s(r, t)=n(n-1) f(t) f(r+t)[F(r+t)-F(t)]^{n-2}
$$

marginal density of $R$ is

$$
h(r)=\int_{-\infty}^{\infty} n(n-1) f(t) f(r+t)[F(r+t)-F(t)]^{n-2} \mathrm{~d} t, \quad r>0,
$$

and the distribution function of the variable $R$ is

$$
H(y)=\int_{0}^{y} h(r) \mathrm{d} r=n \int_{-\infty}^{\infty} f(t)\left\{\int_{0}^{y}(n-1) f(r+t)[F(r+t)-F(t)]^{n-2} \mathrm{~d} r\right\} \mathrm{d} t
$$

for $y>0$. Because

$$
\frac{\partial}{\partial r}[F(r+t)-F(t)]^{n-1}=(n-1) f(r+t)[F(r+t)-F(t)]^{n-2}
$$

we obtain

$$
H(y)=n \int_{-\infty}^{\infty} f(t)\left\{[F(r+t)-F(t)]^{n-1}\right\}_{0}^{y} \mathrm{~d} t=n \int_{-\infty}^{\infty} f(t)[F(y+t)-F(t)]^{n-1} \mathrm{~d} t
$$

It can be derived that the simultaneous distribution function $G_{1, n}$ of the variables $X_{(1)}$ and $X_{(n)}$ is

$$
G_{1, n}(x, y)=F^{n}(y)-[F(y)-F(x)]^{n} \quad \text { for } x<y
$$

In connection with random sample we introduce rank of the random variable. If the random variable $X_{i}$ is in the random sample $j$ th (i.e., if $X_{i}=X_{(j)}$ ), then the rank $R_{i}$ of this variable equals to $j$. Value $R_{i}$ equals the number of variables in the random sample which are smaller or equal $X_{i}$. This procedure is applied when the distribution is continuous where all values $X_{1}(\omega), \ldots, X_{n}(\omega)$ are different with probability one (no ties). If several values are identical then every variable from this group usually obtains arithmetical mean from the corresponding ranks.

### 4.3 Random sample from the normal distribution

Consider problems investigated in section 4.1. If we specify distribution which generates the sample, we can specify some assertions and some other derive.

Theorem 4.6 Let $X_{1}, \ldots, X_{n}$ be the sample from the distribution $\mathrm{N}\left(\mu, \sigma^{2}\right)$, where $\sigma^{2}>0$. Then the following asertions hold:
(a) $\bar{X} \sim \mathrm{~N}\left(\mu, \frac{\sigma^{2}}{n}\right)$.
(b) If $n \geq 2$, then $(n-1) S^{2} / \sigma^{2} \sim \chi_{n-1}^{2}$.
(c) If $n \geq 2$, then $\bar{X}$ and $S^{2}$ are independent.

Proof. (a) We know that $X_{1}+\cdots+X_{n} \sim \mathrm{~N}\left(n \mu, n \sigma^{2}\right)$. Then $\bar{X}=n^{-1}\left(X_{1}+\cdots+X_{n}\right) \sim$ $\mathrm{N}\left(\mu, \sigma^{2} / n\right)$.
(b) Since

$$
S^{2}=\frac{1}{n-1} \sum\left(X_{i}-\bar{X}\right)^{2}=\frac{1}{n-1} \sum\left[\left(X_{i}-\mu\right)-(\bar{X}-\mu)\right]^{2},
$$

we can consider variables $X_{i}-\mu$ instead of original $X_{i}$. The equality ensures that $S^{2}$ is not changed when $X_{i}$ is substituted by $X_{i}-\mu$. Vector $\boldsymbol{b}_{1}=\left(n^{-1 / 2}, \ldots, n^{-1 / 2}\right)^{\prime}$ has the unit length. Thus there exist vectors $\boldsymbol{b}_{2}, \ldots, \boldsymbol{b}_{n}$ such that the matrix $\boldsymbol{B}^{\prime}=\left(\boldsymbol{b}_{1}, \ldots, \boldsymbol{b}_{n}\right)$ is orthonormal. Make the transform $\boldsymbol{Y}=\boldsymbol{B} \boldsymbol{X}$. Obviously, the first component of the vector $\boldsymbol{Y}$ is $Y_{1}=\sqrt{n} \bar{X}$. Since $\boldsymbol{B}$ is orthonormal, we see that $\boldsymbol{B}^{\prime} \boldsymbol{B}=\boldsymbol{I}$. We have $\boldsymbol{X}=\boldsymbol{B}^{\prime} \boldsymbol{Y}$ and

$$
\begin{aligned}
(n-1) S^{2} & =\sum X_{i}^{2}-n \bar{X}^{2}=\boldsymbol{X}^{\prime} \boldsymbol{X}-n \bar{X}^{2}=\boldsymbol{Y}^{\prime} \boldsymbol{B} \boldsymbol{B}^{\prime} \boldsymbol{Y}-n \bar{X}^{2} \\
& =\boldsymbol{Y}^{\prime} \boldsymbol{Y}-n \bar{X}^{2}=Y_{1}^{2}+Y_{2}^{2}+\cdots+Y_{n}^{2}-Y_{1}^{2}=Y_{2}^{2}+\cdots+Y_{n}^{2}
\end{aligned}
$$

The simultaneous density of variables $X_{1}, \ldots, X_{n}$ is equal to the product of their densities. We compare this product with the formula (3.2). Under our simplifying assumption $\mathrm{E} X_{i}=0$ we can see that the random vector $\boldsymbol{X}=\left(X_{1}, \ldots, X_{n}\right)^{\prime}$ has distribution $\mathrm{N}\left(\mathbf{0}, \sigma^{2} \boldsymbol{I}\right)$. Then $\boldsymbol{Y}$ has distribution $\mathrm{N}\left(\mathbf{0}, \boldsymbol{B} \sigma^{2} \boldsymbol{I} \boldsymbol{B}^{\prime}\right)$, which is distribution $\mathrm{N}\left(\mathbf{0}, \sigma^{2} \boldsymbol{I}\right)$. Variables $Y_{1}, \ldots, Y_{n}$ are independent and each of them has distribution $\mathrm{N}\left(0, \sigma^{2}\right)$. Thus $Y_{i} / \sigma \sim \mathrm{N}(0,1)$ and we have

$$
(n-1) S^{2} / \sigma^{2}=\left(Y_{2} / \sigma\right)^{2}+\cdots+\left(Y_{n} / \sigma\right)^{2} \sim \chi_{n-1}^{2} .
$$

(c) It follows from (b) that the variables $Y_{1}, \ldots, Y_{n}$ are independent. Thus the variables $Y_{1}=\sqrt{n} \bar{X}$ and $Y_{2}^{2}+\cdots+Y_{n}^{2}=(n-1) S^{2}$ are independent. If we add to all variables $X_{i}$ the original expectation $\mu$, then $\bar{X}$ changes $\mu$ and $S^{2}$ remains the same. Their independence remains.

## Chapter 5

## Estimating theory

### 5.1 Statistics and unbiased estimators

Let the random vector $\boldsymbol{X}=\left(X_{1}, \ldots, X_{n}\right)^{\prime}$ have the density $f(\boldsymbol{x}, \boldsymbol{\theta})$ with respect to a $\sigma$-finite measure $\mu$, and $\boldsymbol{\theta}=\left(\theta_{1}, \ldots, \theta_{m}\right)^{\prime}$ is an unknown parameter. Using vector $\boldsymbol{X}$ the best estimator of the parameter $\boldsymbol{\theta}$ should be found. It is only known that $\boldsymbol{\theta}$ is an element of a parametric space $\Omega \subset \mathbb{R}_{m}$. If the problem is to find point estimator, it means to find a measurable mapping $g:\left(\mathbb{R}_{n}, \mathcal{B}_{n}\right) \rightarrow\left(\mathbb{R}_{m}, \mathcal{B}_{m}\right)$ such that the random vector $\boldsymbol{T}=g(\boldsymbol{X})$ is the best approximation of the value $\boldsymbol{\theta}$. In the case of interval estimator we wish to find interval or another appropriate set which covers $\boldsymbol{\theta}$ with sufficiently large probability. In this chapter we deal with point estimators.

Usually, we create a new random vector $\boldsymbol{S}=\left[S_{1}(\boldsymbol{X}), \ldots, S_{k}(\boldsymbol{X})\right]^{\prime}$. This new vector $\boldsymbol{S}$ is called statistics. We emphasize that statistics is not a function of the parameter $\boldsymbol{\theta}$. We choose functions $S_{i}(\boldsymbol{x})$ such that the vector $\boldsymbol{S}$ has lower dimension than $\boldsymbol{X}$ and no information about $\boldsymbol{\theta}$ is lost. If we intend to take statistics $\boldsymbol{S}$ as estimator of $\boldsymbol{\theta}$, we must have $k=m$.

We say that the estimator $\boldsymbol{T}$ of the parameter $\boldsymbol{\theta}$ is unbiased if $\boldsymbol{E} \boldsymbol{T}=\boldsymbol{\theta}$ holds for every $\boldsymbol{\theta} \in \Omega$. If we have $\mathrm{ET}=\boldsymbol{\theta}+\boldsymbol{b}(\boldsymbol{\theta})$, where the function $\boldsymbol{b}$ is not identically vanishing on the set $\Omega$ the estimator $\boldsymbol{T}$ is called biased. Vector $\boldsymbol{b}(\boldsymbol{\theta})$ is called bias of $\boldsymbol{T}$ at $\boldsymbol{\theta}$.

Instead of $\boldsymbol{E} \boldsymbol{T}$ we should write $\mathrm{E}_{\boldsymbol{\theta}} \boldsymbol{T}$ to indicate that the expectation is calculated when the parameter has value $\boldsymbol{\theta}$. However, we shall mostly use ET

A requirement on estimator is its unbiasedness. However, it can happen that there exists another estimator which is biased but better from another point of view.

### 5.2 Examples

Example 5.1 Let $X_{1}, \ldots, X_{n}$ be a sample from $\mathbf{N}\left(\mu, \sigma^{2}\right)$, where $n \geq 2$ and $\sigma>0$. Assume that none of parameters $\mu$ a $\sigma^{2}$ is known and we should estimate $\sigma^{2}$. Denote

$$
Y=\sum_{i=1}^{n}\left(X_{i}-\bar{X}\right)^{2}
$$

The variable $S^{2}=\frac{1}{n-1} Y$ has been used as estimator of $\sigma^{2}$ and we justified it by the property that $S^{2}$ is unbiased estimator for $\sigma^{2}$ (theorem 4.1). Another estimator for $\sigma^{2}$
could be the sample variance $M_{2}$ defined as

$$
M_{2}=\frac{1}{n} Y .
$$

We show that

$$
\mathrm{E}\left(M_{2}-\sigma^{2}\right)^{2}<\mathrm{E}\left(S^{2}-\sigma^{2}\right)^{2},
$$

i.e., that $M_{2}$ has smaller mean square error than $S^{2}$. Theorem 4.6 b ) on p. 48 gives that $Y / \sigma^{2} \sim \chi_{n-1}^{2}$. It implies

$$
\mathrm{E} Y=\sigma^{2}(n-1), \quad \operatorname{var} Y=2 \sigma^{4}(n-1), \quad \mathrm{E} Y^{2}=\operatorname{var} Y+(\mathrm{E} Y)^{2}=\sigma^{4}\left(n^{2}-1\right)
$$

Inserting for $M_{2}$ and $S^{2}$ we get

$$
\begin{aligned}
\mathrm{E}\left(M_{2}-\sigma^{2}\right)^{2} & =\mathrm{E} M_{2}^{2}-2 \sigma^{2} \mathrm{E} M_{2}+\sigma^{4}=\frac{1}{n^{2}} \mathrm{E} Y^{2}-\frac{2 \sigma^{2}}{n} \mathrm{E} Y+\sigma^{4} \\
& =\frac{2 n-1}{n^{2}} \sigma^{4}, \\
\mathrm{E}\left(S^{2}-\sigma^{2}\right)^{2} & =\operatorname{var} S^{2}=\frac{1}{(n-1)^{2}} \operatorname{var} Y=\frac{2}{n-1} \sigma^{4} .
\end{aligned}
$$

Since for every positive integer $n$ we have

$$
\frac{2 n-1}{n^{2}}<\frac{2}{n-1}
$$

the mean square error of the variable $M_{2}$ is smaller than that of $S^{2}$.
It is interesting that the coefficient $\frac{1}{n}$ by $Y$ is not optimal in sense of mean square error. Look for a number $k$ such that the expression $\mathrm{E}\left(k Y-\sigma^{2}\right)^{2}$ is minimal. Since

$$
\begin{aligned}
\mathrm{E}\left(k Y-\sigma^{2}\right)^{2} & =k^{2} \mathrm{E} Y^{2}-2 k \sigma^{2} \mathrm{E} Y+\sigma^{4}=\sigma^{4}\left[k^{2}\left(n^{2}-1\right)-2 k(n-1)+1\right] \\
& =\sigma^{4}\left[\left(n^{2}-1\right)\left(k-\frac{1}{n+1}\right)^{2}+\frac{2}{n+1}\right],
\end{aligned}
$$

it is clear that $k=\frac{1}{n+1}$ gives the minimum and the minimum is $\frac{2}{n+1} \sigma^{4}$.
This example is special case of more general situation (see Williams 2001, p. 191). Let $T$ be such an unbiased estimator of the parameter $\theta$ that $0 \neq \mathrm{E} T^{2}<\infty$ for every $\theta \in \Omega$. Then $\mathrm{E}(a T-\theta)^{2}$ is minimal in the case

$$
a=\frac{\theta^{2}}{\mathrm{E} T^{2}} .
$$

In our case we had $\theta=\sigma^{2}, T=S^{2}$. It happens that $a$ does not depend on $\theta$. This was also in our special case.

Example 5.2 Let random variable $X$ have geometric distribution $\operatorname{Ge}(p)$, where $p \in(0,1)$ is an unknown parameter. Define $q=1-p$. Random variable $X$ is number of failures in sample from Bernoulli distribution before the first success. We have $\mathrm{P}(X=k)=q^{k} p$,
$k=0,1, \ldots$ Let us look for an unbiased estimator for $p$. If $T(X)$ is such estimator, it must satisfy

$$
\mathrm{E} T(X)=\sum_{k=0}^{\infty} T(k) q^{k} p=p, \quad p \in(0,1)
$$

From here we get

$$
\sum_{k=0}^{\infty} T(k) q^{k}=1, \quad q \in(0,1)
$$

and the estimator satisfies $T(0)=1$ and $T(k)=0$ for $k \geq 1$. This is a poor estimator because the number of failures before the first success is taken only as information if the success was already in the first experiment or not.

Example 5.3 Let a random variable $X$ have Poisson distribution $\operatorname{Po}(\lambda)$. Let $\lambda>0$ be an unknown parameter. We look for an unbiased estimator for $\mathrm{e}^{-2 \lambda}$. If $T(X)$ is such an estimator, we must have $\mathrm{E} T(X)=\mathrm{e}^{-2 \lambda}$. It means that

$$
\sum_{x=0}^{\infty} T(x) \frac{\mathrm{e}^{-\lambda} \lambda^{x}}{x!}=\mathrm{e}^{-2 \lambda}
$$

and so

$$
\sum_{x=0}^{\infty} T(x) \frac{\lambda^{x}}{x!}=\mathrm{e}^{-\lambda}
$$

Finally, we obtain

$$
\sum_{x=0}^{\infty} T(x) \frac{\lambda^{x}}{x!}=\sum_{x=0}^{\infty}(-1)^{x} \frac{\lambda^{x}}{x!} .
$$

This equality must hold for all $\lambda>0$ and so coefficients by $\lambda^{x}$ must be the same. It gives $T(x)=(-1)^{x}$. This estimator is not good. It can be negative although it is estimator of a non-negative function. Further, small change of variable $X$ causes large change of estimator.

There are also other modifications of this example. Williams (2001) on p. 188 introduces that Lehmann is the author of the following result. Let

$$
\mathrm{P}(X=k)=\frac{\lambda^{k}}{k!} \frac{1}{\mathrm{e}^{\lambda}-1}, \quad k=1,2,3, \ldots
$$

(it is truncated Poisson distribution). We look for an unbiased estimator $T$ of the parametric function $1-\mathrm{e}^{-\lambda}$ based on $X$. Since $T$ must be an unbiased estimator, we must have

$$
\frac{1}{\mathrm{e}^{\lambda}-1} \sum_{k=1}^{\infty} T(k) \frac{\lambda^{k}}{k!}=1-\mathrm{e}^{-\lambda}
$$

i.e.

$$
\sum_{k=1}^{\infty} T(k) \frac{\lambda^{k}}{k!}=2 \sum_{n=1}^{\infty} \frac{\lambda^{2 n}}{(2 n)!}
$$

It implies that

$$
T= \begin{cases}0, & \text { when } X \text { is an odd number, } \\ 2, & \text { when } X \text { is an even number. }\end{cases}
$$

Since $1-\mathrm{e}^{-\lambda} \in(0,1)$, the estimator $T$ is not acceptable.

Example 5.4 Let $X \sim \operatorname{Bi}(n, p)$, i.e.,

$$
\mathrm{P}(X=x)=\binom{n}{x} p^{x}(1-p)^{n-x}, \quad n \geq 1, \quad 0<p<1, \quad x=0,1, \ldots, n .
$$

We show that there exists no unbiased estimator for the parametric function $\frac{1}{p}$. Assume that there exists a function $T$, that $\mathrm{E} T(X)=\frac{1}{p}$ for every $p \in(0,1)$. Then

$$
\sum_{x=0}^{n} T(x)\binom{n}{x} p^{x}(1-p)^{n-x}=\frac{1}{p}, \quad 0<p<1
$$

The left hand side is a polynomial in $p$ having degree maximally $n$, and it cannot be the same as the function $\frac{1}{p}$ on the interval $(0,1)$.
Remark 5.5 Let $X_{1}, X_{2}, \ldots$ be independent random variables with Bernoulli distribution with probability of success $p \in(0,1)$. Then $X=X_{1}+\cdots+X_{n} \sim \operatorname{Bi}(n, p)$. Example 5.4 does not imply, that for the parametric function $\frac{1}{p}$ is not possible to find an unbiased estimator.

Let $\xi$ be the number of failures in the sample from the Bernoulli distribution before the first success. Then $\xi$ has geometric distribution $\operatorname{Ge}(p)$, i.e., $\mathrm{P}(\xi=k)=p(1-p)^{k}$, $k=0,1,2, \ldots$ It is well known that $\mathrm{E} \xi=\frac{1-p}{p}=\frac{1}{p}-1$. Thus $\xi+1$ is an unbiased estimator for $\frac{1}{p}$.

Let us remark that in examples 5.2 - 5.4 the sample sizes were only 1 . In the remark 5.5 the sample had not a fixed size.

### 5.3 Consistent estimators

### 5.3.1 Definition

Let $\theta$ be an univariate parameter. Assume that $X_{1}, X_{2}, \ldots$ is a sample from a distribution which depends on $\theta$. Let us have an estimator $T_{n}=g_{n}\left(X_{1}, \ldots, X_{n}\right)$ defined for all nonnegative integers. We say that the estimator $T_{n}$ is consistent, if $T_{n} \rightarrow \theta$ in probability for $n \rightarrow \infty$.

Theorem 5.6 Let $\mathrm{E} T_{n}^{2}<\infty$ for every nonnegative integer $n$. If $\mathrm{E} T_{n} \rightarrow \theta$ and $\operatorname{var} T_{n} \rightarrow 0$, then $T_{n}$ is a consistent estimator of the parameter $\theta$.

Proof. For every $\varepsilon>0$ we have

$$
\begin{aligned}
\mathrm{P}\left(\left|T_{n}-\theta\right|>\varepsilon\right)= & \int_{\left|T_{n}-\theta\right|>\varepsilon} \mathrm{dP} \leq \int_{\left|T_{n}-\theta\right|>\varepsilon} \varepsilon^{-2}\left(T_{n}-\theta\right)^{2} \mathrm{dP} \\
\leq & \varepsilon^{-2} \int\left[\left(T_{n}-\mathrm{E} T_{n}\right)+\left(\mathrm{E} T_{n}-\theta\right)\right]^{2} \mathrm{dP} \\
= & \varepsilon^{-2}\left[\int\left(T_{n}-\mathrm{E} T_{n}\right)^{2} \mathrm{dP}\right. \\
& \left.\quad+2\left(\mathrm{E} T_{n}-\theta\right) \int\left(T_{n}-\mathrm{E} T_{n}\right) \mathrm{dP}+\left(\mathrm{E} T_{n}-\theta\right)^{2}\right] \\
= & \varepsilon^{-2}\left[\operatorname{var} T_{n}+\left(\mathrm{E} T_{n}-\theta\right)^{2}\right] \rightarrow 0 .
\end{aligned}
$$

### 5.3.2 Example

Example 5.7 Let $X_{1}, \ldots, X_{n}$ be a sample from the rectangular distribution $\mathrm{R}(0, \theta)$, where $\theta>0$ is an unknown parameter. Let $X_{(n)}=\max \left(X_{1}, \ldots, X_{n}\right)$. We show that $X_{(n)}$ is a biased consistent estimator of the parameter $\theta$. Since

$$
\mathrm{P}\left(X_{(n)}<x\right)=\frac{x^{n}}{\theta^{n}}, \quad 0<x<\theta
$$

the density of the variable $X_{(n)}$ is

$$
p(x)=\frac{n x^{n-1}}{\theta^{n}}, \quad 0<x<\theta .
$$

This implies

$$
\mathrm{E} X_{(n)}=\frac{n}{\theta^{n}} \int_{0}^{\theta} x^{n} \mathrm{~d} x=\frac{n \theta}{n+1}, \quad \mathrm{E} X_{(n)}^{2}=\frac{n}{\theta^{n}} \int_{0}^{\theta} x^{n+1} \mathrm{~d} x=\frac{n \theta^{2}}{n+2}
$$

and thus

$$
\operatorname{var} X_{(n)}=\mathrm{E} X_{(n)}^{2}-\left[\mathrm{E} X_{(n)}\right]^{2}=\frac{n \theta^{2}}{(n+1)^{2}(n+2)}
$$

Using theorem 5.6 we have that $X_{(n)}$ is a consistent estimator for $\theta$. However, in this case it is not difficult to modify $X_{(n)}$ to obtain from $X_{(n)}$ an unbiased consistent estimator. If we define $T=\frac{n+1}{n} X_{(n)}$, then

$$
\mathrm{E} T=\theta, \quad \operatorname{var} T=\frac{\theta^{2}}{n(n+2)}
$$

## Chapter 6

## Empirical estimators

### 6.1 Empirical distribution function

We have the numbers $x_{1}, \ldots, x_{n}$. We order them in such a way that $x_{(1)} \leq \cdots \leq x_{(n)}$. Empirical distribution function (ecdf - empirical cumulative distribution function) is defined by the formula

$$
F_{n}(x)=\frac{1}{n} \sum_{i=1}^{n} \chi_{(-\infty, x]}\left(x_{i}\right),
$$

where

$$
\chi_{A}(x)= \begin{cases}1 & \text { for } x \in A, \\ 0 & \text { for } x \notin A\end{cases}
$$

is characteristic function of the set $A$. It means that $F_{n}(x)=0$ for $x<x_{(1)}$. If all the values $x_{1}, \ldots, x_{n}$ are different, then at each of them the function $F_{n}(x)$ has a jump $1 / n$. If the value $x_{i}$ is in collection $x_{1}, \ldots, x_{n}$ together $k$-times, then $F_{n}(x)$ has at point $x_{i}$ jump $k / n$. For all values $x \geq x_{(n)}$ we have $F_{n}(x)=1$.

### 6.2 Sample quantiles

Consider numbers $x_{1}, \ldots, x_{n}$. The sample quantiles (sometimes called empirical quantiles) could be defined as values of quantile function belonging to the empirical distribution function $F_{n}(x)$. This definition is introduced in the book Venables, Ripley (2002) on p. 108. People who use program $R$ have a little different definition. We explain it using publication Verzani (2002).

Sample median is the point in the data that splits it into half. For example, data

$$
\begin{array}{lllll}
10, & 17, & 18, & 25, & 28
\end{array}
$$

have sample median 18 , since two values are larger and two are less. In case of data

$$
\begin{equation*}
10, \quad 17, \quad 18, \quad 25, \quad 28, \quad 28 \tag{6.1}
\end{equation*}
$$

median could be any number between 18 and 25 , for concreteness it is taken as the average 21,5.

The $p$ quantile (also known as the $100 p \%$ - percentile) is the point in the data where $100 p \%$ is less and $100(1-p) \%$ is larger. If there are $n$ data points, then the $p$ quantile
occurs at the position $1+(n-1) p$ with weighted averaging if this is between integers. For example the .25 quantile of the numbers $10,17,18,25,28,28$ occurs at the position $1+(6-1)(.25)=2.25$. That is $1 / 4$ of the way between the second and third number which in this example is 17.25 .

Program R has 9 types of sample quantiles. The type 7 is default. Details can be found in Hyndman, Fan (1996) and in help to function quantile.

Quantile corresponding to $p=0.5$ is median $Q(0.5)$, for $p=0.25$ we get lower quartile (or the first quartile) $Q(0.25)$ and for $p=0.75$ we get upper quartile (or third quartile) $Q(0.75)$. The difference $Q(0.75)-Q(0.25)$ is interquartile range.

### 6.3 Sample correlation coefficient

Let $\left(X_{1}, Y_{1}\right)^{\prime}, \ldots,\left(X_{n}, Y_{n}\right)^{\prime}$ be a sample from a two-dimensional distribution. Denote

$$
\begin{array}{cc}
\bar{X}=\frac{1}{n} \sum_{i=1}^{n} X_{i}, \quad \bar{Y}=\frac{1}{n} \sum_{i=1}^{n} Y_{i}, & S_{X Y}=\frac{1}{n-1} \sum_{i=1}^{n}\left(X_{i}-\bar{X}\right)\left(Y_{i}-\bar{Y}\right), \\
S_{X}^{2}=\frac{1}{n-1} \sum_{i=1}^{n}\left(X_{i}-\bar{X}\right)^{2}, & S_{Y}^{2}=\frac{1}{n-1} \sum_{i=1}^{n}\left(Y_{i}-\bar{Y}\right)^{2} .
\end{array}
$$

If

$$
\mathrm{E} X_{i}=\mu_{X}, \quad \mathrm{E} Y_{i}=\mu_{Y}, \quad \operatorname{var} X_{i}=\sigma_{X}^{2}, \quad \operatorname{var} Y_{i}=\sigma_{Y}^{2}, \quad \operatorname{cov}\left(X_{i}, Y_{i}\right)=\sigma_{X Y}
$$

then according theorem 4.1 we have

$$
\mathrm{E} \bar{X}=\mu_{X}, \quad \mathrm{E} \bar{Y}=\mu_{Y}, \quad \mathrm{E} S_{X}^{2}=\sigma_{X}^{2}, \quad \mathrm{E} S_{Y}^{2}=\sigma_{Y}^{2}
$$

and similarly can be proved that

$$
\mathrm{E} S_{X Y}=\sigma_{X Y}
$$

Correlation coefficient $\rho$ was defined in section 2.6 defined as

$$
\rho=\frac{\sigma_{X Y}}{\sqrt{\sigma_{X}^{2} \sigma_{Y}^{2}}}
$$

It is natural to define the sample correlation coefficient $r$ using an analogous formula in which unknown variances and unknown covariance are substituted by their unbiased estimators. If $S_{X}^{2}>0, S_{Y}^{2}>0$, define

$$
r=\frac{S_{X Y}}{\sqrt{S_{X}^{2} S_{Y}^{2}}}
$$

If $S_{X}^{2}=0$ or $S_{Y}^{2}=0$, the sample correlation coefficient is not defined. An elementary arrangement gives

$$
\begin{equation*}
r=\frac{\sum X_{i} Y_{i}-n \bar{X} \bar{Y}}{\sqrt{\left(\sum X_{i}^{2}-n \bar{X}^{2}\right)\left(\sum Y_{i}^{2}-n \bar{Y}^{2}\right)}} . \tag{6.2}
\end{equation*}
$$

Schwarz inequality implies $-1 \leq r \leq 1$.

Theorem 6.1 Let $\left(X_{1}, Y_{1}\right)^{\prime}, \ldots,\left(X_{n}, Y_{n}\right)^{\prime}$ be a sample from a two-dimensional normal distribution with positive variances and the correlation coefficient $\rho \in(-1,1)$. Then $r$ has the density

$$
\begin{equation*}
f_{n}(r)=\frac{2^{n-3}}{(n-3)!\pi}\left(1-\rho^{2}\right)^{(n-1) / 2}\left(1-r^{2}\right)^{(n-4) / 2} \sum_{k=0}^{\infty} \Gamma^{2}\left(\frac{n+k-1}{2}\right) \frac{(2 \rho r)^{k}}{k!} \tag{6.3}
\end{equation*}
$$

for $-1<r<1$.
Proof. See Cramér (1946).
Theorem 6.2 Let assumptions of theorem 6.1 hold and let $\rho=0$. Then the random variable

$$
\begin{equation*}
T=\frac{r}{\sqrt{1-r^{2}}} \sqrt{n-2} \tag{6.4}
\end{equation*}
$$

has the distribution $\mathrm{t}_{n-2}$.
Proof. The $\Gamma$ function satisfies

$$
\Gamma(2 p)=\frac{2^{2 p-1}}{\sqrt{\pi}} \Gamma(p) \Gamma\left(p+\frac{1}{2}\right), \quad p>0 .
$$

We apply this formula to $(n-3)!=\Gamma(n-2)=\Gamma\left(2 \frac{n-2}{2}\right)$. For $\rho=0$ we can write the density (6.3) in the form

$$
\begin{equation*}
f_{n}(r)=\frac{\Gamma\left(\frac{n-1}{2}\right)}{\Gamma\left(\frac{n-2}{2}\right) \sqrt{\pi}}\left(1-r^{2}\right)^{(n-4) / 2}, \quad-1<r<1 . \tag{6.5}
\end{equation*}
$$

We use the transform (6.4) and obtain the density of $\mathrm{t}_{n-2}$ distribution, which was derived in theorem 3.10

Theorem 6.2 shows how to test the hypothesis $H_{0}: \rho=0$ against alternative $H_{1}: \rho \neq$ 0 . First, the sample correlation coefficient $r$ and the variable $T$ are calculated using (6.4) and in the case $|T| \geq t_{n-2}(\alpha)$ hypothesis $H_{0}$ is rejected on the level $\alpha$. The assumption that the sample $\left(X_{1}, Y_{1}\right)^{\prime}, \ldots,\left(X_{n}, Y_{n}\right)^{\prime}$ is from the normal distribution is very important. Test that correlation coefficient $\rho$ is zero is identical with the test $\beta_{1}=0$ in the regression $\operatorname{model} Y_{i}=\beta_{0}+\beta_{1} x_{i}+e_{i}$.

Test that coefficient $\rho$ is zero is very frequent. From this reason critical values for $r$ were tabulated using theorem 6.2. Since in this procedure critical values of $t$ are used, critical value $r_{n}(\alpha)$ is defined as the number for which under $H_{0}$

$$
\mathrm{P}\left[|r| \geq r_{n}(\alpha)\right]=\alpha
$$

holds. This corresponds to the two-sided test. One-sided tests one obtains using elementary modification. However, a computer gives directly $p$-value of the test.

Let us remark that for a sample from the normal distribution in the case $\rho=0$ for $n \geq 3$ one obtains

$$
\mathrm{E} r=0, \quad \operatorname{var} r=\frac{1}{n-1} .
$$

In the case $\rho \in(-1,1)$ can be proved that

$$
\mathrm{E} r=\rho+O\left(n^{-1}\right) \quad \operatorname{var} r=\frac{\left(1-\rho^{2}\right)^{2}}{n}+o\left(n^{-1}\right)
$$

(see Cramér 1946). If the remaining members are ignored, the transformation stabilizing variance can be derived. We dealt with this problem in section 3.4 (see example 3.14 on p. 43). It was derived that the variable $Z$ calculated by means of Fisher $z$-transformation

$$
Z=\frac{1}{2} \ln \frac{1+r}{1-r}
$$

has the distribution with the moments

$$
\mathrm{E} Z \doteq \frac{1}{2} \ln \frac{1+\rho}{1-\rho}, \quad \operatorname{var} Z \doteq \frac{1}{n-3}
$$

and this distribution with $n \rightarrow \infty$ fast converges to the normal distribution. This can be demonstrated on the following fact. We know that the normal distribution has skewness $\alpha_{3}=0$ and kurtosis $\alpha_{4}=3$. Calculations show that $Z$ has skewness and kurtosis given by formulas

$$
\alpha_{3} \doteq \frac{\rho^{6}}{(n-1)^{3}}, \quad \alpha_{4} \doteq 3+\frac{2}{n-1}+\frac{4+2 \rho^{2}-3 \rho^{4}}{(n-1)^{2}} .
$$

If we want to test the hypothesis $H_{0}: \rho=\rho_{0}$, where $\rho_{0} \in(-1,1)$ is a given number against alternative $H_{1}: \rho \neq \rho_{0}$, we calculate first

$$
Z=\frac{1}{2} \ln \frac{1+r}{1-r}, \quad \zeta_{0}=\frac{1}{2} \ln \frac{1+\rho_{0}}{1-\rho_{0}} .
$$

If $H_{0}$ holds then the random variable

$$
U=\sqrt{n-3}\left(Z-\zeta_{0}\right)
$$

has approximately normal distribution $\mathrm{N}(0,1)$. Thus $H_{0}$ will be rejected in the case when

$$
|U| \geq u\left(\frac{\alpha}{2}\right)
$$

Using $z$-transformation an approximate confidence interval for $\rho$ can be constructed. If $\rho$ is the actual value of the correlation coefficient, then

$$
\mathrm{P}\left[\sqrt{n-3}\left|Z-\frac{1}{2} \ln \frac{1+\rho}{1-\rho}\right|<u\left(\frac{\alpha}{2}\right)\right] \doteq 1-\alpha
$$

One gets from this formula that the confidence interval is

$$
\left(\frac{D-1}{D+1}, \frac{H-1}{H+1}\right),
$$

where

$$
D=\exp \left\{2 Z-\frac{2 u\left(\frac{\alpha}{2}\right)}{\sqrt{n-3}}\right\}, \quad H=\exp \left\{2 Z+\frac{2 u\left(\frac{\alpha}{2}\right)}{\sqrt{n-3}}\right\}
$$

Table 6.1: Concentration of milk acid

| $\xi_{i}$ | 40 | 64 | 34 | 15 | 57 | 45 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $\eta_{i}$ | 33 | 46 | 23 | 12 | 56 | 40 |

Example 6.3 Concentration of the milk acid in the blood of mothers (values $\xi_{i}$ ) and their newborn children (values $\eta_{i}$ ) was measured. The results are introduced in tab. 6.1.

Calculation gives $r=0.935$. Critical value is equal to $r_{6}(0,05)=0.8114$. Since $|r| \geq r_{6}(0.05)$, we reject the hypothesis that the concentration of milk acid in blood of mothers and their newborns are uncorrelated values.

Fisher $z$-transformation gives $Z=1.695$. If we want to test $H_{0}: \rho=0$, we have $\rho_{0}=0, \zeta_{0}=0, U=2.937$. Since $|U| \geq u(0.025)=1.96$, we reject $H_{0}$ also using this test.

For the construction of confidence interval for $\rho$ with confidence coefficient 0.95 we get $D=3.088, H=285.439$. From this we calculate that the confidence interval is (0.511, 0.993).

### 6.4 Sample coefficient of multiple correlation

Let the vectors

$$
\begin{equation*}
\binom{Y_{1}}{\boldsymbol{X}_{1}}, \ldots,\binom{Y_{n}}{\boldsymbol{X}_{n}} \tag{6.6}
\end{equation*}
$$

be a sample from $(p+1)$-dimensional distribution. Remember that the random vectors $\boldsymbol{X}_{1}, \ldots, \boldsymbol{X}_{n}$ are $p$-dimensional. The sample correlation coefficient between $i$-th a $j$-th components $\boldsymbol{X}_{1}, \ldots, \boldsymbol{X}_{n}$ will be denoted $r_{i j}$. Let $r_{0 i}$ be a sample correlation coefficient between $Y$-th variables and $i$-th components of vectors $\boldsymbol{X}_{1}, \ldots, \boldsymbol{X}_{n}$.

Introduce sample correlation matrices

$$
\boldsymbol{R}_{\boldsymbol{X} \boldsymbol{X}}=\left(r_{i j}\right)_{i, j=1}^{p} \quad \boldsymbol{R}_{Y \boldsymbol{X}}=\left(r_{0 i}\right)_{i=1}^{p}, \quad \boldsymbol{R}_{\boldsymbol{X} Y}=\boldsymbol{R}_{Y \boldsymbol{X}}^{\prime}
$$

The diagonal of the matrix $\boldsymbol{R}_{\boldsymbol{X} \boldsymbol{X}}$ contains units and the matrix is symmetric. We shall assume that it is also regular. This holds under very general conditions, see Anděl (1978).

If we substitute in (2.18) unknown theoretical correlation matrices by their sample versions, we can define sample coefficient of multiple correlation $r_{Y, \boldsymbol{X}}=r_{0.1,2, \ldots, k}$ as nonnegative number satisfying

$$
r_{Y, \boldsymbol{X}}^{2}=\boldsymbol{R}_{Y \boldsymbol{X}} \boldsymbol{R}_{\boldsymbol{X} \boldsymbol{X}}^{-1} \boldsymbol{R}_{\boldsymbol{X} Y}
$$

If $p=2$, we obtain

$$
r_{0.1,2}^{2}=\frac{r_{01}^{2}+r_{02}^{2}-2 r_{01} r_{02} r_{12}}{1-r_{12}^{2}}
$$

Theorem 6.4 If random vectors (6.6) are the sample from the regular normal distribution, if $n>p+1$, and if $\rho_{Y, \boldsymbol{X}}=0$, then the random variable

$$
Z=\frac{n-p-1}{p} \frac{r_{Y \boldsymbol{X}}^{2}}{1-r_{Y \boldsymbol{X}}^{2}}
$$

has $\mathrm{F}_{p, n-p-1}$ distribution.

Proof. See Anděl (1978).
Theorem 6.4 is an instruction how to test the hypothesis $H_{0}$, that the variable $Y$ does not depend on vector $\boldsymbol{X}$. If we are sure that the assumption concerning normality is fulfilled, we calculate $Z$. In the case $Z \geq F_{p, n-p-1}(\alpha)$ we reject $H_{0}$. The value $r_{Y, \boldsymbol{X}}^{2}$ is called sample coefficient of determination. Further the adjusted coefficient of determination

$$
R_{\mathrm{adj}}^{2}=1-\frac{n-1}{n-p-1}\left(1-r_{Y \boldsymbol{X}}^{2}\right)
$$

is introduced. Although authors of statistical software prefer adjusted coefficient of determination, the use of $R_{\text {adj }}^{2}$ may be dangerous. For example, in the case $r_{Y \boldsymbol{X}}^{2}<p /(n-1)$ we get $R_{\mathrm{adj}}^{2}<0$. But $R_{\mathrm{adj}}^{2}$ is an estimator of theoretical coefficient of determination $\rho_{Y \boldsymbol{X}}^{2}$, which is nonnegative.

Example 6.5 In year 1957 statisticians investigated expenses $Y_{i}$ for food and drinks in households in dependence on number of people in the household $x_{i}$ and on net earnings $z_{i}$. The data concerning 7 randomly chosen households are given in Tab. 6.2.

Table 6.2: Expenses for food and drinks

| $Y_{i}$ | 4 | 3 | 4 | 1 | 6 | 4 | 5 |
| :--- | ---: | ---: | ---: | ---: | ---: | ---: | ---: |
| $x_{i}$ | 4 | 2 | 4 | 1 | 5 | 3 | 4 |
| $z_{i}$ | 10 | 8 | 12 | 3 | 15 | 12 | 13 |

The coefficient of multiple correlation which describes dependence of expenses on number of people and earnings is 0.983 . This is statistically significant value, its $p$-value is 0.001179 .

### 6.5 Sample coefficient of partial correlation

Assume that

$$
\left(\begin{array}{c}
Y_{1}  \tag{6.7}\\
\boldsymbol{X}_{1} \\
Z_{1}
\end{array}\right), \ldots,\left(\begin{array}{c}
Y_{n} \\
\boldsymbol{X}_{n} \\
Z_{n}
\end{array}\right)
$$

is a random sample from a $(p+2)$-dimensional distribution. Vectors $\boldsymbol{X}_{i}$ have again $p$ components. Let $r_{p+1, i}$ be sample correlation coefficient between $Z$-variables and $i$-th components of vectors $\boldsymbol{X}_{1}, \ldots, \boldsymbol{X}_{n}$. Denote

$$
\boldsymbol{R}_{Z \boldsymbol{X}}=\left(r_{p+1, i}\right)_{i=1}^{p}, \quad \boldsymbol{R}_{\boldsymbol{X} Z}=\boldsymbol{R}_{Z \boldsymbol{X}}^{\prime}
$$

In view of theorem 2.18 on p. 29 define sample coefficient of partial correlation $r_{Y, Z \cdot \boldsymbol{X}}$ by the formula

$$
r_{Y, Z . \boldsymbol{X}}=\frac{r_{Y Z}-\boldsymbol{R}_{Y \boldsymbol{X}} \boldsymbol{R}_{\boldsymbol{X} \boldsymbol{X}}^{-1} \boldsymbol{R}_{\boldsymbol{X} Z}}{\sqrt{\left(1-\boldsymbol{R}_{Y \boldsymbol{X}} \boldsymbol{R}_{\boldsymbol{X} \boldsymbol{X}}^{-1} \boldsymbol{R}_{\boldsymbol{X} Y}\right)\left(1-\boldsymbol{R}_{Z \boldsymbol{X}} \boldsymbol{R}_{\boldsymbol{X} \boldsymbol{X}}^{-1} \boldsymbol{R}_{\boldsymbol{X} Z}\right)}},
$$

if the denominator is not zero.

If $p=1$, then we have

$$
r_{Y, Z . X}=\frac{r_{Y Z}-r_{Y X} r_{Z X}}{\sqrt{\left(1-r_{Y X}^{2}\right)\left(1-r_{Z X}^{2}\right)}} .
$$

Theorem 6.6 Let random vectors (6.7) be a sample from regular normal distribution. If $\rho_{Y, Z \cdot X}=0$ and if $n>p+2$ then the random variable

$$
\begin{equation*}
T=\frac{r_{Y, Z \cdot \boldsymbol{X}}}{\sqrt{1-r_{Y, Z \cdot \boldsymbol{X}}^{2}}} \sqrt{n-p-2} \tag{6.8}
\end{equation*}
$$

has $\mathrm{t}_{n-p-2}$ distribution.
Proof. See Anděl (1978).
Theorem 6.6 is used for testing hypothesis $H_{0}: \rho_{Y, Z . X}=0$. From formula (6.8) we calculate $T$ and in the case $|T| \geq t_{n-p-2}(\alpha)$ we reject $H_{0}$. The variable $r_{Y, Z \cdot X}$ can be also directly compared with the critical value for the common correlation coefficient, only $n$ must be substituted by the number $n-p$. It means that $H_{0}$ is rejected in the case

$$
\left|r_{Y, Z . X}\right| \geq r_{n-p}(\alpha)
$$

Example 6.7 We use again data from example 6.5 on p. 62. First, we calculate the matrix of the partial correlation coefficients.

|  | $[, 1]$ | $[, 2]$ | $[, 3]$ |
| ---: | ---: | ---: | ---: |
| $[1]$, | 1.0000000 | 0.517452512 | 0.831167731 |
| $[2]$, | 0.5174525 | 1.000000000 | 0.008143009 |
| $[3]$, | 0.8311677 | 0.008143009 | 1.000000000 |

Sample coefficients of partial correlation are $r_{Y, X . Z}=0.517$ and $r_{Y, Z . X}=0.831$. The corresponding two-sided critical value is 0.8114 . We can see that there exists statistically significant dependence between expenses for food and drinks and for earning even if the influence of the number of the family is eliminated. However, on the basis of given data we cannot reject the hypothesis that expenses for food and drinks do not depend on number of people living in the household if the influence of earning is eliminated. But the sample size was very small, we used it only for illustrations.

## Chapter 7

## Interval estimators

Consider a random vector $\boldsymbol{X}=\left(X_{1}, \ldots, X_{n}\right)^{\prime}$ such that its distribution depends on the parameter $\boldsymbol{\theta}$. We say that the random variable $S$ is pivotal (for $\boldsymbol{\theta}$ ), if $S$ is function only of $\boldsymbol{X}$ and $\boldsymbol{\theta}$ and the distribution of $S$ does not depend on $\boldsymbol{\theta}$.

If the distribution of the vector $\boldsymbol{X}$ depends on the parameter $(\boldsymbol{\theta}, \boldsymbol{\delta})$, then $S$ is pivotal for $\boldsymbol{\theta}$, if $S$ is a function only of $\boldsymbol{X}$ and $\boldsymbol{\theta}$ and in the same time the distribution of $S$ does not depend on $(\boldsymbol{\theta}, \boldsymbol{\delta})$. In this case $\boldsymbol{\delta}$ is called the nuisance parameter.

Pivotal statistics can be used for constructing confidence intervals and confidence sets. Assume first that $\boldsymbol{\theta}=\theta$ is a univariate parameter and $S=S(\boldsymbol{X}, \theta)$ pivotal statistics. If $\alpha \in(0,1)$ is given then we find such numbers $q_{L}, q_{U}$, that it holds

$$
\mathrm{P}\left\{q_{L} \leq S(\boldsymbol{X}, \theta) \leq q_{U}\right\}=1-\alpha .
$$

The inequality $q_{L} \leq S(\boldsymbol{X}, \theta) \leq q_{U}$ will be transformed into form

$$
L\left(\boldsymbol{X}, q_{L}, q_{U}\right) \leq \theta \leq U\left(\boldsymbol{X}, q_{L}, q_{U}\right)
$$

which presents the confidence interval for $\theta$ with confidence coefficient $1-\alpha$. If the parameter $\boldsymbol{\theta}$ is multidimensional, then the inequality $q_{L} \leq S(\boldsymbol{X}, \boldsymbol{\theta}) \leq q_{U}$ is transformed to the form $\boldsymbol{\theta} \in Z\left(\boldsymbol{X}, q_{L}, q_{U}\right)$, which gives the confidence set $Z$.

Example 7.1 Let $X_{1}, \ldots, X_{n}(n \geq 2)$ be a sample from $\mathbf{N}\left(\mu, \sigma^{2}\right)$, where $\sigma>0$. If the parameter $\sigma$ is known, then

$$
S=(\bar{X}-\mu) /(\sigma / \sqrt{n})
$$

is pivotal statistics for $\mu$. Variable $S$ has distribution $\mathbf{N}(0,1)$. Denote $u=u_{\alpha / 2}$ the critical value of the distribution $\mathrm{N}(0,1)$. Then

$$
\mathrm{P}\left\{-u \leq \frac{\bar{X}-\mu}{\sigma / \sqrt{n}} \leq u\right\}=1-\alpha
$$

This implies

$$
\mathrm{P}\left\{\bar{X}-\frac{u \sigma}{\sqrt{n}} \leq \mu \leq \bar{X}+\frac{u \sigma}{\sqrt{n}}\right\}=1-\alpha
$$

and thus

$$
\left[\bar{X}-\frac{u \sigma}{\sqrt{n}}, \bar{X}+\frac{u \sigma}{\sqrt{n}}\right]
$$

is confidence interval for $\mu$ with confidence coefficient $1-\alpha$. The length of this interval is $\Delta=2 u \sigma / \sqrt{n}$. From equation $2 u \sigma / \sqrt{n}=\delta$ we get $n=4 u^{2} \sigma^{2} / \delta^{2}$.

If neither parameter $\mu$ nor parameter $\sigma$ are known, then $T=(\bar{X}-\mu) /(S / \sqrt{n})$ is the pivotal statistics for $\mu$, and now $\sigma$ is nuisance parameter. We know, that $T \sim \mathrm{t}_{n-1}$, so that distribution of $T$ depends neither on $\mu$, nor on $\sigma$. In this case we have

$$
\mathrm{P}\left\{-t_{n-1}(\alpha) \leq \frac{\bar{X}-\mu}{S / \sqrt{n}} \leq t_{n-1}(\alpha)\right\}=1-\alpha .
$$

Similarly we get that

$$
\left[\bar{X}-\frac{t_{n-1}(\alpha) S}{\sqrt{n}}, \bar{X}+\frac{t_{n-1}(\alpha) S}{\sqrt{n}}\right]
$$

is confidence interval for $\mu$ with confidence coefficient $1-\alpha$. $\diamond$

## Chapter 8

## Testing hypotheses

Let the distribution of the random vector $\boldsymbol{X}=\left(X_{1}, \ldots, X_{n}\right)^{\prime}$ depend on an unknown parameter $\boldsymbol{\theta}=\left(\theta_{1}, \ldots, \theta_{k}\right)^{\prime}$. It is known in advance that the parameter belongs to the parametric space $\Omega$, which is a subset of $\mathbb{R}_{k}$. This symbol $\Omega$ has nothing to do with the space $\Omega$, which was introduced as the space of elementary events.

A detailed analysis can lead to hypothesis that $\boldsymbol{\theta}$ belongs to a subset $\omega$ of the space $\Omega$. We are not sure with this assertion and so we call the assertion $\boldsymbol{\theta} \in \omega$ null hypothesis. Briefly it is denoted by $H_{0}: \boldsymbol{\theta} \in \omega$. The other possibility is alternative hypothesis $H_{1}: \boldsymbol{\theta} \notin \omega$. Equivalently one can write $H_{1}: \boldsymbol{\theta} \in \Omega \backslash \omega$. If the set $\omega$ has just one element, we say that the hypothesis $H_{0}$ is simple. If the set $\Omega \backslash \omega$ has one element, we say that the hypothesis $H_{1}$ is simple.

The test of hypothesis $H_{0}$ on the basis of vector $\boldsymbol{X}$ is usually made in the following way. A suitable set $W \in \mathcal{B}_{n}$ is found such that is called critical set. If the event $\{\boldsymbol{X} \in W\}$ is realized, then we reject $H_{0}$. Otherwise we do not reject $H_{0}$. In this decision one of the following cases is realized.
(i) $H_{0}$ is valid and the test do not reject it. The decision is correct.
(ii) $H_{0}$ is not valid and the test rejects it. The decision is correct.
(iii) $H_{0}$ is valid and the test rejects it. We say that it is error of the first kind.
(iv) $H_{0}$ is not valid and the test does not reject it. We say that it is error of the second kind.

Assume that we test $H_{0}: \boldsymbol{\theta}=\boldsymbol{\theta}_{0}$ against alternative $H_{1}: \boldsymbol{\theta}=\boldsymbol{\theta}_{1}$. Let the test have critical set $W$. Then $\beta\left(\boldsymbol{\theta}_{1}\right)=\mathbf{P}\left(\boldsymbol{X} \in W \mid \boldsymbol{\theta}_{1}\right)$ is called power of the test.

We show connection between testing hypotheses and confidence intervals. Let $\theta$ be univariate parameter and $S=S(\boldsymbol{X}, \theta)$ pivotal statistics. Let

$$
W=\left\{S\left(\boldsymbol{X}, \theta_{0}\right) \leq c_{1}, S\left(\boldsymbol{X}, \theta_{0}\right) \geq c_{2}\right\}, \quad c_{1}<c_{2}
$$

be critical set for testing hypothesis $H_{0}: \theta=\theta_{0}$, such that

$$
\mathrm{P}\left\{S\left(\boldsymbol{X}, \theta_{0}\right) \leq c_{1} \mid \theta_{0}\right\}=\alpha_{1}, \quad \mathrm{P}\left\{S\left(\boldsymbol{X}, \theta_{0}\right) \geq c_{2} \mid \theta_{0}\right\}=\alpha_{2}, \quad \alpha_{1}+\alpha_{2}=\alpha
$$

Since $S$ is pivotal, we have

$$
\mathrm{P}\left\{S\left(\boldsymbol{X}, \theta_{0}\right) \leq c_{1}\right\}=\alpha_{1}, \quad \mathrm{P}\left\{S\left(\boldsymbol{X}, \theta_{0}\right) \geq c_{2}\right\}=\alpha_{2} .
$$

Assume that inequality $c_{1}<S(\boldsymbol{X}, \theta)<c_{2}$ is equivalent to inequality $w_{1}<\theta<w_{2}$, where $w_{1}=w_{1}(\boldsymbol{X}), w_{2}=w_{2}(\boldsymbol{X})$. Then

$$
1-\alpha=\mathrm{P}\left\{c_{1}<S(\boldsymbol{X}, \theta)<c_{2}\right\}=\mathrm{P}\left\{w_{1}<\theta<w_{2}\right\} .
$$

Interval $\left(w_{1}, w_{2}\right)$ is confidence interval for $\theta$ with confidence coefficient $1-\alpha$ and it is complement to the critical set for testing $H_{0}$.

Statistical thinking is based on the following principle, which is applied in practical life. If an event has in the experiment only very small probability, we behave as if this event cannot come. The size of this probability denoted by $\alpha$ depends on consequences which the event would have. In practical situations one chooses $\alpha=0,05$ and we shall do this in our text. Hypothesis $H_{0}$ is chosen so that the error of the first kind is more important than error of the second kind. If we do not want to accept the error of the first kind, we must define critical set $W$ so that the probability of error of the first kind would not be larger than $\alpha$. The best choice of the critical test $W$ is such that under this condition the probability of the second kind is minimal. Number $\sup _{\boldsymbol{\theta} \in \omega} \mathrm{P}(\boldsymbol{X} \in W)$ is called level of the test. In some cases the best critical set can be found using Neyman-Pearson lemma.

Lemma 8.1 (Neyman-Pearson) Let $\omega=\left\{\theta_{0}\right\}, \Omega \backslash \omega=\left\{\theta_{1}\right\}$, so that both hypotheses $H_{0}$ and $H_{1}$ are simple. Let $\boldsymbol{X}$ have density $p_{0}$ when $H_{0}$ is valid and density $p_{1}$ under $H_{1}$. Let for a given probability $\alpha \in(0,1)$ there exists a number $c$ such that for the set

$$
\begin{equation*}
W_{0}=\left\{\boldsymbol{x}: p_{1}(\boldsymbol{x}) \geq c p_{0}(\boldsymbol{x})\right\} \tag{8.1}
\end{equation*}
$$

we have

$$
\int_{W_{0}} p_{0}(\boldsymbol{x}) \mathrm{d} \boldsymbol{x}=\alpha
$$

Then for an arbitrary set $W \in \mathcal{B}_{n}$ which fulfills condition

$$
\int_{W} p_{0}(\boldsymbol{x}) \mathrm{d} \boldsymbol{x}=\alpha
$$

it holds

$$
\int_{W_{0}} p_{1}(\boldsymbol{x}) \mathrm{d} \boldsymbol{x} \geq \int_{W} p_{1}(\boldsymbol{x}) \mathrm{d} \boldsymbol{x}
$$

Proof. We have

$$
\begin{aligned}
\int_{W_{0}} p_{1}(\boldsymbol{x}) \mathrm{d} \boldsymbol{x} & -\int_{W} p_{1}(\boldsymbol{x}) \mathrm{d} x=\int_{W_{0} \backslash W} p_{1}(\boldsymbol{x}) \mathrm{d} \boldsymbol{x}-\int_{W \backslash W_{0}} p_{1}(\boldsymbol{x}) \mathrm{d} \boldsymbol{x} \\
& \geq \int_{W_{0} \backslash W} c p_{0}(\boldsymbol{x}) \mathrm{d} \boldsymbol{x}-\int_{W \backslash W_{0}} c p_{0}(\boldsymbol{x}) \mathrm{d} \boldsymbol{x} \\
& =\int_{W_{0}} c p_{0}(\boldsymbol{x}) \mathrm{d} \boldsymbol{x}-\int_{W} c p_{0}(\boldsymbol{x}) \mathrm{d} \boldsymbol{x}=c \alpha-c \alpha=0 .
\end{aligned}
$$

It follows from the lemma that from all critical sets ensuring probability of the first kind equal to $\alpha$ it is $W_{0}$ which has the smallest probability of the second kind.

Thus $W_{0}$ is the best critical set. The set (8.1) can be explained as follows. If for the given $\boldsymbol{x}$ the number $p_{1}(\boldsymbol{x})$ is substantially larger than number $p_{0}(\boldsymbol{x})$, then we conclude that the parameter is $\theta_{1}$.

On the other side, if $p_{0}(\boldsymbol{x})$ is considerably larger than $p_{1}(\boldsymbol{x})$, we decide that the parameter is $\theta_{0}$. It is also problem of estimating parameters and the lemma 8.1 shows that the reasonable procedure can be based on comparison of densities with given value $\boldsymbol{x}$. This leads to the maximum likelihood method.

The critical set is often defined so that a test statistics $S=S(\boldsymbol{X})$ is larger (or smaller) than a calculated value. In such case it is often used $p$-value. It is the probability of obtaining a value as numerically large as or larger than the observed statistics.

## Chapter 9

## One-sample problem

### 9.1 Descriptive statistics

### 9.1.1 Graphs

Boxplot or more descriptively box-and-whiskers plot is a graphical summary of a distribution. The box in the middle indicates hinges, nearly quartiles, and median. The lines (whiskers) show the largest and the smallest observation that falls within a distance of 1.5 times the box size from the nearest hinge. If any observations fall farther away, the additional points are considered extreme values and are shown separately.

If the data are not too many, we can show them on the left (or right) hand side of the graph. In this way we obtain rugplot.

In the case of many data a picture of histogram is useful. Also other graphs are used, for example stripchart.

### 9.2 One-sample Kolmogorov-Smirnov test

In this section we deal with one-sample Kolmogorov-Smirnov test. Let $X_{1}, \ldots, X_{n}$ be a sample from a distribution with continuous distribution function.

Introduce random variables

$$
\xi_{i}(x)= \begin{cases}1, & \text { if } \quad X_{i} \leq x \\ 0, & \text { if } \quad X_{i}>x\end{cases}
$$

for $i=1, \ldots, n$. Define

$$
\begin{equation*}
F_{n}(x)=\frac{1}{n} \sum_{i=1}^{n} \xi_{i}(x) \tag{9.1}
\end{equation*}
$$

Function $F_{n}(x)$ je empirical distribution function. Given a sample, it is the same as the empirical distribution function which was introduced in section 6.1 on p. 57 . We prove that with growing $n$ the function $F_{n}(x)$ approaches to the true distribution function $F(x)$.

Theorem 9.1 Pro every real $x$ we have

$$
F_{n}(x) \rightarrow F(x) \quad \text { almost surely for } \quad n \rightarrow \infty .
$$

Proof. For every fixed $x$ the variables $\xi_{i}(x)$ are independent and identically distributed. They satisfy

$$
\mathrm{P}\left[\xi_{i}(x)=1\right]=F(x), \quad \mathrm{E} \xi_{i}(x)=F(x)
$$

Since $F_{n}(x)$ is defined by the formula (9.1), the assertion follows from Kolmogorov theorem.

It is possible to prove a stronger assertion.
Theorem 9.2 (Glivenko-Cantelli) Denote $D_{m}=\sup _{x}\left|F_{m}(x)-F(x)\right|$. Then it holds

$$
\mathrm{P}\left(\lim _{m \rightarrow \infty} D_{m}=0\right)=1
$$

Proof. See Gnedenko (1954).
We want to test hypothesis $H_{0}$ that this distribution function is $F$. Let $F_{n}$ be empirical distribution function corresponding to the sample $X_{1}, \ldots, X_{n}$. Define

$$
\begin{equation*}
D_{n}=\sup _{x}\left|F_{n}(x)-F(x)\right| . \tag{9.2}
\end{equation*}
$$

With respect to theorems 9.1 and 9.2 large values of the variable $D_{n}$ will give evidence against the hypothesis $H_{0}$. If $n$ is small, special tables of critical values are used. If $n$ is larger, the limit formula is applied, namely that

$$
\lim _{n \rightarrow \infty} \mathrm{P}\left(\sqrt{n} D_{n}<\lambda\right)=K(\lambda)
$$

where

$$
\begin{equation*}
K(\lambda)=1-2 \sum_{k=1}^{\infty}(-1)^{k+1} \exp \left(-2 k^{2} \lambda^{2}\right) . \tag{9.3}
\end{equation*}
$$

For large $n$ critical values $D_{n}(\alpha)$ for random variable $D_{n}$ are approximated by means of

$$
\begin{equation*}
D_{n}(\alpha) \doteq \sqrt{\frac{1}{2 n} \ln \frac{2}{\alpha}} \tag{9.4}
\end{equation*}
$$

(see Likeš, Laga 1978). It means that $H_{0}$ is rejected when $D_{n} \geq D_{n}(\alpha)$.
Notice that calculation of variable $D_{n}$ can be restricted to those values of $x$, in which $F_{n}$ has a jump. In these points it is necessary to take into account not only the difference $F_{n}(x)-F(x)$, but also the limit from the right.

It is necessary to emphasize that the hypothesis $H_{0}$ must determine the distribution function $F$ completely including all parameters.

Kolmogorov-Smirnov test can be used for testing the hypothesis that the random sample $X_{1}, \ldots, X_{n}$ is from rectangular distribution $\mathrm{R}(0,1)$. This is suitable for testing generators of random numbers. The test cannot be used for testing hypothesis that the sample is from the normal distribution. This hypothesis does not specify parameters $\mu$ a $\sigma^{2}$. In the case that we estimate the parameters from the sample and the function $F$ take distribution function of the normal distribution with estimated parameters, the distribution of the test statistics $D_{n}$ would be considerably changed. From this reason the critical values were determined using simulations. For the normal distribution see Lilliefors (1967) and Iman (1982), for the exponential distribution see Lilliefors (1969) and Iman (1982). The generalization to samples from discrete distributions is introduced
in papers Conover (1972) and Mantel (1974). Test of hypothesis that the sample is from the Poisson distribution is described in Campbell, Oprian (1979). Kolmogorov-Smirnov test was generalized to censored samples (see Barr, Davison 1973).

Example 9.3 We simulated the sample with size 20 from the rectangular distribution $\mathrm{R}(0,1)$.
$\begin{array}{lllllllllllllllllllll}0.29 & 0.79 & 0.41 & 0.88 & 0.94 & 0.05 & 0.53 & 0.89 & 0.55 & 0.46 & 0.96 & 0.45 & 0.68\end{array}$
$0.570 .10 \quad 0.90 \quad 0.25 \quad 0.04 \quad 0.33 \quad 0.95$
The one-sample Kolmogorov-Smirnov test gives the results
D $=0.183, \mathrm{p}$-value $=0.4604$
alternative hypothesis: two-sided
Since the $p$-value is larger than 0.05 , the hypothesis about sample from the rectangular distribution is not rejected. See Fig. $9.1 \diamond$.


Figure 9.1: Kolmogorov-Smirnov one-sample test

### 9.3 One-sample t test

Let $X_{1}, \ldots, X_{n}$ be a random sample from z $\mathrm{N}\left(\mu, \sigma^{2}\right)$, where $\sigma^{2}>0$ and $n \geq 2$. Assume that no parameter $\mu$ and $\sigma^{2}$ is known. We shall investigate a test of $H_{0}: \mu=\mu_{0}$ against $H_{1}: \mu \neq \mu_{0}$.

Theorem 9.4 If the true expectation of the normal distribution is $\mu$, then the random variable

$$
T=\frac{\bar{X}-\mu}{S} \sqrt{n}
$$

has $\mathrm{t}_{n-1}$ distribution.

Proof. It follows from Theorem 4.6 on p. 48 that

$$
X=\frac{\bar{X}-\mu}{\sigma} \sqrt{n} \sim \mathrm{~N}(0,1), \quad Z=\frac{(n-1) S^{2}}{\sigma^{2}} \sim \chi_{n-1}^{2}
$$

and that $X$ a $Z$ are independent. We use theorem 40 which says that

$$
X / \sqrt{Z /(n-1)} \sim \mathrm{t}_{n-1}
$$

We easily get $X / \sqrt{Z /(n-1)}=T$.
Critical value $t_{k}(\alpha)$ of Student t distribution with $k$ degrees of freedom is defined so that probability of its exceeding by the random variable with distribution $\mathrm{t}_{k}$ is $\alpha / 2$. It means that in the case $T \sim \mathrm{t}_{k}$ is

$$
\mathrm{P}\left\{|T| \geq t_{k}(\alpha)\right\}=\alpha
$$

This is the difference from definition of most other distributions.
Let us return to the problem formulated at the beginning of this section. If $H_{0}$ holds, then using theorem 9.4 and definition of critical values of $t$ distribution we have

$$
\begin{equation*}
\mathrm{P}\left[\frac{\left|\bar{X}-\mu_{0}\right|}{S} \sqrt{n} \geq t_{n-1}(\alpha)\right]=\alpha \tag{9.5}
\end{equation*}
$$

Practical procedure for testing $H_{0}$ against $H_{1}$ is the following:
(i) Calculate value $T_{0}=\frac{\bar{X}-\mu_{0}}{S} \sqrt{n}$.
(ii) If $\left|T_{0}\right| \geq t_{n-1}(\alpha)$, reject $H_{0}$. Otherwise do not reject $H_{0}$.

Formula (9.5) ensures that the level of the test is $\alpha$.
If we consider the complementary event then from formula (9.5) we get

$$
1-\alpha=\mathrm{P}\left[\bar{X}-\frac{S}{\sqrt{n}} t_{n-1}(\alpha)<\mu<\bar{X}+\frac{S}{\sqrt{n}} t_{n-1}(\alpha)\right] .
$$

Thus the interval $\bar{X} \mp n^{-1 / 2} S t_{n-1}(\alpha)$ is the confidence interval for $\mu$ for unknown $\sigma^{2}$ with confidence coefficient $1-\alpha$.

One-sided tests and one-sided confidence intervals can be derived similarly as for the normal distribution with known variance. The results differ so that instead of $\sigma^{2}$ we have $S^{2}$ and instead of value $u(\alpha)$ we have $t(2 \alpha)$.
Example 9.5 An automaton fills boxes with a washing powder. Each box should contain 1 kg of the powder. Five boxes were randomly taken and their contain exactly weighted. The following departures (in dkg ) were found:

$$
\begin{array}{ccccc}
-3 & 2 & -2 & 0 & -1 .
\end{array}
$$

It should be detected if there is systematic departure from the considered value.
We consider our data as random sample from z $\mathrm{N}\left(\mu, \sigma^{2}\right)$, If there is no systematic departure, the hypothesis $H_{0}: \mu=0$ holds. If there is a departure, the hypothesis $H_{1}: \mu \neq 0$ will hold. We have

$$
n=5, \quad \bar{X}=-0.8, \quad S^{2}=3.7, \quad T_{0}=-0.9300
$$

Since $\left|T_{0}\right|<t_{4}(0.05)=2.776$, the hypothesis $H_{0}$ cannot be rejected. Two-sided confidence interval for the parameter $\mu$ with the confidence coefficient 0,95 is ( $-3.19,1.59$ ). Notice that it contains value $\mu_{0}=0$.

### 9.4 Variance

Consider the random sample $X_{1}, \ldots, X_{n}$ from $\mathrm{N}\left(\mu, \sigma^{2}\right)$, where $n>1$ and no parameter $\mu$ and $\sigma^{2}>0$ is known. We shall deal with the test $H_{0}: \sigma^{2}=\sigma_{0}^{2}$ against $H_{1}: \sigma^{2}>$ $\sigma_{0}^{2}$. Let $\chi_{f}^{2}(\alpha)$ be critical value of distribution $\chi_{f}^{2}$. It is the number which the random variable with distribution $\chi_{f}^{2}$ exceeds with probability $\alpha$. Test is based on the variable $S^{2}=\sum_{i=1}^{n}\left(X_{i}-\bar{X}\right)^{2} /(n-1)$, which is unbiased estimator of the parameter $\sigma^{2}$ and its distribution does not depend on $\mu$. We choose critical set $S^{2} \geq k$. If $H_{0}$ is true and we want

$$
\alpha=\mathrm{P}\left(S^{2} \geq k\right)=\mathrm{P}\left\{\frac{(n-1) S^{2}}{\sigma_{0}^{2}} \geq \frac{(n-1) k}{\sigma_{0}^{2}}\right\}
$$

we must have

$$
(n-1) k / \sigma_{0}^{2}=\chi_{n-1}^{2}(\alpha)
$$

so that

$$
k=\sigma_{0}^{2} \chi_{n-1}^{2}(\alpha) /(n-1)
$$

If the true variance is $\sigma^{2}$, we obtain

$$
\mathrm{P}\left\{\frac{(n-1) S^{2}}{\chi_{n-1}^{2}(\alpha)}<\sigma^{2}\right\}=1-\alpha
$$

Thus

$$
\left((n-1) S^{2} / \chi_{n-1}^{2}(\alpha), \infty\right)
$$

is the right-hand side confidence interval for $\sigma^{2}$.
If we want to test $H_{0}: \sigma^{2}=\sigma_{0}^{2}$ against $H_{1}: \sigma^{2} \neq \sigma_{0}^{2}$, we reject $H_{0}$ in the case that either $S^{2} \leq k_{1}$, or $S^{2} \geq k_{2}$. The statisticians usually choose $k_{1}$ and $k_{2}$ so that

$$
\mathrm{P}\left(S^{2} \leq k_{1}\right)=\frac{\alpha}{2}, \quad \mathrm{P}\left(S^{2} \geq k_{2}\right)=\frac{\alpha}{2}
$$

This will be satisfied when

$$
k_{1}=\frac{\sigma_{0}^{2} \chi_{n-1}^{2}\left(1-\frac{\alpha}{2}\right)}{n-1}, \quad k_{2}=\frac{\sigma_{0}^{2} \chi_{n-1}^{2}\left(\frac{\alpha}{2}\right)}{n-1} .
$$

If the true variance is $\sigma^{2}$, then

$$
\mathrm{P}\left\{\frac{(n-1) S^{2}}{\chi_{n-1}^{2}\left(\frac{\alpha}{2}\right)}<\sigma^{2}<\frac{(n-1) S^{2}}{\chi_{n-1}^{2}\left(1-\frac{\alpha}{2}\right)}\right\}=1-\alpha
$$

It implies that

$$
\left(\frac{(n-1) S^{2}}{\chi_{n-1}^{2}\left(\frac{\alpha}{2}\right)}, \frac{(n-1) S^{2}}{\chi_{n-1}^{2}\left(1-\frac{\alpha}{2}\right)}\right)
$$

is the two-sided confidence interval for $\sigma^{2}$ with confidence coefficient $1-\alpha$.
The two-sided confidence interval satisfying condition $\mathrm{P}\left(S^{2} \leq k_{1}\right)=\mathrm{P}\left(S^{2} \geq k_{2}\right)=$ $\frac{\alpha}{2}$ is not optimal in the sense that its length is not shortest possible. If the density of the corresponding random variable is unimodal and smooth, the optimal confidence interval may be calculated using theorem 9.6 (see Farnsworth 2004). There are two
complementary problems. First, we would find the interval of the given length which has maximal probability. In the second problem we want to find the shortest interval which has the given probability. It is clear that the solution of the second problem leads to the solution of the first one.

Theorem 9.6 Let the random variable $X$ have absolutely continuous distribution function $F$ and the differentiable density $f$. Let $w>0$ be the given number. Consider all couples $(x, x+w)$ such that $f^{\prime}(x)>0, f^{\prime}(x+w)<0$. If $f(x)=f(x+w)$ holds, then the interval $[x, x+w]$ has locally maximal probability among all intervals of length $w$.

Proof. Define

$$
A(x)=\mathrm{P}(X \leq x+w)-\mathrm{P}(x \leq x)=F(x+w)-F(x)
$$

When $w$ is fixed, $A(x)$ depends only on $x$. We have $A^{\prime}(x)=f(x+w)-f(x)$, so that the condition $A^{\prime}(x)=0$ gives $f(x+w)=f(x)$. Since $A^{\prime \prime}(x)=f^{\prime}(x+w)-f^{\prime}(x)<0$, local maximum of $A(x)$ is at point $x$ for which $f(x+w)=f(x)$.

In many cases we have $f(x)=0$ for $x<0, f(x)$ increasing on $\left(0, x_{0}\right)$ and decreasing on $\left(x_{0}, \infty\right)$. Then $A(x)$ has exactly one local maximum which is also global maximum.

### 9.5 Sign test

Let $X_{1}, \ldots, X_{n}$ be a sample from a continuous distribution with median $\tilde{x}$. It means that

$$
\mathrm{P}\left(X_{i}<\tilde{x}\right)=\mathrm{P}\left(X_{i}>\tilde{x}\right)=\frac{1}{2}, \quad i=1, \ldots, n
$$

We test the hypothesis $H_{0}: \tilde{x}=x_{0}$, where $x_{0}$ is a given number. We start with the two-sided test where the alternative hypothesis is $H_{1}: \tilde{x} \neq x_{0}$. We form the differences $X_{1}-x_{0}, \ldots, X_{n}-x_{0}$. If some differences are zeros then they are dropped. Number of positive differences will be denoted as $Y$. If $H_{0}$ holds, $Y$ has binomial distribution $\operatorname{Bi}\left(n, \frac{1}{2}\right)$. Hypothesis $H_{0}$ will be rejected, if $Y$ is nearly zero, or nearly $n$. In such cases tables of critical values $k_{1}$ a $k_{2}$ can be used. They satisfy

$$
\begin{equation*}
\mathrm{P}\left(Y \leq k_{1}\right) \leq \frac{\alpha}{2}, \quad \mathrm{P}\left(Y \geq k_{2}\right) \leq \frac{\alpha}{2} . \tag{9.6}
\end{equation*}
$$

Here $k_{1}$ is the largest and $k_{2}$ the smallest number for which (9.6) is valid. Because the distribution $\operatorname{Bi}\left(n, \frac{1}{2}\right)$ is symmetric, we have $k_{2}=n-k_{1}$.

Hypothesis $H_{0}$ will be rejected in the cases when $Y \leq k_{1}$ or $Y \geq k_{2}$. The level of test is maximally $\alpha$. Usually, it is considerable smaller than $\alpha$.

Introduce random variables $\xi_{1}, \ldots, \xi_{n}$ so that $\xi_{i}=0$ in case $X_{i}-x_{0} \leq 0$ and $\xi_{i}=1$ in the case $X_{i}-x_{0}>0$. Thus $Y=\xi_{1}+\cdots+\xi_{n}$. Since $\mathrm{E} \xi_{i}=\frac{1}{2}$, var $\xi_{i}=\frac{1}{4}$, central limit theorem ensures that the variable $\left(Y-\frac{n}{2}\right) / \sqrt{n}$ has asymptotically distribution $\mathrm{N}\left(0, \frac{1}{4}\right)$. Thus the variable

$$
\begin{equation*}
U=\frac{2 Y-n}{\sqrt{n}} \tag{9.7}
\end{equation*}
$$

has asymptotically distribution $\mathrm{N}(0,1)$. The hypothesis $H_{0}$ will be rejected when $|U| \geq$ $u\left(\frac{\alpha}{2}\right)$. The level of this test tends to $\alpha$. The procedure is used if $n \geq 20$. Practically, $H_{0}$ is rejected when $U^{2} \geq \chi_{1}^{2}(\alpha)$.

The sign test is used specially in the case when the distribution of random variables $X_{i}$ is considerably skew. However, the power of this test as rather small. Since this test has considerably large probability of the error of the second kind, it is recommended to have in the disposal larger number of observations $n$.

If from the technical reasons some differences $X_{i}-x_{0}$ are zeros then these values are left out and number $n$ is correspondingly decreased.

The sign test can be one-sided. Multidimensional sign test is introduced in Bennet (1962).

Example 9.7 Ten persons should independently estimate time one minute. The following results (in seconds) were registered:

$$
53, \quad 48, \quad 45, \quad 55, \quad 63, \quad 51, \quad 66, \quad 56, \quad 50, \quad 58 .
$$

We have $\tilde{x}=60, n=10$, number of differences with positive sign is $Y=2$. For $n=10$ and $\alpha=0,05$ we have $k_{1}=1, k_{2}=9$. Since $Y \in\left(k_{1}, k_{2}\right)$, the sign test does not reject hypothesis $H_{0}$. It can be calculated that in this case the actual level of the test is not 0,05 , but only 0,02 . But the test which would use values $k_{1}=2, k_{2}=8$, would have level 0,11 .

### 9.6 One-sample Wilcoxon test

Let $X_{1}, \ldots, X_{n}$ be random sample from a continuous distribution with the density $f$, which is symmetric around the point $a$. Then we have $f(a+x)=f(a-x)$. Then obviously $a$ must be median $\tilde{x}$. If there exists finite expectation of this distribution then for each $i$ it must hold $\mathrm{E} X_{i}=a$. Finiteness of the expectation is not assumed, however. The one-sample Wilcoxon test is designed to testing hypothesis $H_{0}: \tilde{x}=x_{0}$ against the alternative hypothesis $H_{1}: \tilde{x} \neq x_{0}$.

Assume that no variable $X_{i}$ is equal to $x_{0}$. Define $Y_{i}=X_{i}-x_{0}$. The variables $Y_{i}$ order into non-decreasing sequence with respect to their absolute value

$$
|Y|_{(1)} \leq|Y|_{(2)} \leq \cdots \leq|Y|_{(n)}
$$

Let $R_{i}^{+}$be the rank of variable $\left|Y_{i}\right|$. Define

$$
S^{+}=\sum_{Y_{i} \geq 0} R_{i}^{+}, \quad S^{-}=\sum_{Y_{i}<0} R_{i}^{+} .
$$

It holds $S^{+}+S^{-}=n(n+1) / 2$. If the number $\min \left(S^{+}, S^{-}\right)$is smaller or equal to critical value $w_{n}(\alpha)$, we reject $H_{0}$.

Our assumptions imply that $Y_{1}, \ldots, Y_{n}$ are independent identically distributed random variables and their distribution is symmetric around zero.

Theorem 9.8 Vectors $\left(\operatorname{sign} Y_{1}, \ldots, \operatorname{sign} Y_{n}\right)^{\prime}$ and $\left(|Y|_{(1)}, \ldots,|Y|_{(n)}\right)^{\prime}$ are independent.

Proof. Since the variables $Y_{i}$ are independent, vectors (sign $\left.Y_{i},\left|Y_{i}\right|\right)^{\prime}$ are also independent. From continuity and symmetry of distribution it follows that

$$
\mathrm{P}\left(\operatorname{sign} Y_{i}=1\right)=\mathrm{P}\left(\operatorname{sign} Y_{i}=-1\right)=\frac{1}{2} .
$$

For an arbitrary $y>0$ we have

$$
\begin{aligned}
\mathrm{P}\left(\operatorname{sign} Y_{i}=1,\left|Y_{i}\right|<y\right) & =\mathrm{P}\left(0<Y_{i}<y\right)=\frac{1}{2} \mathrm{P}\left(-y<Y_{i}<y\right) \\
& =\frac{1}{2} \mathrm{P}\left(\left|Y_{i}\right|<y\right)=\mathrm{P}\left(\operatorname{sign} Y_{i}=1\right) \mathrm{P}\left(\left|Y_{i}\right|<y\right) .
\end{aligned}
$$

Thus the variables sign $Y_{i}$ and $\left|Y_{i}\right|$ are for every $i$ independent. The result is that the vectors $\left(\operatorname{sign} Y_{1}, \ldots, \operatorname{sign} Y_{n}\right)^{\prime}$ and $\left(\left|Y_{1}\right|, \ldots,\left|Y_{n}\right|\right)^{\prime}$ are independent. Since the vector $\left(|Y|_{(1)}, \ldots,|Y|_{(n)}\right)^{\prime}$ is a function of the vector $\left(\left|Y_{1}\right|, \ldots,\left|Y_{n}\right|\right)^{\prime}$, the proof is finished.

Theorem 9.9 Let $S=\sum_{i=1}^{n} R_{i}^{+} \operatorname{sign} Y_{i}$. Then

$$
S^{+}=\frac{1}{2} S+\frac{n(n+1)}{4}
$$

Proof. We have $S^{+}-S^{-}=S, S^{+}+S^{-}=n(n+1) / 2$. From here $S^{+}$can be easily calculated.

Theorem 9.10 If $H_{0}$ holds, then

$$
\mathrm{E} S^{+}=\frac{1}{4} n(n+1), \quad \operatorname{var} S^{+}=\frac{1}{24} n(n+1)(2 n+1)
$$

Proof. First we notice that Esign $Y_{i}=0$ for every $i$. From theorem 9.8 we get that $\mathrm{E}\left(R_{i}^{+} \operatorname{sign} Y_{i}\right)=\left(\mathrm{E} R_{i}^{+}\right)\left(\mathrm{E}\right.$ sign $\left.Y_{i}\right)$, and thus

$$
\begin{equation*}
\mathrm{E}\left(R_{i}^{+} \operatorname{sign} Y_{i}\right)=0 . \tag{9.8}
\end{equation*}
$$

From here

$$
\mathrm{E} S=\sum_{i=1}^{n} \mathrm{E}\left(R_{i}^{+} \operatorname{sign} Y_{i}\right)=0
$$

In view of (9.8) we have

$$
\begin{aligned}
\operatorname{var}\left(R_{i}^{+} \operatorname{sign} Y_{i}\right) & =\mathrm{E}\left(R_{i}^{+} \operatorname{sign} Y_{i}\right)^{2}=\mathrm{E}\left(R_{i}^{+}\right)^{2} \mathrm{E}\left(\operatorname{sign} Y_{i}\right)^{2}=\mathrm{E}\left(R_{i}^{+}\right)^{2} \\
& =1^{2} \frac{1}{n}+2^{2} \frac{1}{n}+\cdots+n^{2} \frac{1}{n}=\frac{1}{6}(n+1)(2 n+1) .
\end{aligned}
$$

Similarly can be proved that

$$
\operatorname{cov}\left(R_{i}^{+} \operatorname{sign} Y_{i}, R_{j}^{+} \operatorname{sign} Y_{j}\right)=0 \quad \text { for } i \neq j
$$

Now, we apply theorem 2.4 on p. 22.

It can be proved (see Hájek, Šidák 1967), that $S^{+}$has asymptotically normal distribution. The hypothesis $H_{0}$ can be tested by means of statistics

$$
U=\frac{S^{+}-\mathrm{E} S^{+}}{\sqrt{\operatorname{var} S^{+}}}
$$

where $\mathrm{E} S^{+}$and $\operatorname{var} S^{+}$are introduced in theorem 9.10. If $|U| \geq u\left(\frac{\alpha}{2}\right)$, hypothesis $H_{0}$ is rejected on the level, which is approaching to $\alpha$ as $n \rightarrow \infty$.

It is necessary to emphasize that one of the assumptions of the on-sample Wilcoxon test is the symmetry of the density $f$ around the median. Hypothesis $H_{0}$ can be correctly rejected also in the case when the median is equal to $x_{0}$, but the density $f$ is strongly non-symmetric.

If some of the variables $X_{i}$ is equal to $x_{0}$, usually this observation is left out.
Example 9.11 We show the analysis of the data introduced in example 9.7. We remember that estimates of time of one minute (in seconds) were

$$
53, \quad 48, \quad 45, \quad 55, \quad 63, \quad 51, \quad 66, \quad 56, \quad 50, \quad 58 .
$$

If the median of this distribution is $x_{0}=60$ seconds, we would obtain variables $Y_{i}=$ $X_{i}-60$. They are equal to

$$
\begin{array}{lllllllll}
-7, & -12, & -15, & -5, & 3, & -9, & 6, & -4, & -10,
\end{array} \quad-2 \text {. }
$$

We order the variables in a non-decreasing series with respect to their absolute values. We get

$$
-2, \quad 3, \quad-4, \quad-5, \quad 6, \quad-7, \quad-9, \quad-10, \quad-12, \quad-15 .
$$

The order of the number 3 is 2 , the order of 6 has the order 5 . Thus $S^{+}=2+5=7$. We get $S^{-}=10 \times 11 / 2-S^{+}=48$. Critical value is $w_{10}(0,05)=8$. Since $\min \left(S^{+}, S^{-}\right)=$ $7 \leq w_{10}(0,05)=8$, we reject the hypothesis that in human population half persons the length of one minute undervalues and half overvalues. The asymptotic procedure would give

$$
\mathrm{E} S^{+}=27,5, \quad \operatorname{var} S^{+}=96,25, \quad U=-2,09
$$

Since $|U| \geq u(0.025)=1.96$, hypothesis $H_{0}$ would be rejected also by this procedure.

### 9.7 Hodges-Lehmann estimator

Let $X_{1}, \ldots, X_{n}$ be random variables and $X_{(1)} \leq \cdots \leq X_{(n)}$ the ordered random sample. Define

$$
\tilde{X}= \begin{cases}X_{(k+1)}, & \text { if } n=2 k+1 \\ {\left[X_{(k)}+X_{(k+1)}\right] / 2,} & \text { if } n=2 k\end{cases}
$$

Then $\tilde{X}$ is called median of random variables $X_{1}, \ldots, X_{n}$. We use denotation $\tilde{X}=$ $\operatorname{median}\left(X_{1}, \ldots, X_{n}\right)$.

Let $X_{1}, X_{2}$ be independent random variables with identical distribution function $F$, which has median $\tilde{x}$. Consider the variable $Y=\left(X_{1}+X_{2}\right) / 2$ and denote $G$ the distribution
function of the variable $Y$. Then $\tilde{y}$ is pseudomedian of the distribution, which has the distribution function $F$. Notice that pseudomedian was introduced in the paper Høyland (1965).

Distribution of the random variable $X$ is symmetric about the point $\mu$, if we have for all real $x$

$$
\mathrm{P}(X \geq \mu+x)=\mathrm{P}(X \leq \mu-x)
$$

The distribution is called symmetric, if there exists such $\mu$ that this distribution is symmetric about $\mu$.

Theorem 9.12 If the distribution defined by the distribution function $F$ is symmetric and if there exist median and pseudomedian uniquely, then median and pseudomedian are the same. If the distribution that corresponds to the distribution function $F$ is not symmetric then generally $\tilde{x} \neq \tilde{y}$.

Proof. Assume without loss of generality that the distribution given by the distribution function $F$ is symmetric about zero. A necessary and sufficient condition for it is that its characteristic function is real. Because characteristic function of the sum $X_{1}+X_{2}$ is the product of characteristic functions of individual summands, the distribution of the sum $X_{1}+X_{2}$ is symmetric about zero. If median and pseudomedian are defined uniquely, each of them must be zero.

Let $X_{1}$ and $X_{2}$ be independent identically distributed random variables with exponential distribution with the parameter $\lambda=2$, which has density $f$ and the distribution function $F$ given by formulas

$$
f(x)=\frac{1}{2} \mathrm{e}^{-x / 2}, \quad F(x)=1-\mathrm{e}^{-x / 2}, \quad x>0 .
$$

Median of this distribution $\tilde{x}$ is the root of the equation $F(x)=1 / 2$. We get $\tilde{x}=2 \ln 2=$ 1.386294.

Now, we take into account that $f$ is the density of the distribution $\chi_{2}^{2}$. Consequently, the variable $Z=X_{1}+X_{2}$ has distribution $\chi_{4}^{2}$ with density $g(z)=\frac{1}{4} z \mathrm{e}^{-z / 2}$ for $z>0$. Let $Y=Z / 2$. Then $Y$ has density $h(y)=y \mathrm{e}^{-y}$ for $y>0$ and the distribution function

$$
H(y)=1-(1+y) \mathrm{e}^{-y}, \quad y>0 .
$$

Median $\tilde{y}$ of the distribution with the distribution function $H$ one gets by solving equation $H(y)=1 / 2$. The result is $\tilde{y}=1.67835$. Median of the distribution $\operatorname{Ex}(2)$ is not the same as pseudomedian of this distribution.

Let us return to the original formulation of the test. We defined $Y_{i}=X_{i}-x_{0}$, and the unknown median of the distribution $X_{i}$ is $a$. If it holds $x_{0}=a$, from theorem 9.10 we would have $\mathrm{E} S^{+}=n(n+1) / 4$. It suggest to take as estimator of parameter $a$ such value $x_{0}=\hat{a}$,for which we should have $S^{+}=n(n+1) / 4$. The solution is to choose

$$
\hat{a}=\operatorname{medin}\left\{\frac{X_{i}+X_{j}}{2}, \quad i \leq j\right\}
$$

Each of $n(n+1) / 2$ means $\left(X_{i}+X_{j}\right) / 2$ is called Walsh mean (Walsh 1949). The variable $\hat{a}$ is called Hodges-Lehmann estimator (it belongs to the class of estimators introduced
in paper Hodges, Lehmann 1963). Based on principles leading to Hodges-Lehmann estimator it is possible to construct nonparametric confidence interval for pseudomedian (see Hollander, Wolfe 1973, p. 35). We remark, that the Hodges-Lehmann estimator and nonparametric confidence interval can be constructed also in the case of two samples in connection with two-sample Wilcoxon test (see Hollander, Wolfe 1973, p. 75).

Example 9.13 We continue with the example 9.11. The calculations are made by program r.

```
p-value = 0.03711,
95 percent confidence interval: 50.0 59.5
sample estimates: (pseudo)median
    5 4
```

Hodges-Lehmann estimator for pseudomedian is 54, the confidence interval for pseudomedian with confidence level 0.95 is (50.0, 59.5).

## Chapter 10

## Discrete one-sample problem

### 10.1 Confidence intervals and tests for $p$

### 10.1.1 Tests in binomial distribution

Assume that $X \sim \operatorname{Bi}(n, p)$. We describe a test $H_{0}: p=p_{0}$ against $H_{1}: p \neq p_{0}$, where $p_{0}$ is given value from interval $(0,1)$. The sign test was a special case of this problem with $p_{0}=\frac{1}{2}$.

If $n$ is a small number, we calculate for the given $\alpha$ the largest integer $k_{1}$ such that

$$
S_{1}\left(k_{1}\right)=\sum_{i=0}^{k_{1}}\binom{n}{i} p_{0}^{i}\left(1-p_{0}\right)^{n-i} \leq \frac{\alpha}{2}
$$

and the smallest integer $k_{2}$ such, that

$$
S_{2}\left(k_{2}\right)=\sum_{i=k_{2}}^{n}\binom{n}{i} p_{0}^{i}\left(1-p_{0}\right)^{n-i} \leq \frac{\alpha}{2} .
$$

Hypothesis $H_{0}$ will be rejected on the level maximally $\alpha$, if $X \leq k_{1}$ or $X \geq k_{2}$.
A direct calculation of sums $S_{1}\left(k_{1}\right)$ and $S_{2}\left(k_{2}\right)$ can be mathematically very difficult. A better procedure is to use the relation

$$
\begin{equation*}
\sum_{i=0}^{s}\binom{n}{i} p^{i}(1-p)^{n-i}=F_{2(n-s), 2(s+1)}^{*}\left[\frac{(s+1)(1-p)}{p(n-s)}\right], \tag{10.1}
\end{equation*}
$$

which is valid for $s=0,1, \ldots, n-1$; here $F_{m, n}^{*}(x)$ is distribution function of the FisherSnedecor distribution. See Ling (1992), Peizer, Pratt (1968) and Pratt (1968).

This method is equivalent to the following procedure. Denote

$$
\begin{aligned}
& D=\frac{X}{X+(n-X+1) F_{2(n-X+1), 2 X}\left(\frac{\alpha}{2}\right)}, \\
& H=\frac{(X+1) F_{2(X+1), 2(n-X)}\left(\frac{\alpha}{2}\right)}{n-X+(X+1) F_{2(X+1), 2(n-X)}\left(\frac{\alpha}{2}\right)},
\end{aligned}
$$

where $F_{m, n}(\beta)$ denotes the critical value of the $\mathrm{F}_{m, n}$ distribution on the level $\beta$. If $0<$ $X<n$, then $(D, H)$ is confidence interval for parameter $p$ with the confidence coefficient $1-\alpha$. In the case $p_{0} \notin(D, H)$, we reject the hypothesis $H_{0}$. Here $(D, 1)$ is right-hand side confidence interval for parameter $p$ with confidence coefficient $1-\frac{\alpha}{2}$ (when $X=n$ ) and $(0, H)$ is left-hand side confidence interval for $p$ with confidence coefficient $1-\frac{\alpha}{2}$ (also when $X=0$ ).

Example 10.1 Simonoff (2003) on p. 66 introduces that among the 13 patients, that had Lymski borelioza, to a given diagnostic test 8 reacted. Estimated sensitivity of the test is $8 / 13=61.5 \%$.

### 10.1.2 Wald confidence interval

Let $X \sim \operatorname{Bi}(n, p)$. Let $u_{\alpha}$ be critical value of the distribution $\mathrm{N}(0,1)$ on level $\alpha$. If value $X=x(x \neq 0, x \neq n)$, is observed, then the maximum-likelihood estimator of the parameter $p$ is $\hat{p}=x / n$.

Denote $q=1-p, \hat{q}=1-\hat{p}$,

$$
\xi=\frac{\hat{p}-p}{\sqrt{p q / n}}, \quad Z=\frac{\hat{p}-p}{\sqrt{\hat{p} \hat{q} / n}}
$$

Then $\hat{p} \xrightarrow{\mathrm{P}} p, \hat{q} \xrightarrow{\mathrm{P}} q, \xi \xrightarrow{\mathrm{~d}} \mathrm{~N}(0,1)$. Since

$$
Z=\frac{\frac{\hat{p}-p}{\sqrt{p q / n}}}{\sqrt{\frac{\hat{p} \hat{q}}{p q}}}
$$

from Cramér-Slucky theorem it follows that $Z \xrightarrow{d} N(0,1)$. From this reason an approximate confidence interval for $p$ with confidence coefficient $1-\alpha$ is equal

$$
\begin{equation*}
\hat{p} \pm u_{\alpha / 2} \sqrt{\hat{p}(1-\hat{p}) / n} \tag{10.2}
\end{equation*}
$$

It is so called Wald confidence interval or standard confidence interval.
It is not recommended to use the Wald interval when $n$ is small. The problem is that the confidence coefficient can substantially differ from its nominal value and in many cases is rather small.

### 10.1.3 Wilson confidence interval

Because of above mentioned problems the statisticians looked for other methods for constructing confidence interval. Since

$$
\mathrm{P}\left(\left|\frac{\hat{p}-p}{\sqrt{p(1-p) / n}}\right| \leq u_{\alpha / 2}\right) \approx 1-\alpha
$$

we have

$$
\mathrm{P}\left(|\hat{p}-p|^{2} \leq u_{\alpha / 2}^{2} p(1-p) / n\right) \approx 1-\alpha .
$$

The roots of the equation

$$
|\hat{p}-p|^{2}=u_{\alpha / 2}^{2} p(1-p) / n
$$

determine new confidence interval. Define shortly $u=u_{\alpha / 2}$. Then we get the equation

$$
\left(n+u^{2}\right) p^{2}-\left(2 n \hat{p}+u^{2}\right) p+n \hat{p}^{2}=0
$$

with roots

$$
\begin{aligned}
p_{12} & =\frac{2 n \hat{p}+u^{2} \pm \sqrt{\left(2 n \hat{p}+u^{2}\right)^{2}-4\left(n+u^{2}\right) n \hat{p}^{2}}}{2\left(n+u^{2}\right)} \\
& =\hat{p} \frac{n}{n+u^{2}}+\frac{1}{2} \frac{u^{2}}{n+u^{2}} \pm \sqrt{\frac{\hat{p}(1-\hat{p})}{n} \frac{n^{2} u^{2}}{\left(n+u^{2}\right)^{2}}+\frac{1}{4} \frac{u^{4}}{\left(n+u^{2}\right)^{2}}} .
\end{aligned}
$$

We derived Wilson confidence interval (also called score interval or also q-interval). Denote the center of the Wilson interval by symbol $c$. Since $c$ is the weighted mean of the values $\hat{p}$ and $\frac{1}{2}$, we get $\left|\frac{1}{2}-c\right|<\left|\frac{1}{2}-\hat{p}\right|$.

### 10.2 Confidence intervals for parameter $\lambda$

### 10.2.1 Standard confidence interval

Let $X_{1}, \ldots, X_{n}$ be a sample from $\operatorname{Po}(\lambda)$. Maximum likelihood estimator of the parameter $\lambda$ is $\hat{\lambda}=\bar{X}$. It is known that

$$
\mathrm{E} \bar{X}=\lambda, \quad \operatorname{var} \bar{X}=\lambda / n, \quad Z=\frac{\bar{X}-\lambda}{\sqrt{\lambda / n}} \xrightarrow{\mathrm{~d}} \mathrm{~N}(0,1) .
$$

Since $\bar{X} \xrightarrow{\mathrm{P}} \lambda$, we obtain

$$
\frac{\bar{X}-\lambda}{\sqrt{\bar{X} / n}} \xrightarrow{\mathrm{~d}} \mathrm{~N}(0,1) .
$$

From here it follows that the interval with endpoints

$$
\begin{equation*}
\bar{X} \pm u_{\alpha / 2} \sqrt{\bar{X} / n} \tag{10.3}
\end{equation*}
$$

is confidence interval for $\lambda$ with asymptotic confidence coefficient $1-\alpha$. It is called standard confidence interval.

### 10.2.2 Score confidence interval

If the true value of the parameter is $\lambda$, then it follows from the asymptotic normality of the variable $Z$ that

$$
\mathrm{P}\left(\frac{|\bar{X}-\lambda|}{\sqrt{\lambda / n}} \leq u_{\alpha / 2}\right) \rightarrow 1-\alpha
$$

Write $u=u_{\alpha / 2}$. Then the endpoints of the score confidence interval are roots of the equation

$$
\frac{|\bar{X}-\lambda|}{\sqrt{\lambda / n}}=u
$$

We write this equation in the form $\bar{X}^{2}-2 \bar{X} \lambda+\lambda^{2}=u \lambda / n$ and we get the solution

$$
\begin{equation*}
\lambda_{12}=\frac{1}{2}\left[2 \bar{X}+\frac{u^{2}}{n} \pm \sqrt{\left(2 \bar{X}+\frac{u^{2}}{n}\right)^{2}-4 \bar{X}^{2}}\right]=\bar{X}+\frac{u^{2}}{2 n} \pm \frac{u}{\sqrt{n}} \sqrt{\bar{X}+\frac{u^{2}}{4 n}} . \tag{10.4}
\end{equation*}
$$

### 10.2.3 Clopper-Pearson confidence interval

The sums of probabilities in the Poisson distribution can be calculated using the distribution function of the $\chi^{2}$ distribution. Remember that the density of $\chi_{n}^{2}$ distribution is

$$
\begin{equation*}
f_{n}(x)=\frac{1}{2^{n / 2} \Gamma(n / 2)} x^{n / 2-1} \mathrm{e}^{-x / 2}, \quad x>0 \tag{10.5}
\end{equation*}
$$

Integrating by parts it can be shown that

$$
\sum_{k=0}^{m} \frac{\lambda^{k}}{k!} \mathrm{e}^{-\lambda}=\int_{2 \lambda}^{\infty} f_{2 m+2}(x) \mathrm{d} x
$$

Assume that $X \sim \operatorname{Po}(\lambda)$. Then the Clopper-Pearson confidence interval for $\lambda$ based on $X$ is $\left(\lambda_{d}, \lambda_{u}\right)$, where the limits $\lambda_{d}$ and $\lambda_{u}$ are given by the conditions

$$
\mathrm{P}\left(X \geq x \mid \lambda=\lambda_{d}\right)=\alpha / 2, \quad \mathrm{P}\left(X \leq x \mid \lambda=\lambda_{u}\right)=\alpha / 2
$$

and $\lambda_{d}=0$ for $x=0$. Let $\chi_{\nu}^{2}(\alpha)$ be upper $\alpha$ percentile of $\chi_{\nu}^{2}$ distribution (critical value of the $\chi_{\nu}^{2}$ distribution on the level $\alpha$ ). Then the solution is

$$
\lambda_{d}=\left\{\begin{array}{ll}
0, & \text { for } x=0, \\
\frac{1}{2 n} \chi_{2 x}^{2}\left(1-\frac{\alpha}{2}\right), & \text { for } x \neq 0,
\end{array} \quad \lambda_{u}=\frac{1}{2 n} \chi_{2 x+2}^{2}\left(\frac{\alpha}{2}\right)\right.
$$

In the case that $X_{1}, \ldots, X_{n}$ is the sample from $\operatorname{Po}(\lambda)$, we define $X=\sum_{i=1}^{n} X_{i}$. Thus we have $X \sim \operatorname{Po}(n \lambda)$. The limit $\lambda_{u}$ on the basis $X$ is given by the condition

$$
\frac{\alpha}{2}=\mathrm{P}\left(X \leq x \mid \lambda=\lambda_{u}\right)=\mathrm{P}\left(\chi_{2 x+2}^{2} \geq 2 n \lambda_{u}\right)
$$

This gives $2 n \lambda_{u}=\chi_{2 x+2}^{2}(\alpha / 2)$, it means $\lambda_{u}=\frac{1}{2 n} \chi_{2 x+2}^{2}(\alpha / 2)$.

### 10.3 Tests $\chi^{2}$ when parameters are known

Let random vector $\boldsymbol{X}$ have the multinomial distribution. In view of (2.26) on p. 31 we can apply the central limit theorem. Define $\boldsymbol{Y}=\boldsymbol{D}^{-1} \boldsymbol{X}$. The vector $\boldsymbol{Y}$ has also asymptotically normal distribution because it arises by linear transformation from $\boldsymbol{X}$. Using results derived in section 2.9 on p. 30 we have $\mathbf{E} \boldsymbol{Y}=\left(\sqrt{n p_{1}}, \ldots, \sqrt{n p_{k}}\right)^{\prime}, \operatorname{var} \boldsymbol{Y}=\boldsymbol{Q}$. Applying theorem 3.8 on p. 39, we can see that $(\boldsymbol{Y}-\mathbf{E} \boldsymbol{Y})^{\prime}(\boldsymbol{Y}-\mathbf{E} \boldsymbol{Y})$ has asymptotically $\chi_{k-1}^{2}$ distribution, because the rank of the the matrix $\boldsymbol{Q}$ is $k-1$. Variable $(\boldsymbol{Y}-\mathbf{E} \boldsymbol{Y})^{\prime}(\boldsymbol{Y}-$ $E \boldsymbol{Y}$ ) is denoted as $\chi^{2}$ and it equals to

$$
\begin{equation*}
\chi^{2}=\sum_{i=1}^{k} \frac{\left(X_{i}-n p_{i}\right)^{2}}{n p_{i}} \tag{10.6}
\end{equation*}
$$

Variables $X_{i}$ are called empirical frequencies and $n p_{i}$ are theoretical frequencies. In some cases the value $\chi^{2}$ is calculated from (10.6) because it is important to know summands on the right hand side. The complete value $\chi^{2}$ can be calculated from the modified formula (10.6)

$$
\begin{equation*}
\chi^{2}=\frac{1}{n} \sum_{i=1}^{k} \frac{X_{i}^{2}}{p_{i}}-n \tag{10.7}
\end{equation*}
$$

Using variable $\chi^{2}$ defined in (10.6) and introduced in (10.7) we can test the hypothesis that the true values of probabilities of a multinomial distribution are equal to numbers $p_{1}, \ldots, p_{k}$. If we get $\chi^{2} \geq \chi_{k-1}^{2}(\alpha)$, we reject the hypothesis $H_{0}$. This Pearson $\chi^{2}$ test can be applied for testing regularity of dice, (where the probability should be $1 / 6$ for each possibility), for checking generators of random numbers and in many other cases.

It is necessary to emphasize that the test $\chi^{2}$ is asymptotic and so it can be recommended only if the sample size $n$ is sufficiently large. Modern computers enable to find the critical value using simulations.

Example 10.2 In the book Yule, Kendall (1950) are introduced results of 4096 throws with 12 dices. For each throw it was recorded how many six's were obtained. The results are introduced in table 10.1.

Table 10.1: Results of 4096 throws with 12 dices

|  | Number of 6 |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 and more | Total |
| $n_{i}$ | 447 | 1145 | 1181 | 796 | 380 | 115 | 24 | 8 | 4096 |
| $p_{i}$ | 0.112 | 0.269 | 0.296 | 0.197 | 0.089 | 0.028 | 0.007 | 0.001 | 1.000 |
| $n p_{i}$ | 459 | 1103 | 1213 | 809 | 364 | 116 | 27 | 5 | 4096 |

Probability of a 6 is $1 / 6$ and results are independent, number of 6 is random variable with binomial distribution $\operatorname{Bi}\left(12, \frac{1}{6}\right)$. Thus

$$
p_{i}=\binom{12}{i}\left(\frac{1}{6}\right)^{i}\left(\frac{5}{6}\right)^{12-i}, \quad i=0,1, \ldots, 12
$$

Using (10.6) or (10.7) we get $\chi^{2}=5.484$. Since this result is less than critical value $\chi_{7}^{2}(0.05)=14.07$, we cannot reject the hypothesis that the dices are regular.

### 10.4 Tests $\chi^{2}$ when parameters are not known

It happens frequently that the probabilities $p_{1}, \ldots, p_{k}$ depend on an unknown parameter $\boldsymbol{a}=\left(a_{1}, \ldots, a_{m}\right)^{\prime}$. We can write $p_{1}=p_{1}(\boldsymbol{a}), \ldots, p_{k}=p_{k}(\boldsymbol{a})$. Pro each $\boldsymbol{a}$ we must have

$$
p_{1}(\boldsymbol{a})+\cdots+p_{k}(\boldsymbol{a})=1
$$

If the functions $p_{i}(\boldsymbol{a})$ are sufficiently smooth then we obtain from here

$$
\begin{equation*}
\frac{\partial p_{1}(\boldsymbol{a})}{\partial a_{j}}+\cdots+\frac{\partial p_{k}(\boldsymbol{a})}{\partial a_{j}}=0, \quad j=1, \ldots, m \tag{10.8}
\end{equation*}
$$

This relation is used for derivation of other formulas. Instead of (10.7) we have now

$$
\begin{equation*}
\chi^{2}(\boldsymbol{a})=\frac{1}{n} \sum_{i=1}^{k} \frac{X_{i}^{2}}{p_{i}(\boldsymbol{a})}-n . \tag{10.9}
\end{equation*}
$$

For estimating $\boldsymbol{a}$ similar procedure can be used as it was least squares method in the case of linear model. Let $\boldsymbol{a}^{*}$ be the value of the parameter $\boldsymbol{a}$, which minimizes (10.9). Then $\boldsymbol{a}^{*}$ is called estimator of the parameter $\boldsymbol{a}$ using method of minimal $\chi^{2}$. We get it solving the system of equation

$$
\begin{equation*}
\frac{\partial \chi^{2}(\boldsymbol{a})}{\partial a_{j}}=-\frac{1}{n} \sum_{i=1}^{k} \frac{X_{i}^{2}}{p_{i}^{2}(\boldsymbol{a})} \frac{\partial p_{i}(\boldsymbol{a})}{\partial a_{j}}=0, \quad j=1, \ldots, m \tag{10.10}
\end{equation*}
$$

Usually, it is difficult to solve this system and so another procedure was looked for. Instead of (10.9) we can differentiate relation

$$
\begin{equation*}
\chi^{2}(\boldsymbol{a})=\sum_{i=1}^{k} \frac{\left[X_{i}-n p_{i}(\boldsymbol{a})\right]^{2}}{n p_{i}(\boldsymbol{a})} . \tag{10.11}
\end{equation*}
$$

This leads to

$$
\begin{equation*}
-\frac{1}{2} \frac{\partial \chi^{2}(\boldsymbol{a})}{\partial a_{j}}=\sum_{i=1}^{k}\left(\frac{X_{i}-n p_{i}(\boldsymbol{a})}{p_{i}(\boldsymbol{a})}+\frac{\left[X_{i}-n p_{i}(\boldsymbol{a})\right]^{2}}{2 n p_{i}^{2}(\boldsymbol{a})}\right) \frac{\partial p_{i}(\boldsymbol{a})}{\partial a_{j}}=0 \tag{10.12}
\end{equation*}
$$

for $j=1, \ldots, m$. It is the same as the system (10.10). It can be shown that with growing $n$ the influence of the second member on the right hand side of formula (10.12) has less influence. If we leave it out, we come to a new system of equations

$$
\sum_{i=1}^{k} \frac{X_{i}-n p_{i}(\boldsymbol{a})}{p_{i}(\boldsymbol{a})} \frac{\partial p_{i}(\boldsymbol{a})}{\partial a_{j}}=0, \quad j=1, \ldots, m
$$

Using the relation (10.8), we have finally the system

$$
\begin{equation*}
\sum_{i=1}^{k} \frac{X_{i}}{p_{i}(\boldsymbol{a})} \frac{\partial p_{i}(\boldsymbol{a})}{\partial a_{j}}=0, \quad j=1, \ldots, m \tag{10.13}
\end{equation*}
$$

The solution of the system (10.13) denote $\hat{\boldsymbol{a}}$. It is called estimator of parameter $\boldsymbol{a}$ by modified method of minimum $\chi^{2}$.

System (10.13) is related to problem of estimating parameter $\boldsymbol{a}$ by maximum likelihood method. Likelihood function of multinomial distribution is

$$
f(\boldsymbol{a})=\frac{n!}{X_{1}!\ldots X_{k}!}\left[p_{1}(\boldsymbol{a})\right]^{X_{1}} \ldots\left[p_{k}(\boldsymbol{a})\right]^{X_{k}} .
$$

Thus the logarithmic likelihood function is

$$
L(\boldsymbol{a})=\ln f(\boldsymbol{a})=\ln \frac{n!}{X_{1}!\ldots X_{k}!}+\sum_{i=1}^{k} X_{i} \ln p_{i}(\boldsymbol{a}) .
$$

Likelihood equations are

$$
\frac{\partial L(\boldsymbol{a})}{\partial a_{j}}=0 \quad \text { for } j=1, \ldots, m
$$

Estimator of the parameter $\boldsymbol{a}$ using maximum likelihood method is solution of the system of equations

$$
\begin{equation*}
\sum_{i=1}^{k} \frac{X_{i}}{p_{i}(\boldsymbol{a})} \frac{\partial p_{i}(\boldsymbol{a})}{\partial a_{j}}=0 \quad \text { for } j=1, \ldots, m \tag{10.14}
\end{equation*}
$$

which is the same as the system of equations (10.13) for estimator $\boldsymbol{a}$ by modified method of minimum $\chi^{2}$.

Theorem 10.3 Let $m<k-1$ and assume that for all points a from nondegenerated finite closed interval $A z \mathbb{R}_{m}$ hold:
(1) $p_{1}(\boldsymbol{a})+\cdots+p_{k}(\boldsymbol{a})=1$.
(2) There exists such $c>0$, that $p_{i}(\boldsymbol{a})>c^{2}$ for $i=1, \ldots, k$.
(3) Every function $p_{i}(\boldsymbol{a})$ has continuous derivatives

$$
\frac{\partial p_{i}(\boldsymbol{a})}{\partial a_{j}} \quad \text { and } \quad \frac{\partial^{2} p_{i}(\boldsymbol{a})}{\partial a_{j} \partial a_{s}} \quad \text { for } \quad j, s=1, \ldots, m
$$

(4) Matrix $\left(\frac{\partial p_{i}(\boldsymbol{a})}{\partial a_{j}}\right)$, which is of type $k \times m$, has rank $m$.

Let $\boldsymbol{a}^{0}$ be inner point of $A$. Denote $p_{i}^{0}=p_{i}\left(\boldsymbol{a}^{0}\right)$. Let $\boldsymbol{X}=\left(X_{1}, \ldots, X_{k}\right)^{\prime}$ have multinomial distribution with parameters $n, p_{1}^{0}, \ldots, p_{k}^{0}$. Then in the case $n \rightarrow \infty$ there exist such sequences of positive numbers $\varepsilon_{n} \rightarrow 0$ and $\delta_{n} \rightarrow 0$, that the system (10.13) has with probability at least $1-\varepsilon_{n}$ one root $\hat{\boldsymbol{a}}_{n}$ such that $\left|\hat{\boldsymbol{a}}_{n}-\boldsymbol{a}^{0}\right|<\delta_{n}$. If we insert this root into (10.14) [or equivalently to (10.13)], the variable $\chi^{2}\left(\hat{\boldsymbol{a}}_{n}\right)$ for $n \rightarrow \infty$ has asymptotically $\chi_{k-m-1}^{2}$ distribution.

Proof. See Anděl (1978) or Cramér (1946).
Let us remark that assumption (4) excludes to introduce superfluous parameters $a_{i}$ into model. Analogous theorem can be proved also for other kind of estimators, see Rao 1978. But there exist nice estimators of the parameter $\boldsymbol{a}$ which do not satisfy assumptions of theorem 10.3. Typically $\chi^{2}$ test is used as test for distribution and as the test of independence in contingency tables. We shall introduce these methods. Also here it is necessary to have theoretical frequencies $n p_{i}(\hat{\boldsymbol{a}})$ sufficiently large.

### 10.5 Test of independence

Let the random vector $\boldsymbol{X}=(Y, Z)^{\prime}$ have discrete distribution, variable $Y$ takes values $1, \ldots, r$ and variable $Z$ values $1, \ldots, c$. We shall write

$$
p_{i j}=\mathrm{P}(Y=i, Z=j), \quad p_{i .}=\sum_{j} p_{i j}, \quad p_{\cdot j}=\sum_{i} p_{i j}
$$

Assume that we have sample of size $n$ from this distribution. Let $n_{i j}$ be number of the cases when the pair $(i, j)$ appeared in the sample. Random variables $n_{i j}$ then have simultaneous multinomial distribution with parameter $n$ and with probabilities $p_{i j}$. There is a difference in comparison with section 10.4, namely that probabilities $p_{i j}$ as well as empirical frequencies $n_{i j}$ are written as matrices instead of vectors. Matrix $\left(n_{i j}\right)$ is called contingency table. Further we write

$$
n_{i .}=\sum_{j} n_{i j}, \quad n_{\cdot j}=\sum_{i} n_{i j} .
$$

Clearly it holds

$$
n=\sum_{i} n_{i .}=\sum_{j} n_{. j}=\sum_{i} \sum_{j} n_{i j} .
$$

Numbers $p_{i .}$ and $p_{. j}$ are called marginal probabilities and values $n_{i}$. and $n_{. j}$ are marginal frequencies. Matrix of probabilities $\left(p_{i j}\right)$ and the contingency table $\left(n_{i j}\right)$ are introduced in tab. 10.2.

Table 10.2: Matrix of probabilities and contingency table

Matrix of probabilities

|  | $Z$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| $Y$ | 1 | $\cdots$ | $c$ | $\Sigma$ |
| 1 | $p_{11}$ | $\cdots$ | $p_{1 c}$ | $p_{1 .}$ |
| $\cdots$ | $\cdots$ | $\cdots$ | $\cdots$ | $\cdots$ |
| $\cdots$ | $\cdots$ |  |  |  |
| $r$ | $p_{r 1}$ | $\cdots$ | $p_{r c}$ | $p_{r .}$ |
| $\Sigma$ | $p_{.1}$ | $\cdots$ | $p_{. c}$ | 1 |

Contingency table

|  | $Z$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| $Y$ | 1 | $\cdots$ | $c$ | $\Sigma$ |
| 1 | $n_{11}$ | $\cdots$ | $n_{1 c}$ | $n_{1 .}$ |
| $\cdots$ | $\cdots$ | $\cdots$ | $\cdots$ | $\cdots$ |
| $\cdots$ | $\cdots$ |  |  |  |
| $r$ | $n_{r 1}$ | $\cdots$ | $n_{r c}$ | $n_{r .}$ |
| $\Sigma$ | $n_{.1}$ | $\cdots$ | $n_{. c}$ | $n$ |

In practical situations the contingency table arises in the following way. We follow two characteristics. They can be discrete and have only a few values (man - woman, blood group $0-\mathrm{A}-\mathrm{B}-\mathrm{AB}$ ) or we prepare only some categories. In many cases we give numbers $1,2, \ldots$ only as marks, but they are not exact values.

The most frequent problem solved in contingency tables is testing hypothesis that the variables $Y$ and $Z$ are independent. Before derivation of the test independence, we prove an auxiliary assertion.

Theorem 10.4 Variables $Y$ and $Z$ are independent if and only if for all pairs $(i, j)$ the relation $p_{i j}=p_{i . p} p_{. j}$ holds.

Proof. It is known that $Y$ and $Z$ are independent if and only if $\mathrm{P}(Y \in A, Z \in B)=$ $\mathrm{P}(Y \in A) \mathrm{P}(Z \in B)$ for arbitrary sets $A \subset\{1, \ldots, r\}, B \subset\{1, \ldots, c\}$. If we choose $A=\{i\}, B=\{j\}$, then it follows that in the case of independence $Y$ and $Z$ we must have $p_{i j}=p_{i .} p_{. j}$. Choose $A=\{1,2\}, B=\{1,2,3\}$. The general case is similar. We have

$$
\begin{aligned}
\mathrm{P}(Y \in A, Z \in B) & =\sum_{i=1}^{2} \sum_{j=1}^{3} p_{i j}=\sum_{i=1}^{2} \sum_{j=1}^{3} p_{i .} p_{. j} \\
& =\left(\sum_{i=1}^{2} p_{i .}\right)\left(\sum_{j=1}^{3} p_{. j}\right)=\mathrm{P}(Y \in A) P(Z \in B) .
\end{aligned}
$$

Thus the hypothesis of independence $H_{0}$ can be written in the form

$$
H_{0}: p_{i j}=p_{i .} p_{. j}, \quad i=1, \ldots, r ; j=1, \ldots, c
$$

It means that probabilities $p_{i j}$ of multinomial distribution are functions of smaller number of unknown parameters, namely of marginal probabilities $p_{i .}$ a $p_{. j}$. But the marginal probabilities are not independent, since

$$
\sum_{i} p_{i .}=\sum_{j} p_{\cdot j}=1
$$

If we wish to fulfil condition (4) from theorem 10.3, then we cannot include probabilities $p_{r \text {. and }} p_{. c}$ among unknown parameters, because they can be calculated from other probabilities. Thus we have $m=r-1+c-1=r+c-2$ unknown parameters. However, we consider only situations where all marginal probabilities are positive. Otherwise we would skip some rows or some columns.

Unknown parameters $p_{1 .}, \ldots, p_{r-1, .}$ and $p_{.1}, \ldots, p_{., c-1}$ can be calculated from the system (10.13). Instead of $X_{i}$ we have here variables $n_{i j}$. We obtain

$$
\begin{equation*}
\sum_{j=1}^{c}\left(\frac{n_{i j}}{p_{i .}}-\frac{n_{r j}}{p_{r .}}\right)=0, \quad i=1, \ldots, r-1 \tag{10.15}
\end{equation*}
$$

and

$$
\begin{equation*}
\sum_{i=1}^{r}\left(\frac{n_{i j}}{p_{. j}}-\frac{n_{i c}}{p_{. c}}\right)=0, \quad j=1, \ldots, c-1, \tag{10.16}
\end{equation*}
$$

since we have for $h=1, \ldots, r-1$ that

$$
\frac{\partial p_{i . p_{. j}}}{\partial p_{h .}}=\left\{\begin{aligned}
p_{\cdot j} & \text { for } i=h \\
-p_{\cdot j} & \text { for } i=r \\
0 & \text { in other cases }
\end{aligned}\right.
$$

Similar result can be obtained for partial derivatives with respect to $p_{. l}$. Formula (10.15) holds also for $i=r$ and (10.16) holds also for $j=c$. Instead of (10.15) we can write

$$
\begin{equation*}
\frac{n_{i .}}{p_{i .}}-\frac{n_{r .}}{p_{r .}}=0, \quad i=1, \ldots, r . \tag{10.17}
\end{equation*}
$$

From here we get

$$
n_{i .}=\frac{n_{r .}}{p_{r .}} p_{i .}, \quad i=1, \ldots, r .
$$

Summing over $i$ we have $n=n_{r .} / p_{r .}$, so that estimator for $p_{r .}$ is $\hat{p}_{r .}=n_{r .} / n$. Finally, inserting into (10.17) we have estimators

$$
\hat{p}_{i .}=\frac{n_{i .}}{n}, \quad i=1, \ldots, r .
$$

Similarly can be solved (10.16) and the result is

$$
\hat{p}_{. j}=\frac{n_{. j}}{n}, \quad j=1, \ldots, c
$$

Theorem 10.3 ensures that the variable

$$
\begin{equation*}
\chi^{2}=\sum_{i=1}^{r} \sum_{j=1}^{c} \frac{\left(n_{i j}-\frac{n_{i . n_{. j}}}{n}\right)^{2}}{\frac{n_{i .} n_{. j}}{n}} \tag{10.18}
\end{equation*}
$$

has asymptotically distribution $\chi^{2}$, and its number of degrees of freedom is

$$
r c-(r+c-2)-1=(r-1)(c-1) .
$$

If we get $\chi^{2} \geq \chi_{(r-1)(c-1)}^{2}(\alpha)$, we rejct the hypothesis $H_{0}$ that the variables $Y$ and $Z$ are independent. Of course, the theoretical frequencies $n_{i .} n_{. j} / n$ must be sufficiently large.

Example 10.5 U 6800 mu byla zjiovna barva o a barva vlas (viz Yule, Kendall 1950). Vsledky jsou uvedeny v tab. 10.3.

Table 10.3: Colour of eyes and hair

|  | Color of hair |  |  |  |  |
| :--- | ---: | ---: | ---: | ---: | ---: |
| Colour of eyes | Fair | Chestnut | Black | Red-haired | Total |
| Blue | 1768 | 807 | 189 | 47 | 2811 |
| Green | 946 | 1387 | 746 | 53 | 3132 |
| Brown | 115 | 438 | 288 | 16 | 857 |
| Total | 2829 | 2632 | 1223 | 116 | 6800 |

We obtained $\chi^{2}=1073.508, d f=6, p$-value $<2.2 e-16$.
Because of small $p$-value we reject the hypothesis that color of eyes and color of hair in men population are independent variables.

## $10.6 \quad 2 \times 2$ tables

### 10.6.1 Test $\chi^{2}$

Test of independence in contingency table $2 \times 2$ can be based on formula (10.18). In the case $r=c=2$ we get

$$
\chi^{2}=\sum_{i=1}^{2} \sum_{j=1}^{2} \frac{\left(n_{i j}-\frac{n_{i \cdot n_{\cdot j}}}{n}\right)^{2}}{\frac{n_{i \cdot .} n_{\cdot j}}{n}}=\frac{1}{n} \sum_{i=1}^{2} \sum_{j=1}^{2} \frac{\left(n n_{i j}-n_{i \cdot} n_{. j}\right)^{2}}{n_{i \cdot n} n_{\cdot j}} .
$$

For every pair $(i, j)$ we have

$$
\left(n n_{i j}-n_{i .} n_{. j}\right)^{2}=\left(n_{11} n_{22}-n_{12} n_{21}\right)^{2},
$$

and thus

$$
\begin{align*}
\chi^{2} & =\frac{\left(n_{11} n_{22}-n_{12} n_{21}\right)^{2}}{n} \sum_{i=1}^{2} \sum_{j=1}^{2} \frac{1}{n_{i . n} n_{. j}}=\frac{\left(n_{11} n_{22}-n_{12} n_{21}\right)^{2}}{n} \frac{n^{2}}{n_{1 .} n_{2 .} n_{.1} n_{.2}} \\
& =n \frac{\left(n_{11} n_{22}-n_{12} n_{21}\right)^{2}}{n_{1 .} n_{2 .} n_{.1} n_{.2}} \tag{10.19}
\end{align*}
$$

If hypothesis of independence is valid, then the statistic $\chi^{2}$ has asymptotically $\chi_{1}^{2}$ distribution.

### 10.6.2 Odds ratio

Another approach to $2 \times 2$ tables can be motivated in the following example. Assume that a man has a disease. He checks up that this disease had 18 men. Some of them were cured, some not. Some are alive, some not. Data are in tab. 10.4.

Table 10.4: Data on sick men

|  | Alive | Dead | Total |
| :--- | :---: | :---: | :---: |
| Cured | 5 | 6 | 11 |
| Not cured | 3 | 4 | 7 |
| Total | 8 | 10 | 18 |

The man can think as follows. If he cures, his chance to alive can be estimated 5:6. If he does not cure, then the chance to alive is $3: 4$. Using division we find the better possibility: the expression

$$
\frac{5: 6}{3: 4}=\frac{5 \times 4}{6 \times 3}=\frac{20}{18}
$$

is larger than 1 , and so it will be better to cure. Such expression is generally

$$
b=\frac{n_{11} n_{22}}{n_{12} n_{21}}
$$

and we call it odds ratio. Since $n_{i j} / n$ is estimator of probability $p_{i j}, b$ is estimator of $C$.

$$
\beta=\frac{p_{11} p_{22}}{p_{12} p_{21}} .
$$

Theorem 10.6 In $2 \times 2$ table the equality $\beta=1$ holds if and only if $p_{i j}=p_{i .} p_{. j}$ for all couples $(i, j), i \neq j$.

Proof. If $p_{i j}=p_{i .} p_{. j}, i \neq j$ for all couples $(i, j)$, then we get immediately that $\beta=1$.
Now, assume that $\beta=1$ holds. If we denote $p_{11} / p_{12}=\lambda$, then from $\beta=1$ it follows that also $p_{21} / p_{22}=\lambda$. From here

$$
p_{11}=\lambda p_{12}, \quad p_{21}=\lambda p_{22}
$$

The corresponding table of probabilities can be written as tab. 10.5.

Table 10.5: Table of probabilities

$$
\begin{array}{|ll|l|}
\hline \lambda p_{12} & p_{12} & (\lambda+1) p_{12} \\
\lambda p_{22} & p_{22} & (\lambda+1) p_{22} \\
\hline & & (\lambda+1) p_{.2} \\
\hline
\end{array}
$$

Since $(\lambda+1) p_{.2}=1$, we get that $\lambda+1=1 / p_{.2}$. Because $(\lambda+1) p_{12}=p_{1 .}$, we see that $p_{12}=p_{1 . p .2}$. Similarly from the relation $(\lambda+1) p_{22}=p_{2}$. it follows that $p_{22}=p_{2 .} p_{.2}$. Finally we get

$$
\begin{aligned}
& p_{11}=p_{1 .}-p_{12}=p_{1 .}-p_{1 .} p_{.2}=p_{1 .}\left(1-p_{.2}\right)=p_{1 .} p_{.1}, \\
& p_{21}=p_{2 .}-p_{22}=p_{2 .}-p_{2 .} p_{.2}=p_{2 .}\left(1-p_{.2}\right)=p_{2 . p_{.1}} .
\end{aligned}
$$

The dependence of variables will be larger if $\beta$ is far from 1 . However, do not forget that $0 \leq \beta \leq \infty$. It was proved (see Edwards 1963), that every reasonable measure of dependence in $2 \times 2$ table must be function of parameter $\beta$, in the sample the function $b$.

Values $\beta$ are not symmetric around point 1 . From this reason the characteristics logarithmic interaction $d$ and theoretic logarithmic interaction $\delta$ were proposed, which are defined as

$$
d=\ln b, \quad \delta=\ln \beta .
$$

It was proved (see Goodman 1964), that variable

$$
D=\frac{d-\delta}{\sqrt{\frac{1}{n_{11}}+\frac{1}{n_{12}}+\frac{1}{n_{21}}+\frac{1}{n_{22}}}}
$$

has asymptotically distribution $\mathrm{N}(0,1)$. If we want to test hypothesis independence $H_{0}$ using this method, we insert $\delta=0$ and $H_{0}$ is rejected in the case that $|D| \geq u\left(\frac{\alpha}{2}\right)$. It is important that using $D$ it is possible to test $H_{0}$ also against one-sided alternatives. Again, the test is asymptotic and should be used when the frequencies are sufficiently large.

Let us return to the parameter $\beta$. It can be expressed in the form

$$
\beta=\frac{p_{11} p_{22}}{p_{12} p_{21}}=\frac{p_{11}\left(1-p_{1 .}-p_{.1}+p_{11}\right)}{\left(p_{1 .}-p_{11}\right)\left(p_{.1}-p_{11}\right)} .
$$

Probability $p_{11}$ is function of $\beta, p_{1 .}, p_{.1}$. The same holds also for other probabilities $p_{i j}$. Conditional distribution of frequencies $n_{i j}$ for given marginal frequencies depends only on $\beta$. Then it suffices to know only the frequency $n_{11}$ since other frequencies $n_{i j}$ are determined. Conditional probability $\mathrm{P}\left(n_{11}=t\right)$ depends only on $n_{1 .}, n_{.1}, n, \beta$. Fisher (1935) derived, that this probability is given by non-central hypergeometric distribution

$$
\begin{equation*}
\mathrm{P}\left(n_{11}=t \mid n_{1 .}, n_{.1}, n, \beta\right)=\frac{\binom{n_{1 .}}{t}\binom{n-n_{1 .}}{n_{.1}-t} \beta^{t}}{\sum_{u}\binom{n_{1 .}}{u}\binom{n-n_{1 .}}{n_{.1}-u} \beta^{u}} \tag{10.20}
\end{equation*}
$$

Using formula (10.20) it is possible to obtain conditional confidence interval for $\beta$ (see Agresti 2002, p. 99). The value $\hat{\beta}$, which maximizes probability (10.20), is called conditional maximum likelihood estimator of the parameter $\beta$. The estimator

$$
b=\left(n_{11} n_{22}\right) /\left(n_{12} n_{21}\right)
$$

mentioned above is unconditional maximum likelihood estimator of the parameter $\beta$, since it is based on maximum likelihood estimators of probabilities $p_{i j}$ of this multinomial distribution.

Example 10.7 In England it was investigated if the weight of criminals and their intellect are independent variables. Data (see Yule, Kendall 1950) are presented in tab. 10.6.

We test the hypothesis $H_{0}: \delta=0$ against $H_{1}: \delta \neq 0$. For $\delta=0$ we get $D=-3,03$. Since $|D| \geq u(0,025)=1,96$, we reject the hypothesis $H_{0}$.

Table 10.6: Data on criminals

| Intellect | Weight <br> over 150 lb |  | Total |
| :--- | :---: | :---: | :---: |
| Normal | 272 | 124 | 396 |
| Lowered | 82 | 15 | 97 |
| Total | 354 | 139 | 493 |

We compare this result with the classical Pearson test. We get $\chi^{2}=9,67, p$-value $=0.002$. Since $p$-value is smaller than 0.05 , hypothesis of independence would be rejected also by this test. Notice that $D^{2}=9,18$ is not very different from the value $\chi^{2}=9,67$. $\diamond$

The application of the odds-ratio can also sometimes give paradoxical results. Consider again the example presented at the beginning of this section. Let us imagine that a woman is ill. She would have for disposal data on 23 ill women (see tab. 10.7).

Table 10.7: Data on sick women

|  | Alive | Dead | Total |
| :--- | :---: | :---: | :---: |
| Cured | 6 | 3 | 9 |
| Not cured | 9 | 5 | 14 |
| Total | 15 | 8 | 23 |

Table 10.8: Data on sick people

|  | Alive | Dead | Total |
| :--- | :---: | :---: | :---: |
| Cured | 11 | 9 | 20 |
| Not cured | 12 | 9 | 21 |
| Total | 23 | 18 | 41 |

This woman calculates odds ratio $b=(6: 3) /(9: 5)=30 / 27$. Since $b>1$, for her it would be better to cure.

If the data are collapsed, we obtain tab. 10.8.
In the collapsed table we have $b=99 / 108<1$. This leads to the surprising conclusion that for men and women it is better to cure but for people not to cure. This is Simpson paradox.

### 10.6.3 Fisher's factorial test

If the frequencies are small and it is not appropriate to use in the $2 \times 2$ the limiting distribution $\chi_{1}^{2}$, in such a case is applied the following method. Probability that given $n$ frequencies $n_{11}, n_{12}, n_{21}, n_{22}$, will be realized is

$$
P\left(n_{11}, n_{12}, n_{21}, n_{22}\right)=\frac{n!}{n_{11}!n_{12}!n_{21}!n_{22}!} p_{11}^{n_{11}} p_{12}^{n_{12}} p_{21}^{n_{21}} p_{22}^{n_{22}}
$$

Assume that the hypothesis independence $H_{0}: p_{i j}=p_{i .} p_{. j}$ is true. Denote

$$
Q=p_{1 .}^{n_{1}} p_{2 .}^{n_{2} .} p_{.1}^{n_{1}{ }_{1}} p_{.2}^{n .2} .
$$

Then under $H_{0}$ we get

$$
\begin{equation*}
P\left(n_{11}, n_{12}, n_{21}, n_{22}\right)=\frac{n!}{n_{11}!n_{12}!n_{21}!n_{22}!} Q . \tag{10.21}
\end{equation*}
$$

Probability that a table with marginal frequencies $n_{1 .}, n_{2 .}, n_{.1}, n_{.2}$ arizes, is equal to

$$
R=\sum_{i=\max \left(0, n_{.1}-n_{2 .}\right)}^{\min \left(n_{1 .,} n_{.1}\right)} P\left(i, n_{1 .}-i, n_{.1}-i, i+n_{2 .}-n_{.1}\right) .
$$

Inserting from (10.21) we obtain

$$
R=Q \frac{n!}{n_{1}!n_{2}!} \sum_{i=\max \left(0, n_{.1}-n_{2 .}\right)}^{\min \left(n_{1 ., n .1}\right)}\binom{n_{1 .}}{i}\binom{n_{2 .}}{n_{.1}-i} .
$$

But for arbitrary nonnegative integers $r, s$ and $k$ fulfilling condition $r+s \geq k$ comparing coefficients by $t^{k}$ in the formula

$$
(1+t)^{r}(1+t)^{s}=(1+t)^{r+s}
$$

we get Vandermond convolutory formula

$$
\sum_{i=\max (0, k-s)}^{\min (r, k)}\binom{r}{i}\binom{s}{k-i}=\binom{r+s}{k} .
$$

This gives

$$
R=Q \frac{(n!)^{2}}{n_{1}!n_{2}!n_{.1}!n_{.2}!} .
$$

Conditional probability $P$, that in given table with marginal frequencies $n_{1 .}, n_{2 .}, n_{.1}, n_{.2}$ a table with frequencies $n_{11}, n_{12}, n_{21}, n_{22}$ arises, is equal

$$
\begin{align*}
P & =\frac{P\left(n_{11}, n_{12}, n_{21}, n_{22}\right)}{R} . \\
P & =\frac{n_{1}!n_{2}!n_{.1}!n_{22}!}{n!n_{11}!n_{12}!n_{21}!n_{22}!} . \tag{10.22}
\end{align*}
$$

Sometimes $P$ is introduced in an equivalent form

$$
P=\frac{\binom{n_{1 .}}{n_{11}}\binom{n_{2 .}}{n_{21}}}{\binom{n}{n_{.1}}}
$$

An advantage of the conditional probability $P$ is that it does not contain any unknown parameters and so we have no problem in estimating them.

The testing procedure depends on the problem if we want to test hypothesis $H_{0}$ against one-sided or two-sided alternative. Let $d$ be the logarithmic interaction of he given table. If we test $H_{0}$ against the alternative $H_{1}: \delta<0$ (where $\delta$ is the theoretical logarithmic interaction), probabilities $P$ are summed for the tables which have the same marginal frequencies as the original table and their logarithmic interactions are smaller or equal number $d$. If this sum is smaller or equal $\alpha, H_{0}$ is rejected.

When testing $H_{0}$ against $H_{1}: \delta>0$ we add probabilities $P$ of the tables with the same marginal frequencies as the original table, the logarithmic interactions having larger or equal $d$. If the sum of probabilities smaller or equal $\alpha, H_{0}$ is rejected. The two-sided test can be done analogously.

This test was derived by R. A. Fisher. Since calculation of probabilities is based on formula (10.22), the test is called Fisher's factorial test. The actual level of the test is usually less than $\alpha$. Sometimes it is called Fisher's exact test.

Example 10.8 Some 24 randomly chosen students were asked if they have good or bad results in maths and if the study music. Denote $M+$ good and $M-$ bad result in math and denote $H+$ (and $H-$ ) the case when the student studies (or not studies) music. The results are in tab. 10.9.

Table 10.9: Mathematics and music

|  | $H+$ | $H-$ | Celkem |
| :--- | :---: | :---: | :---: |
| $M+$ | 6 | 4 | 10 |
| $M-$ | 1 | 13 | 14 |
| Total | 7 | 17 | 24 |

We should test the hypothesis that the results in math and study of music are independent.

We find all tables with the same marginal frequencies as the starting table (see tab. 10.10). Then we calculate their logarithmic interactions $d$ and Fisher's probabilities $P$.

You can see that the sum of all probabilities $P$ is really 1. We do two-sided test and so we sum the probabilities $P$, which correspond to tables with absolute value of logarithmic interaction larger or equal to the number 2.97. We get the number

$$
0.009916+0.008495+0.000347=0.018758
$$

The sum 0.018758 is not larger than $\alpha=0.05$, and so we reject the hypothesis about independence. We emphasize that this does not prove the causality.

Table 10.10: Set of contingency tables with the same marginal frequencies as tab. 10.9

$$
\begin{aligned}
& P=0.009916 \quad P=0.086766 \quad P=0.260297 \quad P=0.347063
\end{aligned}
$$

$$
\begin{aligned}
& P=0.220858 \quad P=0.066258 \quad P=0.008495 \quad P=0.000347
\end{aligned}
$$

## Chapter 11

## Paired problem

### 11.1 Paired t test

Consider the random sample $\left(Y_{1}, Z_{1}\right)^{\prime}, \ldots,\left(Y_{n}, Z_{n}\right)^{\prime}$ from a twodimensional distribution with vector of mean values $\left(\mu_{1}, \mu_{2}\right)^{\prime}$. We want to test the hypothesis $H_{0}: \mu_{1}-\mu_{2}=\Delta$ against alternative $H_{1}: \mu_{1}-\mu_{2} \neq \Delta$, where $\Delta$ is given number (mostly zero). Define $X_{i}=$ $Y_{i}-Z_{i}, i=1, \ldots, n$. Variables $X_{1}, \ldots, X_{n}$ are independent and identically distributed. Assume that $X_{i} \sim \mathrm{~N}\left(\mu, \sigma^{2}\right)$. Obviously $\mu=\mu_{1}-\mu_{2}$. Now, we have to test $H_{0}^{\prime}: \mu=\Delta$ against $H_{1}^{\prime}: \mu \neq \Delta$ and the problem is changed to the one sample $t$ test, which is in this case called paired $t$ test.

The hypothesis $H_{0}^{\prime}$, and also the hypothesis $H_{0}$, will be rejected at level $\alpha$,if $\mid \bar{X}-$ $\Delta \mid \sqrt{n} / S \geq t_{n-1}(\alpha)$, where $S$ is calculated from z $X_{1}, \ldots, X_{n}$. The most frequent case is the situation when $\left\{\left(Y_{i}, Z_{i}\right)^{\prime}\right\}$ is the sample from a two-dimensional normal normal distribution. This assumption ensures that the paired $t$ test can be used. The paired $t$ test is used usually in situations when we have on each from $n$ objects measured two variables and individual objects are considered as independent but not the measurements on the same object.

Confidence interval for $\Delta$ can be derived from the fact that

$$
\mathrm{P}\left\{|\bar{X}-\Delta| \sqrt{n} / S \leq t_{n-1}(\alpha)\right\}=1-\alpha .
$$

Thus confidence interval for $\Delta$ has endpoints

$$
\bar{X} \mp \frac{1}{\sqrt{n}} S t_{n-1}(\alpha) .
$$

Example 11.1 It should be decided if two front tyres go down equally fast. Six new cars were chosen and after some time it were measured how much two front tyres went down.

Differences in go down can be considered as independent random variables with distribution $\mathrm{N}\left(\mu, \sigma^{2}\right)$. If both tyres go down equally fast, the hypothesis $H_{0}: \mu=0$ is valid. We have $n=6, \Delta=0, \bar{X}=0,0833, S^{2}=0,0377, T=1,0518$. Since $1,0518<t_{5}(0,05)=2,571$, we cannot reject the hypothesis that both front tyre go down equally fast.

Table 11.1: Tyres go down

| Number of car | 1 | 2 | 3 | 4 | 5 | 6 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| right tyre : | 1.8 | 1.0 | 2.2 | 0.9 | 1.5 | 1.6 |
| left tyre : | 1.5 | 1.1 | 2.0 | 1.1 | 1.4 | 1.4 |
| Difference | 0.3 | -0.1 | 0.2 | -0.2 | 0.1 | 0.2 |

### 11.2 Paired sign test

Let $\left(Y_{1}, Z_{1}\right)^{\prime}, \ldots,\left(Y_{n}, Z_{n}\right)^{\prime}$ be a random sample from a two-dimensional distribution. Define $X_{i}=Y_{i}-Z_{i}, i=1, \ldots, n$. Assume that the variables $X_{i}$ have a continuous distribution with a unique median $\tilde{x}$. We should test the hypothesis $H_{0}$, that $\tilde{x}=x_{0}$, where $x_{0}$ is a given number. Thus the problem is transformed to one-dimensional sigh test. The procedure is called paired sign test.

### 11.3 Paired Wilcoxon test

Consider a random sample $\left(Y_{1}, Z_{1}\right)^{\prime}, \ldots,\left(Y_{n}, Z_{n}\right)^{\prime}$ from a two-dimensional distribution. Denote $X_{i}=Y_{i}-Z_{i}, i=1, \ldots, n$. Assume that the variables $X_{i}$ have a continuous distribution with a density which is symmetric around the point $a$ and positive in its neighbourhood. Then $a$ is a median of this distribution. We want to test the hypothesis $H_{0}$, that $a=x_{0}$, where $x_{0}$ is a given number. The problem is transformed to one-sample Wilcoxon test. This procedure is called one-sample Wilcoxon test.

### 11.4 Spearman correlation coefficient

We have seen that the analysis of sample correlation coefficient has the assumption that the sample is from the normal distribution. However, it happens quite often that this assumption is not valid. And sometimes in the random sample $\left(X_{1}, Y_{1}\right)^{\prime}, \ldots,\left(X_{n}, Y_{n}\right)^{\prime}$ the values of the mentioned random variables it is not possible to determine, only their order is in our disposal. But if the order $X$-values and $Y$-values are very similar it indicates some dependence between $X_{i}$ a $Y_{i}$.

Assume that $\left(X_{1}, Y_{1}\right)^{\prime}, \ldots,\left(X_{n}, Y_{n}\right)^{\prime}$ is the sample from a continuous two-dimensional distribution. Let $R_{1}, \ldots, R_{n}$ be orders of variables $X_{1}, \ldots, X_{n}$ and $Q_{1}, \ldots, Q_{n}$ orders of variables $Y_{1}, \ldots, Y_{n}$. It is quite usual to order couples $\left(X_{1}, Y_{1}\right)^{\prime}, \ldots,\left(X_{n}, Y_{n}\right)^{\prime}$ in advance such that $R_{i}=i, i=1, \ldots, n$.

Spearman correlation coefficient $r_{S}$ is defined as sample correlation coefficient calculated from $\left(R_{1}, Q_{1}\right)^{\prime}, \ldots,\left(R_{n}, Q_{n}\right)^{\prime}$, it means

$$
r_{S}=\frac{\sum R_{i} Q_{i}-n \bar{R} \bar{Q}}{\sqrt{\left(\sum R_{i}^{2}-n \bar{R}^{2}\right)\left(\sum Q_{i}^{2}-n \bar{Q}^{2}\right)}}
$$

Theorem 11.2 We have

$$
\begin{equation*}
r_{S}=1-\frac{6}{n\left(n^{2}-1\right)} \sum_{i=1}^{n}\left(R_{i}-Q_{i}\right)^{2} . \tag{11.1}
\end{equation*}
$$

Proof. We have

$$
\begin{equation*}
r_{S}=\frac{\sum R_{i} Q_{i}-n \bar{R} \bar{Q}}{\sqrt{\left(\sum R_{i}^{2}-n \bar{R}^{2}\right)\left(\sum Q_{i}^{2}-n \bar{Q}^{2}\right)}} \tag{11.2}
\end{equation*}
$$

where

$$
\begin{gathered}
\bar{R}=\frac{1}{n} \sum_{i=1}^{n} R_{i}=\frac{1}{n} \sum_{i=1}^{n} i=\frac{n+1}{2}, \quad \bar{Q}=\bar{R}, \\
\sum_{i=1}^{n} R_{i}^{2}=\sum_{i=1}^{n} Q_{i}^{2}=\sum_{i=1}^{n} i^{2}=\frac{n(n+1)(2 n+1)}{6}, \\
\sum R_{i} Q_{i}=\frac{1}{2}\left(\sum R_{i}^{2}+\sum Q_{i}^{2}\right) \\
-\frac{1}{2} \sum\left(R_{i}-Q_{i}\right)^{2} \\
\\
=\frac{n(n+1)(2 n+1)}{6}-\frac{1}{2} \sum\left(R_{i}-Q_{i}\right)^{2} .
\end{gathered}
$$

These results we insert into (11.1) and after some simplification we get formula (11.2).

Critical values are denoted by $r_{S}(\alpha)$. If $\left|r_{S}\right| \geq r_{S}(\alpha)$, we reject hypothesis of independence $Y_{i}$ and $X_{i}$. For $n>30$ we use asymptotic normality of the coefficient $r_{S}$. We calculate

$$
\begin{equation*}
r_{S}^{*}(\alpha)=\frac{u\left(\frac{\alpha}{2}\right)}{\sqrt{n-1}} \tag{11.3}
\end{equation*}
$$

Hypothesis of independence is rejected in the case that $\left|r_{S}\right| \geq r_{S}^{*}(\alpha)$. One-sided tests can be derived similarly.

If $\left(X_{1}, Y_{1}\right)^{\prime}, \ldots,\left(X_{n}, Y_{n}\right)^{\prime}$ is the sample from the regular two-dimensional normal distribution with correlation coefficient $\rho$, then it can be proved (see van der Waerden 1957), that

$$
\mathrm{E} r_{S}=\frac{6}{\pi} \frac{n-2}{n+1} \arcsin \frac{\rho}{2}+\frac{6}{\pi(n+1)} \arcsin \rho
$$

With growing $n$ the second member on the right-hand side tends to zero and the sample correlation coefficient $r$ tends almost surely to $\rho$. We get an approximation

$$
r \doteq 2 \sin \left(\frac{\pi}{6} r_{S}\right)
$$

If in our data from which $r_{S}$ is calculated, there are many agreements, it is recommended to use corrected Spearman correlation coeficient (see Kendall 1962 and Sachs 1974). It is defined by the formula

$$
r_{S, \text { korig }}=1-\frac{6 \sum\left(R_{i}-Q_{i}\right)^{2}}{n^{3}-n-T_{x^{\prime}}-T_{y^{\prime}}},
$$

where

$$
T_{x^{\prime}}=\frac{1}{2} \sum\left(t_{x^{\prime}}^{3}-t_{x^{\prime}}\right), \quad T_{y^{\prime}}=\frac{1}{2} \sum\left(t_{y^{\prime}}^{3}-t_{y^{\prime}}\right)
$$

Here symbol $t_{x^{\prime}}$ denotes number of equally large $X$-values. (If we have among $X$ - values a few groups with the same number of observations, then $t_{x^{\prime}}$ are sizes of the groups. Symbol $t_{x^{\prime}}$ is defined analogously.)

## Chapter 12

## Discrete paired problem

### 12.1 McNemar test

In some cases we want to apply another test than the test of independence or the test of homogeneity. Sometimes we have a set of $n$ randomly chosen statistical units and presence and absence of a characteristic is investigated. Then an intervention in every unit is executed and repeatedly it is investigated if the characteristic is present or not. The aim of the investigation is to find if the intervention changed probability of the occurrence of the characteristic.

Denote 1 presence and 0 absence of the characteristic. In this case it is necessary to have data in the form of tab. 12.1. We assume that these data are sample from a multinomial distribution with parameter $n$ and with probabilities introduced in tab. 12.2.

Table 12.1: Frequencies for the McNemar test

| Before | After intervention |  |  |
| :--- | :---: | :---: | :---: |
| intervention | 1 | 0 | Total |
| 1 | $n_{11}$ | $n_{12}$ | $n_{1 .}$ |
| 0 | $n_{21}$ | $n_{22}$ | $n_{2 .}$ |
| Total | $n_{.1}$ | $n_{.2}$ | $n$ |

Table 12.2: Probabilities for McNemar test

| Before | After intervention |  |  |
| :--- | :---: | :---: | :---: |
| intervention | 1 | 0 | Total |
| 1 | $p_{11}$ | $p_{12}$ | $p_{1 .}$ |
| 0 | $p_{21}$ | $p_{22}$ | $p_{2 .}$ |
| Total | $p_{.1}$ | $p_{.2}$ | 1 |

We want to test $H_{0}: p_{1 .}=p_{.1}$. By chance $H_{0}$ is equivalent to hypothesis of symmetry $H_{0}^{\prime}: p_{12}=p_{21}$. In this case all probabilities in tab. 12.2 are determined by two unknown parameters $p_{11}$ and $p_{12}$. If $H_{0}^{\prime}$ holds then $p_{21}=p_{12}$ and $p_{22}=1-p_{11}-2 p_{12}$.

From formula (10.13) we get

$$
\begin{aligned}
\frac{n_{11}}{p_{11}}-\frac{n_{22}}{p_{22}} & =0, \\
\frac{n_{12}}{p_{12}}+\frac{n_{21}}{p_{21}}-2 \frac{n_{22}}{p_{22}} & =0 .
\end{aligned}
$$

It implies

$$
\begin{align*}
n_{11} & =\frac{n_{22}}{p_{22}} p_{11}  \tag{12.1}\\
n_{12}+n_{21} & =2 \frac{n_{22}}{p_{22}} p_{12} \tag{12.2}
\end{align*}
$$

We include a trivial equality

$$
n_{22}=\frac{n_{22}}{p_{22}} p_{22}
$$

and then we add all relations. This gives

$$
n=\frac{n_{22}}{p_{22}}
$$

so that an estimator for $p_{22}$ is $\hat{p}_{22}=n_{22} / n$. Inserting in (12.1) and (12.2) we obtain

$$
\hat{p}_{11}=\frac{n_{11}}{n}, \quad \hat{p}_{12}=\frac{n_{12}+n_{21}}{2 n}, \quad \hat{p}_{21}=\hat{p}_{12} .
$$

The variable

$$
\chi^{2}=\sum_{i=1}^{2} \frac{\left(n_{i i}-n \hat{p}_{i i}\right)^{2}}{n \hat{p}_{i i}}+\frac{\left(n_{12}-n \hat{p}_{12}\right)^{2}}{n \hat{p}_{12}}+\frac{\left(n_{21}-n \hat{p}_{21}\right)^{2}}{n \hat{p}_{21}}
$$

is equal to

$$
\begin{equation*}
\chi^{2}=\frac{\left(n_{12}-n_{21}\right)^{2}}{n_{12}+n_{21}} \tag{12.3}
\end{equation*}
$$

and has asymptotically $\chi_{1}^{2}$ distribution. Hypothesis $H_{0}$ is rejected, when $\chi^{2} \geq \chi_{1}^{2}(\alpha)$. In textbooks it is introduced that this asymptotic result is applicable for $n_{12}+n_{21} \geq 8$. The test was published in McNemar (1947).

When frequencies are small then we use the result that under $H_{0}$ the conditional distribution of frequencies $n_{12}$ is binomial $\mathrm{Bi}\left(n_{12}+n_{21}, \frac{1}{2}\right)$. A detailed derivation can be found in the book Anděl (2007), for example. Define $N=n_{12}+n_{21}$. Hypothesis $H_{0}$ is rejected, if $n_{12} \leq k_{1}$ or $n_{12} \geq k_{2}$, where $k_{1}$ and $k_{2}$ are corresponding critical values. This test is two-sided. Using its variant based on the binomial distribution it is easy to apply the McNemar test also against its one-sided alternatives.

Example 12.1 It was investigated if application of a medicament has as a side effect change of speed of shrinkage of blood. Randomly was determined 100 patients. Each of them was determined if his shrinkage of blood is slow or fast. Then the patients obtained the mentioned medicament and after adequate time the speed of shrinkage of blood was determined again. The results are in tab. 12.3.

Table 12.3: Shrinkage of blood

| Before <br> application | After application |  |  |
| :--- | :---: | :---: | :---: |
| Slow | Fast | Total |  |
| Slow | 24 | 28 | 52 |
| Fast | 12 | 36 | 48 |
| Total | 36 | 64 | 100 |

Using (12.3) we get $\chi^{2}=6,4$. This value is larger than $\chi_{1}^{2}(0,05)=3,84$. Thus we reject the hypothesis that the application of medicament has no influence on speed of shrinkage of blood.

For $N=28+12=40$ and $\alpha=0.05$ critical values are $k_{1}=13, k_{2}=27$. Since $n_{12}=28 \geq k_{2}$, we reject the hypothesis that the application of medicament has no influence on speed of shrinkage of blood, too.

The calculation using the program $R$ can be following one.

```
slow.aft <- c(24,12)
quick.aft <- c(28,36)
tbl <- cbind(pomala.aft,rychla.aft)
rownames(tbl) <- c("pomala.pred","rychla.pred")
names(dimnames(tbl)) <- c("reakce.pred","reakce.po")
mcnemar.test(tbl, correct=F)
    McNemar's Chi-squared test
data: tbl McNemar's chi-squared = 6.4, df = 1, p-value = 0.01141
```


### 12.2 Stuart test

Consider a square contingency table with dimension $c \times c$. The data should be used for testing hypothesis of homogeneity of marginal probabilities

$$
H_{0}: p_{1 .}=p_{.1}, \quad \ldots \quad p_{c .}=p_{. c} .
$$

We describe the Stuart test, which is direct generalization of the McNemar test. Introduce the following notation:

$$
d_{i}=n_{i .}-n_{. i} \quad \text { for } i=1, \ldots, c, \quad \boldsymbol{d}=\left(d_{1}, \ldots, d_{c-1}\right)^{\prime} .
$$

Let $\boldsymbol{V}=\left(V_{i j}\right)_{i, j=1, \ldots, c-1}$ be the matrix of dimension $(c-1) \times(c-1)$, the elements of which are

$$
\begin{aligned}
V_{i i} & =n_{i .}+n_{. i}-2 n_{i i}, \\
V_{i j} & =-\left(n_{i j}+n_{j i}\right) \quad \text { for } \quad i \neq j .
\end{aligned}
$$

Theorem 12.2 (Stuart) If the hypothesis $H_{0}$ is valid, then the variable $Q=\boldsymbol{d}^{\prime} \boldsymbol{V}^{-1} \boldsymbol{d}$ has asymptotically $\chi_{c-1}^{2}$ distribution.

Proof. See Stuart (1955) or Anděl (2007).
It is easy to check that for $c=2$ the variable $Q$ is the same as the variable $\chi^{2}$ which is introduced in formula (12.3). If $c=3$ the variable $Q$ can be calculated using the formula

$$
\begin{equation*}
Q=\frac{N_{23} d_{1}^{2}+N_{13} d_{2}^{2}+N_{12} d_{3}^{2}}{2\left(N_{12} N_{23}+N_{12} N_{13}+N_{13} N_{23}\right)}, \tag{12.4}
\end{equation*}
$$

where

$$
N_{i j}=\frac{n_{i j}+n_{j i}}{2}
$$

A similar but more complicated explicit formula was derived also for $c=4$ (see Krauth 1985).

## Chapter 13

## Two-sample problem

### 13.1 Descriptive statistics

The description of data and their graphical representation will be illustrated on data called energy available in library ISwR. The data are in form data.frame with 22 rows and 2 columns. It is a description of energy expenditure in the groups of lean and obese women. The first column called expend is numerical vector giving expenditure of energy in MJ during 24 hours. The second column is called stature and it is factor with levels lean a obese. (See Dalgaard 2002.)

```
library(ISwR)
data(energy)
attach(energy)
expend.lean <- expend[stature=="lean"]
expend.obese <- expend[stature=="obese"]
expend.lean
    [1] 7.53 7.48 8.08 8.09 10.15 8.40 10.88 6.13 7.90
[13] 8.11
expend.obese
[1] 9.21 11.51 12.79 11.85 9.97 8.79 9.69 9.68 9.19
```

For each group we prepare histogram. The histograms are placed in such a way that they can be compared (see fig. 13.1).

```
opar <- par(mfrow=c (2,1))
hist(expend.lean, breaks=10, xlim=c(5,13), ylim=c(0,4), col="white")
hist(expend.obese, breaks=10, xlim=c(5,13), ylim=c(0,4), col="grey90")
par(opar)
```

Data can be also represented by boxplots (see fig. 13.2) and using figure called stripchart (see fig. 13.3). Figures were created using program

```
boxplot(expend ~ stature, boxwex=0.2, las=1)
stripchart(expend ~ stature, method="jitter", jitter=0.03, vertical=T,
    las=1)
```

In the case of stripcharts the method called jitter was used to show also data which are identical or very nearly the same.

Histogram of expend.lean


Figure 13.1: Histograms

### 13.2 Two-sample Kolmogorov-Smirnov test

Let $X_{1}, \ldots, X_{m}$ be a random sample from a distribution with continuous distribution function $F$ and let $Y_{1}, \ldots, Y_{n}$ be an independent random sample with a continuous distribution function $G$. Consider a test of hypothesis $H_{0}: F=G$ against $H_{1}: F \neq G$. Let $F_{m}$ be the empirical distribution function of the first sample and $G_{n}$ of the second sample. Theorems 9.1 and 9.2 imply, that the functions $F_{m}$ and $G_{n}$ with increasing $m$ and $n$ converge to distribution functions $F$ and $G$. Define

$$
D_{m, n}=\sup _{x}\left|F_{m}(x)-G_{n}(x)\right| .
$$

If $H_{0}$ is true then the Glivenko-Cantelli theorem gives that $D_{m, n} \rightarrow 0$ almost surely when $m \rightarrow \infty, n \rightarrow \infty$. An exact result is described in the following theorem.

Theorem 13.1 (Smirnov) Let $M=m n /(m+n)$. Define

$$
\begin{equation*}
K(\lambda)=1-2 \sum_{k=1}^{\infty}(-1)^{k+1} \exp \left(-2 k^{2} \lambda^{2}\right) . \tag{13.1}
\end{equation*}
$$

Then for every $\lambda$ we have

$$
\lim _{m, n \rightarrow \infty} \mathrm{P}\left(\sqrt{M} D_{m, n}<\lambda\right)=K(\lambda)
$$



Figure 13.2: Boxplots
Proof. See Smirnov (1944). Modern proof can be found in the book Hájek, Šidák (1967). Function $K(\lambda)$ was introduced in the formula (9.3) on p. 72.

Distribution of the variable $D_{m, n}$ for finite values $m, n$ is introduced in the book Hájek, Šidák (1967). Function $K(\lambda)$ can be approximated by some members from the beginning of the series $1-2 e^{-2 \lambda^{2}}$ (see Likeš, Laga 1978). Then

$$
\mathrm{P}\left(D_{m, n}<\frac{\lambda}{\sqrt{M}}\right) \doteq 1-2 e^{-2 \lambda^{2}} .
$$

The expression on the right hand side equals to $1-\alpha$ for $\lambda=\lambda_{\alpha}=\sqrt{\frac{1}{2} \ln \frac{2}{\alpha}}$. The critical value is approximately

$$
D_{m, n}^{*}(\alpha)=\frac{\lambda_{\alpha}}{\sqrt{M}}=\sqrt{\frac{1}{2 M} \ln \frac{2}{\alpha}} .
$$

Practical use of the Kolmogorov-Smirnov test is the following one. From samples $X_{1}, \ldots, X_{m}$ and $Y_{1}, \ldots, Y_{n}$ empirical distribution functions $F_{m}$ and $G_{n}$ and the variable $D_{m, n}$ are calculated. If the numbers $m$ and $n$ are small, the variable $D_{m, n}$ is compared with exact critical values $D_{m, n}(\alpha)$. If the numbers $m$ and $n$ are not very small, theorem 13.1 can be applied. Define $\lambda_{0}=\sqrt{M} D_{m, n}$ and calculate $K\left(\lambda_{0}\right)$. If we get $K\left(\lambda_{0}\right) \geq 1-\alpha$, we reject $H_{0}$ on the level which tends to $\alpha$ when the sizes of the samples go to infinity. The critical value for the variable $D_{m, n}$ is approximated by $D_{m, n}^{*}(\alpha)$. Hypothesis $H_{0}$ is rejected when $D_{m, n} \geq D_{m, n}^{*}(\alpha)$.

The Kolmogorov-Smirnov test was generalized to the case of comparing three and more samples in the paper Kiefer (1959). Critical values were tabulated in Wolf, Naus (1973). See also Domaǹski (1990).

Example 13.2 Two methods of fertilization were compared. Eight fields were fertilized using the new method and five by old method. The crop of wheat on hectares in tons


Figure 13.3: Stripcharts

Table 13.1: Yield of wheat in tons on hectare

| $X_{i}$ | 5.7 | 5.5 | 4.3 | 5.9 | 5.2 | 5.6 | 5.8 | 5.1 |
| ---: | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $Y_{i}$ | 5.0 | 4.5 | 4.2 | 5.4 | 4.4 |  |  |  |

are labeled $X_{i}$ for new method and $Y_{i}$ for the old method. The data are presented in tab. 13.1. We should find out if the method of fertilization has influence on the yield of wheat.

First, we construct graph of the both distribution functions (see fig. 13.4).

```
new <- c(5.7,5.5,4.3,5.9,5.2,5.6,5.8,5.1)
old <- c(5.0,4.5,4.2,5.4,4.4)
plot.ecdf(new, verticals=T, las=1, xlab="", ylab="", pch="", main="")
plot.ecdf(old, verticals=T, add=T, pch="", lty=2)
```

The full line shows ecdf of yields concerning the new method of fertilization and the dashed line concerns the old one.

In our example we have $D_{8,5}=0.675$. Critical value on the level 5 per cent is 0.75 . (By the way, the approximate critical value is $D_{8,5}^{*}(0.05)=0.774$.) Since $D_{8,5}<0.75$, Kolmogorov-Smirnov test does not reject the hypothesis that both samples are from populations with the same distribution functions.

Both samples have small sizes. Application of theorem 13.1 is recommended for $m+n>35$. If we use the approximation, we get $\lambda_{0}=1.184, K\left(\lambda_{0}\right)=0.879$. Since $K\left(\lambda_{0}\right)<0,95$, we cannot reject the hypothesis.

Using the program $R$ the calculations can be done in the following way.

```
ks.test(new,old)
    Two-sample Kolmogorov-Smirnov test
data: new and old D = 0.675, p-value = 0.07925 alternative
hypothesis: two.sided
```



Figure 13.4: Two-sample Kolmogorov-Smirnov test

### 13.3 Two-sample t test

Let $X_{1}, \ldots, X_{m}$ be a sample from $\mathrm{N}\left(\mu_{1}, \sigma^{2}\right)$ and let $Y_{1}, \ldots, Y_{n}$ be a sample from $\mathrm{N}\left(\mu_{2}, \sigma^{2}\right)$. Assume that $m \geq 2, n \geq 2, \sigma^{2}>0$, and that both samples are mutually independent. Denote

$$
\begin{aligned}
\bar{X} & =\frac{1}{m} \sum_{i=1}^{m} X_{i}, & \bar{Y} & =\frac{1}{n} \sum_{i=1}^{n} Y_{i}, \\
S_{X}^{2} & =\frac{1}{m-1} \sum_{i=1}^{m}\left(X_{i}-\bar{X}\right)^{2}, & S_{Y}^{2} & =\frac{1}{n-1} \sum_{i=1}^{n}\left(Y_{i}-\bar{Y}\right)^{2} .
\end{aligned}
$$

Under these assumptions the following theorem holds.
Theorem 13.3 Random variable

$$
\begin{equation*}
T=\frac{\bar{X}-\bar{Y}-\left(\mu_{1}-\mu_{2}\right)}{\sqrt{(m-1) S_{X}^{2}+(n-1) S_{Y}^{2}}} \sqrt{\frac{m n(m+n-2)}{m+n}} \tag{13.2}
\end{equation*}
$$

has distribution $\mathrm{t}_{m+n-2}$.
Proof. Theorems 4.6 (b) on p. 48 and 3.6 on p. 38 give that

$$
Z=\left[(m-1) S_{X}^{2}+(n-1) S_{Y}^{2}\right] / \sigma^{2} \sim \chi_{m+n-2}^{2}
$$

Similarly as in theorem 4.6 (c) can be proved that the variables $\bar{X}-\bar{Y}$ and $(m-1) S_{X}^{2}+$ $(n-1) S_{Y}^{2}$ are independent. We get

$$
\bar{X}-\bar{Y} \sim \mathrm{~N}\left(\mu_{1}-\mu_{2}, \frac{\sigma^{2}}{m}+\frac{\sigma^{2}}{n}\right)
$$

In the same time we have

$$
U=\frac{\bar{X}-\bar{Y}-\left(\mu_{1}-\mu_{2}\right)}{\sqrt{\frac{\sigma^{2}}{m}+\frac{\sigma^{2}}{n}}} \sim \mathrm{~N}(0,1)
$$

Theorem 3.10 ensures that the variable $U / \sqrt{Z /(m+n-2)}$ has distribution $\mathrm{t}_{m+n-2}$. However, $U / \sqrt{Z /(m+n-2)}=T$.

Two-sample $t$-test is the test of hypothesis $H_{0}: \mu_{1}-\mu_{2}=\delta$, where $\delta$ is a given number (very often it is $\delta=0$ ). If it is a test against alternative $H_{1}: \mu_{1}-\mu_{2} \neq \delta$, the procedure is following one. First, we calculate $T$ from formula (13.2) where we insert $\mu_{1}-\mu_{2}=\delta$. If $|T| \geq t_{m+n-2}(\alpha)$, we reject the hypothesis $H_{0}$ on the level $\alpha$. The one-sided tests are analogous.

Among assumptions of two-sample $t$ test we have that both samples come from normal populations with the same variance. The violation of these assumptions does not influence the result of the test too much. Yet in the case of substantial non-normality we prefer some non-parametric tests (very often it is two-sample Wilcoxon test, see section 13.6). Assumption that the variances are equal can be checked by help of the $F$ test (see section 13.5). If it is known that the variances are different the Welch test is applied (see section 13.4).

Example 13.4 Eleven piglings were randomly divided into two groups. The first group contained 6 piglings and they were fed by diet A. In the second group were 5 piglings on diet B. Average daily increments after 6 months are given in tab. 13.2. It should be established if both diets are equally effective.

Table 13.2: Average daily increments in dkg

| Diet A | 62 | 54 | 55 | 60 | 53 | 58 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Diet B | 52 | 56 | 49 | 50 | 51 |  |

Data are plotted in fig. 13.5 and we apply two-sample $t$ test.

```
da<-c(62,54,55,60,53,58) # data
db<-c(52,56,49,50,51)
boxplot(da, db, names=c("da", "db"), boxwex=0.3, las=1) # graph
t.test(da,db,var.equal=T) # test
    Two Sample t-test
data: da and db
t = 2.7712, df = 9, p-value = 0.02171
alternative hypothesis: true difference in means is not equal to 0
95 percent confidence interval:
    0.9919634 9.8080366
sample estimates:
mean of x mean of y
    57.0 51.6
```

Since $p$-value is smaller than 0.05 , we reject hypothesis that both diets are equally effective. $\diamond$


Figure 13.5: Boxplots for diet a and b

### 13.4 Two-sample Welch test

Let $X_{1}, \ldots, X_{n_{1}}$ be a sample from $\mathrm{N}\left(\mu_{1}, \sigma_{1}^{2}\right)$ and $Y_{1}, \ldots, Y_{n_{2}}$ an independent sample from $\mathrm{N}\left(\mu_{2}, \sigma_{2}^{2}\right)$. Assume that $\sigma_{1}>0, \sigma_{2}>0, n_{1} \geq 2, n_{2} \geq 2$. Define $f_{1}=n_{1}-1, f_{2}=n_{2}-1$,
$\bar{X}=\frac{1}{n_{1}} \sum_{i=1}^{n_{1}} X_{i}, \quad \bar{Y}=\frac{1}{n_{2}} \sum_{i=1}^{n_{2}} Y_{i}, \quad S_{1}^{2}=\frac{1}{f_{1}} \sum_{i=1}^{n_{1}}\left(X_{i}-\bar{X}\right)^{2}, \quad S_{2}^{2}=\frac{1}{f_{2}} \sum_{i=1}^{n_{2}}\left(Y_{i}-\bar{Y}\right)^{2}$.
Welch test (see Welch 1938) was derived for testing the hypothesis $H_{0}: \mu_{1}=\mu_{2}$ against one-sided or two-sided alternative. If variances $\sigma_{1}^{2}$ and $\sigma_{2}^{2}$ were known, we would use the test statistic

$$
\begin{equation*}
\xi=\frac{\bar{X}-\bar{Y}}{\sqrt{\frac{\sigma_{1}^{2}}{n_{1}}+\frac{\sigma_{2}^{2}}{n_{2}}}}, \tag{13.3}
\end{equation*}
$$

which has distribution $\mathrm{N}(0,1)$ under $H_{0}$. If the variances $\sigma_{1}^{2}$ and $\sigma_{2}^{2}$ are not known, it is natural to substitute them by their estimators $S_{1}^{2}$ a $S_{2}^{2}$. Thus we will investigate the test statistic

$$
\begin{equation*}
t=\frac{\bar{X}-\bar{Y}}{\sqrt{\frac{S_{1}^{2}}{n_{1}}+\frac{S_{2}^{2}}{n_{2}}}} . \tag{13.4}
\end{equation*}
$$

The statistics can be written in the form

$$
t=\frac{\frac{\bar{X}-\bar{Y}}{\sqrt{\frac{\sigma_{1}^{2}}{n_{1}}+\frac{\sigma_{2}^{2}}{n_{2}}}} \sqrt{\frac{\sigma_{1}^{2}}{n_{1}}+\frac{\sigma_{2}^{2}}{n_{2}}}}{\sqrt{\underbrace{\frac{f_{1} S_{1}^{2}}{\sigma_{1}^{2}}}_{\eta_{1}} \frac{\sigma_{1}^{2}}{n_{1} f_{1}}+\underbrace{\frac{f_{2} S_{2}^{2}}{\sigma_{2}^{2}}}_{\eta_{2}} \frac{\sigma_{2}^{2}}{n_{2} f_{2}}}} .
$$

Define

$$
\eta_{1}=\frac{f_{1} S_{1}^{2}}{\sigma_{1}^{2}}, \quad \eta_{2}=\frac{f_{2} S_{2}^{2}}{\sigma_{2}^{2}}
$$

We know that

$$
\eta_{1}=\sim \chi_{f_{1}}^{2}, \quad \eta_{2}=\sim \chi_{f_{2}}^{2} .
$$

Inserting from (13.3) we get

$$
t=\frac{\xi}{\sqrt{\underbrace{\frac{\sigma_{1}^{2}}{\frac{\sigma_{1}^{2} f_{1}}{n_{1}}+\frac{\sigma_{2}^{2}}{n_{2}}}}_{a} \eta_{1}+\underbrace{\frac{\sigma_{2}^{2}}{\frac{\sigma}{1}_{2}^{n_{2} f_{2}}}+\frac{\sigma_{2}^{2}}{n_{2}}}_{b}} \eta_{2}} .
$$

Let

$$
a=\frac{\frac{\sigma_{1}^{2}}{n_{1} f_{1}}}{\frac{\sigma_{1}^{2}}{n_{1}}+\frac{\sigma_{2}^{2}}{n_{2}}}, \quad b=\frac{\frac{\sigma_{2}^{2}}{n_{2} f_{2}}}{\frac{\sigma_{1}^{2}}{n_{1}}+\frac{\sigma_{2}^{2}}{n_{2}}}, \quad w=a \eta_{1}+b \eta_{2} .
$$

Then

$$
t=\frac{\xi}{\sqrt{w}} .
$$

To calculate exact distribution of the variable $t$ would be difficult. Welch suggested the following approximation of the distribution of the variable $w$ :

$$
\mathcal{L}(w) \doteq \mathcal{L}(g Z)
$$

where $g$ is an appropriate constant and $Z$ is a random variable having distribution $\chi_{f}^{2}$. The number of degrees $f$ must be determined. The constants $g$ and $f$ can be calculated using moment method from conditions

$$
\begin{aligned}
\mathrm{E} a \eta_{1}+\mathrm{E} b \eta_{2} & =\mathrm{E} g Z \\
\operatorname{var} a \eta_{1}+\operatorname{var} b \eta_{2} & =\operatorname{var} g Z
\end{aligned}
$$

Thus we obtain system of equations

$$
\begin{aligned}
a f_{1}+b f_{2} & =g f, \\
2\left(a^{2} f_{1}+b^{2} f_{2}\right) & =2 g^{2} f .
\end{aligned}
$$

The solution is

$$
g=\frac{a^{2} f_{1}+b^{2} f_{2}}{a f_{1}+b f_{2}}, \quad f=\frac{\left(a f_{1}+b f_{2}\right)^{2}}{a^{2} f_{1}+b^{2} f_{2}} .
$$

In the frame of the used approximation we have

$$
\frac{w}{g} \sim \chi_{f}^{2}
$$

Thus

$$
\frac{\xi}{\sqrt{\frac{w}{g} \cdot \frac{1}{f}}} \sim \mathrm{t}_{f}
$$

A simple derivation gives

$$
g f=a f_{1}+b f_{2}=1
$$

It implies

$$
\frac{\xi}{\sqrt{w}} \sim \mathrm{t}_{f}
$$

where

$$
f=\frac{\left(a f_{1}+b f_{2}\right)^{2}}{a^{2} f_{1}+b^{2} f_{2}}=\frac{1}{a^{2} f_{1}+b^{2} f_{2}}=\frac{\left(\frac{\sigma_{1}^{2}}{n_{1}}+\frac{\sigma_{2}^{2}}{n_{2}}\right)^{2}}{\frac{\sigma_{1}^{4}}{n_{1}^{2} f_{1}}+\frac{\sigma_{2}^{4}}{n_{2}^{2} f_{2}}}
$$

In this formula the unknown parameters $\sigma_{1}^{2}$ a $\sigma_{2}^{2}$ are substituted by estimators $S_{1}^{2}$ a $S_{2}^{2}$. Instead of $f$ the degrees of freedom are taken as

$$
f^{*}=\frac{\left(\frac{S_{1}^{2}}{n_{1}}+\frac{S_{2}^{2}}{n_{2}}\right)^{2}}{\frac{S_{1}^{4}}{n_{1}^{2} f_{1}}+\frac{S_{2}^{4}}{n_{2}^{2} f_{2}}}
$$

and the approximation $t \sim \mathrm{t}_{f^{*}}$ is used.
It can be derived that

$$
\min \left\{f_{1}, f_{2}\right\} \leq f^{*} \leq f_{1}+f_{2} .
$$

Example 13.5 We use data from example 13.4. We get

```
da<-c(62,54,55,60,53,58) db<-c(52,56,49,50,51) t.test(da,db)
    Welch Two Sample t-test
data: da and db t = 2.8487, df = 8.947, p-value = 0.01924
alternative hypothesis: true difference in means is not equal to 0
95 percent confidence interval:
    1.107981 9.692019
sample estimates: mean of x mean of y
        57.0 51.6
```

Since the $p$-value is smaller than 0.05 , we reject the hypothesis that the true difference in means is equal to $0 . \diamond$

### 13.5 Test of equality of variances

Theorem 13.6 Let $X_{1}, \ldots, X_{n}$ be a sample from $\mathrm{N}\left(\mu_{1}, \sigma_{1}^{2}\right)$ and $Y_{1}, \ldots, Y_{m}$ a sample from $\mathrm{N}\left(\mu_{2}, \sigma_{2}^{2}\right)$. Let these two samples be independent. Assume that $n \geq 2, m \geq 2$, $\sigma_{1}^{2}>0, \sigma_{2}^{2}>0$. Let $\bar{X}, S_{X}^{2}$ and $\bar{Y}, S_{Y}^{2}$ be characteristics of the samples. If the equality $\sigma_{1}^{2}=\sigma_{2}^{2}$ holds, then $Z=S_{X}^{2} / S_{Y}^{2} \sim \mathrm{~F}_{n-1, m-1}$.

Proof. The assertion follows from theorem 3.11 on p. 40.
We shall test hypothesis $H_{0}: \sigma_{1}^{2}=\sigma_{2}^{2}$ against $H_{1}: \sigma_{1}^{2} \neq \sigma_{2}^{2}$. We reject $H_{0}$ if $S_{X}^{2} / S_{Y}^{2} \leq k_{1}$, or $S_{X}^{2} / S_{Y}^{2} \geq k_{2}$. The constants $k_{1}$ and $k_{2}$ are chosen so that under $H_{0}$

$$
\begin{equation*}
\mathrm{P}\left(S_{X}^{2} / S_{Y}^{2} \leq k_{1}\right)=\alpha / 2, \quad \mathrm{P}\left(S_{X}^{2} / S_{Y}^{2} \geq k_{2}\right)=\alpha / 2 \tag{13.5}
\end{equation*}
$$

Then the probability of error of the first kind is $\alpha$. Theorem 13.6 gives that (13.5) holds in the case

$$
\begin{equation*}
k_{1}=F_{n-1, m-1}\left(1-\frac{\alpha}{2}\right)=\frac{1}{F_{m-1, n-1}\left(\frac{\alpha}{2}\right)}, \quad k_{2}=F_{n-1, m-1}\left(\frac{\alpha}{2}\right) \tag{13.6}
\end{equation*}
$$

where $F_{u, v}(\alpha)$ is the critical value of F distribution. It is recommended to introduce such denotation that $S_{X}^{2} \geq S_{Y}^{2}$. Then it suffices to see if the inequality $S_{X}^{2} / S_{Y}^{2} \geq F_{n-1, m-1}\left(\frac{\alpha}{2}\right)$ holds, and it is not needed to calculate the inverse of critical values.

If the variances are $\sigma_{1}^{2}$ and $\sigma_{2}^{2}$ and (13.6) holds, then

$$
\mathrm{P}\left\{\frac{S_{X}^{2}}{S_{Y}^{2}} \frac{1}{k_{2}} \leq \frac{\sigma_{1}^{2}}{\sigma_{2}^{2}} \leq \frac{S_{X}^{2}}{S_{Y}^{2}} \frac{1}{k_{1}}\right\}=1-\alpha
$$

Then

$$
\left(\frac{S_{X}^{2}}{S_{Y}^{2}} \frac{1}{F_{n-1, m-1}\left(\frac{\alpha}{2}\right)}, \frac{S_{X}^{2}}{S_{Y}^{2}} F_{m-1, n-1}\left(\frac{\alpha}{2}\right)\right)
$$

is two-sided confidence interval for the ratio $\sigma_{1}^{2} / \sigma_{2}^{2}$ with confidence coefficient $1-\alpha$.
Since $F$-test is sensitive to assumption about equality of variances, the Levene test is often used instead (see section 15.6, p. 143).

Example 13.7 Consider again data introduced in example 13.4. We have

```
da<-c(62,54,55,60,53,58)
db<-c(52,56,49,50,51)
var.test(da,db)
    F test to compare two variances
data: da and db
F = 1.7534, num df = 5, denom df = 4, p-value = 0.6063
alternative hypothesis: true ratio of variances is not equal to 1
95 percent confidence interval:
    0.1872423 12.9541010
```

sample estimates: ratio of variances
1.753425

Since $p$-value is larger than 0.05 , the hypothesis that the true ratio of variances is equal to 1 is not rejected. Now, we show Levene test.

```
prirust <- c(da, db)
dieta <- factor(c(rep("A",6), rep("B",5)))
library(car)
leveneTest(prirust, dieta)
Levene's Test for Homogeneity of Variance (center = median)
    Df F value Pr(>F)
group 1 1.3439 0.2762
    9
```

Since $p$-value 0.2762 is larger than 0.05 , Levene test also does not reject hypothesis that true ratio of variances is equal to 1 .

Let us remark that in the case of data prepared like in this example the classical two-sample $t$-test will be calculated using
t.test(prirust ~ dieta, var.equal=T)
and Welch two-sample $t$-test using
t.test(prirust ~ dieta).

### 13.6 Two-sample Wilcoxon test

Let $X_{1}, \ldots, X_{m}$ be a random sample from a continuous distribution with a distribution function $F$ and $Y_{1}, \ldots, Y_{n}$ an independent random sample with a distribution function $G$.

We want to test the hypothesis $H_{0}: F=G$ against the alternative $H_{1}: F \neq G$. All $m+n$ variables $X_{1}, \ldots, X_{m}, Y_{1}, \ldots, Y_{n}$ form a pooled sample. Let $T_{1}$ be sum of ranks $X_{1}, \ldots, X_{m}$ and $T_{2}$ sum of ranks $Y_{1}, \ldots, Y_{n}$. It is clear that

$$
T_{1}+T_{2}=\frac{1}{2}(m+n)(m+n+1)
$$

First we investigate general properties of tests of this type. Let $N=m+n$ and let $R_{i}$ be the rank of the $i$ th variable. Finally, let $a(i)$ be a function defined for $i=1, \ldots, N$. The variable

$$
S=\sum_{i=1}^{N} c_{i} a\left(R_{i}\right)
$$

is called simple linear rank statistic.
The numbers $c_{1}, \ldots, c_{N}$ are regression constants and $a(i)$ are scores. Define

$$
\begin{aligned}
\bar{a} & =\frac{1}{N} \sum_{i=1}^{N} a(i), & \bar{c} & =\frac{1}{N} \sum_{i=1}^{N} c_{i}, \\
\sigma_{a}^{2} & =\frac{1}{N} \sum_{i=1}^{N}[a(i)-\bar{a}]^{2}, & \sigma_{c}^{2} & =\frac{1}{N} \sum_{i=1}^{N}\left(c_{i}-\bar{c}\right)^{2} .
\end{aligned}
$$

Theorem 13.8 If $H_{0}$ holds, then

$$
\mathrm{E} S=N \bar{a} \bar{c}, \quad \operatorname{var} S=\frac{N^{2}}{N-1} \sigma_{a}^{2} \sigma_{c}^{2}
$$

Proof. If $H_{0}$ holds, then $R_{i}$ is a random variable which is equal to every value $1, \ldots, N$ with probability $1 / N$. Thus

$$
\begin{equation*}
\mathrm{E} a\left(R_{i}\right)=\sum_{t=1}^{N} a(t) \frac{1}{N}=\bar{a} \tag{13.7}
\end{equation*}
$$

so that

$$
\mathrm{E} S=\sum_{i=1}^{N} c_{i} \mathrm{E} a\left(R_{i}\right)=\sum_{i=1}^{N} c_{i} \bar{a}=N \bar{a} \bar{c}
$$

If $i \neq j$, then under $H_{0}$ we have

$$
\mathrm{P}\left(R_{i}=s, R_{j}=t\right)=\frac{1}{N(N-1)} \quad \text { for } \quad 1 \leq s \neq t \leq N
$$

Using (13.7) we get

$$
\operatorname{var} a\left(R_{i}\right)=\mathrm{E}\left[a\left(R_{i}\right)-\mathrm{E} a\left(R_{i}\right)\right]^{2}=\mathrm{E}\left[a\left(R_{i}\right)-\bar{a}\right]^{2}=\frac{1}{N} \sum_{t=1}^{N}[a(t)-\bar{a}]^{2}=\sigma_{a}^{2}
$$

and then for $i \neq j$

$$
\begin{aligned}
\operatorname{cov}\left[a\left(R_{i}\right), a\left(R_{j}\right)\right] & =\mathrm{E}\left[a\left(R_{i}\right)-\bar{a}\right]\left[a\left(R_{j}\right)-\bar{a}\right] \\
& =\frac{1}{N(N-1)} \sum_{s \neq t} \sum_{s}[a(s)-\bar{a}][a(t)-\bar{a}] \\
& =\frac{1}{N(N-1)}\left\{\sum_{s} \sum_{t}[a(s)-\bar{a}][a(t)-\bar{a}]-\sum_{s}[a(s)-\bar{a}]^{2}\right\} \\
& =-\frac{1}{N(N-1)} \sum_{s}[a(s)-\bar{a}]^{2}=-\frac{1}{N-1} \sigma_{a}^{2} .
\end{aligned}
$$

This implies that

$$
\begin{aligned}
\operatorname{var} S & =\sum_{i} c_{i}^{2} \operatorname{var} a\left(R_{i}\right)+\sum_{i \neq j} \sum_{i} c_{j} \operatorname{cov}\left[a\left(R_{i}\right), a\left(R_{j}\right)\right] \\
& =\sigma_{a}^{2}\left(\sum_{i} c_{i}^{2}-\frac{1}{N-1} \sum_{i \neq j} c_{i} c_{j}\right) \\
& =\sigma_{a}^{2}\left(\sum_{i} c_{i}^{2}-\frac{1}{N-1} \sum_{i} \sum_{j} c_{i} c_{j}+\frac{1}{N-1} \sum_{i} c_{i}^{2}\right) \\
& =\frac{\sigma_{a}^{2}}{N-1}\left[N \sum_{i} c_{i}^{2}-\left(\sum c_{i}\right)^{2}\right]=\frac{N}{N-1} \sigma_{a}^{2} \sum_{i}\left(c_{i}-\bar{c}\right)^{2} \\
& =\frac{N^{2}}{N-1} \sigma_{a}^{2} \sigma_{c}^{2} .
\end{aligned}
$$

Theorem 13.9 If $H_{0}$ holds, then

$$
\mathrm{E} T_{1}=\frac{1}{2} m(m+n+1), \quad \operatorname{var} T_{1}=\frac{1}{12} m n(m+n+1)
$$

Proof. Variable $T_{1}$ is special case of $S$, if we insert $a(i)=i$ and

$$
c_{i}=\left\{\begin{array}{lll}
1 & \text { pro } \quad i=1, \ldots, m \\
0 & \text { pro } \quad i=m+1, \ldots, m+n
\end{array}\right.
$$

Define again $N=m+n$. We have

$$
\begin{array}{ll}
\bar{a}=\frac{1}{N} \sum_{i=1}^{N} i=\frac{N+1}{2}, & \sigma_{a}^{2}=\frac{1}{N} \sum_{i=1}^{N} i^{2}-\bar{a}^{2}=\frac{1}{12}(N+1)(N-1), \\
\bar{c}=\frac{m}{N}, & \sigma_{c}^{2}=\frac{1}{N} \sum_{i=1}^{N} c_{i}^{2}-\bar{c}^{2}=\frac{m n}{N^{2}} .
\end{array}
$$

It follows from theorem 13.8 that

$$
\mathrm{E} T_{1}=N \bar{a} \bar{c}=\frac{m(m+n+1)}{2}, \quad \operatorname{var} T_{1}=\frac{N^{2}}{N-1} \sigma_{a}^{2} \sigma_{c}^{2}=\frac{m n(m+n+1)}{12} .
$$

Instead of $T_{1}$ the variable $U_{1}=m n+\frac{1}{2} m(m+1)-T_{1}$ is used. The test based on $U_{1}$ is called Mann-Whitney test. Let $U_{2}=m n+\frac{1}{2} n(n+1)-T_{2}$. Then $U_{1}+U_{2}=m n$. The statistic $U_{1}$ gives number of cases when $X_{i}<Y_{j}$. Similarly, $U_{2}$ gives number of cases when $X_{i}>Y_{j}$ holds. If $\min \left(U_{1}, U_{2}\right)$ is less or equal to the critical value then the hypothesis $H_{0}$ is rejected. The samples are denoted so that $m \geq n$. If $m$ and $n$ are large, the following procedure is used. It follows from theorem 13.9 that

$$
\begin{equation*}
\mathrm{E} U_{1}=\frac{1}{2} m n, \quad \operatorname{var} U_{1}=\frac{1}{12} m n(m+n+1) \tag{13.8}
\end{equation*}
$$

Since $U_{2}=m n-U_{1}$, we have $\mathrm{E} U_{2}=\mathrm{E} U_{1}$, $\operatorname{var} U_{2}=\operatorname{var} U_{1}$. It is proved that for $m \rightarrow \infty$ and $n \rightarrow \infty$ the variable $U_{1}$ (as well as the variable $T_{1}$ ) has asymptotically normal distribution. We obtain

$$
\begin{equation*}
U=\frac{U_{1}-E U_{1}}{\sqrt{\operatorname{var} U_{1}}} \tag{13.9}
\end{equation*}
$$

where $\mathrm{E} U_{1}$ and $\operatorname{var} U_{1}$ are given in (13.8). If $|U| \geq u\left(\frac{\alpha}{2}\right), H_{0}$ is rejected on the level which tends to $\alpha$. The test based on (13.9) can be used for $m>10, n>10$.

If some variables are equal, we have ties. Then such a variable gets corresponding average rank. If the number of ties is large, instead of $U$ introduced in formula (13.9) the variable

$$
z=\frac{U_{1}-\frac{m n}{2}}{\sqrt{\frac{m n}{S(S-1)}\left(\frac{S^{3}-S}{12}-\sum_{i=1}^{r} \frac{t_{i}^{3}-t_{i}}{12}\right)}},
$$

is used, where $S=m+n, r$ is number of ties and $t_{i}$ is multiplicity of the $i$-th tie.
Although the Wilcoxon test is formulated as a test against a general alternative, it is sensitive especially to a shift $H_{1}^{\prime}: G(x)=F(x-\Delta), \Delta \neq 0$. For other alternatives, Kolmogorov-Smirnov test described in section 13.2 on p. 108 is recommended.

Example 13.10 We shall analyze data introduced in example 13.2, p. 109. The numbers are ordered. The values $X_{i}$ are underlined and their rank is introduced (see tab. 13.3).

Thus

$$
T_{1}=70, \quad U_{1}=6, \quad T_{2}=21, \quad U_{2}=34
$$

Critical value is 6 . Since $\min \left(U_{1}, U_{2}\right)=6 \leq 6$, we reject the hypothesis. The asymptotic procedure calculated in (13.9) gives $U=-2.049$. We have $|U| \geq u(0.025)=1.96$, and so we would reject the hypothesis, that both diets are equally effective, also by this procedure.

Program R gives

Table 13.3: Yields of wheat and their ranks

| Yields |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Ranks | 4.2 | $\underline{4.3}$ | 4.4 | 4.5 | 5.0 | $\underline{5.1}$ | $\frac{5.2}{}$ | 5.4 | $\frac{5.5}{}$ | $\frac{5.6}{}$ | $\frac{5.7}{1}$ | $\frac{5.8}{12}$ | $\frac{5.9}{13}$ |

```
new <- c(5.7,5.5,4.3,5.9,5.2,5.6,5.8,5.1)
old <- c(5.0,4.5,4.2,5.4,4.4)
wilcox.test(new, old, alternative = "two.sided", exact=T, correct=F)
        Wilcoxon rank sum test
data: new and old
W = 34, p-value = 0.04507
alternative hypothesis: true mu is not equal to 0
```

The hypothesis is also rejected.

## Chapter 14

## Discrete two-sample problem

### 14.1 Testing homogeneity of two binomial distributions

Let $p_{1}$ be probability that the event $A$ occurs in an experiment. Assume that in $m$ independent experiments the event $A$ occurred $X$ times. Then the experiment is repeated under different conditions so that the event $A$ occurs with probability $p_{2}$. Assume that in those $n$ additional experiments the event $A$ occurred $Y$ times. Using these data we wont to test hypothesis $H_{0}: p_{1}=p_{2}$ against alternative $H_{1}: p_{1} \neq p_{2}$. The hypothesis $H_{0}$ is called hypothesis of homogeneity of two binomial distributions, since $X \sim \operatorname{Bi}\left(m, p_{1}\right)$ and $Y \sim \operatorname{Bi}\left(n, p_{2}\right)$.

This is one of the oldest statistical problems which occurs frequently till now.
Denote $x=X / m, y=Y / n$. We shall assume that $x(1-x)+y(1-y) \neq 0$. Central limit theorem gives that for large values $m$ and $n$ the approximation

$$
x \sim \mathrm{~N}\left[p_{1}, \frac{p_{1}\left(1-p_{1}\right)}{m}\right], \quad y \sim \mathrm{~N}\left[p_{2}, \frac{p_{2}\left(1-p_{2}\right)}{n}\right]
$$

can be used. Since $x$ a $y$ are independent variables, in the frame of this approximation we have result

$$
\frac{x-y-\left(p_{1}-p_{2}\right)}{\sqrt{\frac{p_{1}\left(1-p_{1}\right)}{m}+\frac{p_{2}\left(1-p_{2}\right)}{n}}} \sim \mathrm{~N}(0,1) .
$$

If $H_{0}$ holds, then we insert in numerator simply $p_{1}-p_{2}=0$. However, in denominator the unknown values $p_{1}$ and $p_{2}$ remain. They can be substituted by their estimators. It can be proved that the limiting distribution remains the same, namely $N(0,1)$. Two kinds of estimators of the parameters $p_{1}$ and $p_{2}$ can be used. Thus we have two variants of the test of homogeneity.

In the first case we use $x$ as estimator of the parameter $p_{1}$ and $y$ as estimator of $p_{2}$. The strong law of large numbers ensures that $x \rightarrow p_{1}$ and $y \rightarrow p_{2}$ almost surely. To test the hypothesis $H_{0}$ we calculate variable

$$
\begin{equation*}
U_{a}=\frac{x-y}{\sqrt{\frac{x(1-x)}{m}+\frac{y(1-y)}{n}}} \tag{14.1}
\end{equation*}
$$

If $\left|U_{a}\right| \geq u\left(\frac{\alpha}{2}\right)$, we reject $H_{0}$. The tests of $H_{0}$ against one-sided alternatives are similar.
In the second case we use the fact that under $H_{0}$ we have $p_{1}=p_{2}$. This value can be estimated by

$$
z=\frac{X+Y}{m+n}=\frac{m x+n y}{m+n} .
$$

Thus we calculate

$$
\begin{equation*}
U_{b}=\frac{x-y}{\sqrt{z(1-z)\left(\frac{1}{m}+\frac{1}{n}\right)}} \tag{14.2}
\end{equation*}
$$

If $\left|U_{b}\right| \geq u\left(\frac{\alpha}{2}\right)$, we reject $H_{0}$. Similar procedure could be used for one-sided alternatives.
Some information about properties of $U_{a}$ and $U_{b}$ is contained in the following assertion published in the paper Eberhardt, Fliegner (1977).

Theorem 14.1 If $m=n$, then $\left|U_{b}\right| \leq\left|U_{a}\right|$ and the equality holds if and only if $x=y$.
Proof. Function $f(x)=x(1-x)$ is concave for $x \in[0,1]$. Thus for all $\gamma \in[0,1]$ and for all numbers $a, b \in[0,1]$ it holds

$$
f[\gamma a+(1-\gamma) b] \geq \gamma f(a)+(1-\gamma) f(b)
$$

Choose $\gamma=\frac{1}{2}, a=x, b=y$. Then we get

$$
\begin{equation*}
\frac{1}{2}(x+y)\left[1-\frac{1}{2}(x+y)\right] \geq \frac{1}{2} x(1-x)+\frac{1}{2} y(1-y) . \tag{14.3}
\end{equation*}
$$

For $m=n$ we have $z=(x+y) / 2$. Numerator of the fraction (14.1) has under the root

$$
\frac{2}{m}\left[\frac{1}{2} x(1-x)+\frac{1}{2} y(1-y)\right]
$$

and denominator of the fraction (14.2) has under the root

$$
\frac{2}{m}\left[\frac{x+y}{2}\left(1-\frac{x+y}{2}\right)\right] .
$$

Inequality (14.3) gives that $\left|U_{b}\right| \leq\left|U_{a}\right|$. The equality in (14.3) holds if and only if $x=y$.

We remark that for $m \neq n$ there is no simple relation between $U_{a}$ and $U_{b}$.
Seemingly for $m=n$ it would be better to use the test which is based on $U_{a}$, since it is more powerful. However, if the size of the sample is small, the probability of the error of the first kind is larger than $\alpha$. For example, for $\alpha=0.05$ and $m=n=20$ the probability of the error of the first kind is 0.081 and for $m=20, n=40$ even 0.085 .

Data can be written in the form of a contingency table (see tab. 14.1). If we use in this table the denotation of frequencies by $n_{i j}$ introduced in section 10.5 , we get

$$
U_{b}^{2}=\frac{\left(\frac{n_{11}}{n_{1 .}}-\frac{n_{21}}{n_{2 .}}\right)^{2}}{\frac{n_{.1}}{n} \frac{n_{.2}}{n} \frac{n}{n_{1 .} n_{2 .}}}=\frac{n\left(n_{11} n_{22}-n_{12} n_{21}\right)^{2}}{n_{1 .} n_{2 .} n_{.1} n_{.2}} .
$$

Table 14.1: Table of successes and failures

|  | Successes | Failures | Total |
| :--- | :---: | :---: | :---: |
| 1. experiment | $X$ | $m-X$ | $m$ |
| 2. experiment | $Y$ | $n-Y$ | $n$ |
| Total | $X+Y$ | $m+n-X-Y$ | $m+n$ |

The result is the formula for the variable $\chi^{2}$ in $2 \times 2$ contingency table (see formula (10.19)). We can say that frequently used statistic is $U_{b}$, whereas $U_{a}$ is rare.

Comparison of probabilities $p_{1}$ and $p_{2}$ in small samples can be found in the papers Santer, Snell (1980), Gart, Nam (1990), D'Agostino et al. (1988).

Example 14.2 It is not recommended to change quickly hot and cold meals because then the teeth have temperature shock. In an experiment 50 teeth were plunged into boiled and cold water. Other 50 teeth were in boiled water without temperature shocks. Finally, all teeth were crushed. From 50 teeth with temperature shocks 21 teeth were broken. From 50 teeth without shocks were only 11 broken. It should be tested if the temperature shocks influence mechanical resistance of teeth. (Osborn 1979).

We have $m=n=50, X=21, Y=11, x=0,42, y=0,22, z=0,32$. This gives

$$
U_{a}=2,195, \quad U_{b}=2,144
$$

If we test the hypothesis of homogeneity against two-sided alternative, we would compare the calculated results with the critical value $u(0.025)=1.96$. The result would be statistically significant. It means that the effect of temperature shocks is statistically proved.

However, our example leads to the test against one-sided alternative. Shocks cannot fasten the teeth. Thus the test statistics should be compared with the critical value $u(0.05)=1.645$. The results larger than this critical values are significant. In the introduced example the hypothesis $H_{0}$ must be rejected.

In program $R$ we get

```
zlomene.zuby <- c(21,11)
zuby.celkem <- c(50,50)
prop.test(zlomene.zuby, zuby.celkem)
    2-sample test for equality of proportions with continuity correction
data: zlomene.zuby out of zuby.celkem X-squared = 3.7224, df = 1, p-value = 0.05369
alternative hypothesis: two.sided 95 percent
confidence interval:
    0.001395761 0.398604239
sample estimates: prop 1 prop 2
    0.42 0.22
```

Since we used the continuity correction, the result is not significant. If we do not use the correction, we would have
prop.test(zlomene.zuby, zuby.celkem, correct =F)
2-sample test for equality of proportions without continuity correction

```
data: zlomene.zuby out of zuby.celkem X-squared = 4.5956, df = 1, p-value = 0.03205
alternative hypothesis: two.sided 95 percent
confidence interval:
    0.02139576 0.37860424
```

sample estimates: prop 1 prop 2
$0.42 \quad 0.22$

It gives significant result. One-sided test is
prop.test(zlomene.zuby, zuby.celkem, correct = F, alternative="greater")
which gives significant result
X-squared $=4.5956, \mathrm{df}=1, \mathrm{p}$-value $=0.01603$
$\diamond$

### 14.2 Confidence interval for difference of probabilities

Let $X \sim \operatorname{Bi}\left(m, p_{1}\right)$ and $Y \sim \operatorname{Bi}\left(n, p_{2}\right)$ be independent random variables. The problem is to find confidence interval for $\Delta=p_{1}-p_{2}$. A review of 11 methods described in papers for a construction of this interval can be found in Newcombe (1998). Here we introduce only three of them.

Denote $\hat{p}_{1}=X / m, \hat{p}_{2}=Y / n, \hat{\Delta}=\hat{p}_{1}-\hat{p}_{2}, q_{i}=1-p_{i}, \hat{q}_{i}=1-\hat{p}_{i}(i=1,2)$. Let $u_{\alpha}$ be the critical value of the distribution $\mathrm{N}(0,1)$ on the level $\alpha$. Then $\hat{p}_{1} \hat{q}_{1} / m+\hat{p}_{2} \hat{q}_{2} / n$ is estimator of var $\Delta$. Since the random variable

$$
T=(\hat{\Delta}-\Delta) / \sqrt{\hat{p}_{1} \hat{q}_{1} / m+\hat{p}_{2} \hat{q}_{2} / n}
$$

has asymptotically distribution $\mathrm{N}(0,1)$, Wald confidence interval is

$$
\hat{\Delta} \mp u_{\alpha / 2} \sqrt{\hat{p}_{1} \hat{q}_{1} / m+\hat{p}_{2} \hat{q}_{2} / n} .
$$

Denote $u=u_{\alpha / 2}$. Let $\left(l_{i}, u_{i}\right)$ be the Wilson confidence interval for $p_{i}$. As we know, endpoints of this interval are roots of quadratic equation

$$
\left(\hat{p}_{i}-p_{i}\right)^{2}=u^{2} p_{i}\left(1-p_{i}\right) / n_{i} .
$$

Then Newcomb confidence interval is

$$
\left(\hat{\Delta}-u \sqrt{\frac{l_{1}\left(1-l_{1}\right)}{m}+\frac{u_{2}\left(1-u_{2}\right)}{n}}, \hat{\Delta}+u \sqrt{\frac{u_{1}\left(1-u_{1}\right)}{m}+\frac{l_{2}\left(1-l_{2}\right)}{n}}\right) .
$$

Confidence interval based on score test is obtained by inverting test

$$
\frac{\hat{p}_{1}-\hat{p}_{2}-\Delta}{\hat{\sigma}}=u_{\alpha},
$$

where

$$
\hat{\sigma}^{2}=\frac{\hat{p}_{1}\left(1-\hat{p}_{1}\right)}{m}+\frac{\left(\hat{p}_{1}-\Delta\right)\left(1-\hat{p}_{1}+\Delta\right)}{n}
$$

and $\hat{p}_{1}$ is maximum likelihood estimator of the probability $p_{1}$ under the condition $\hat{p}_{1}-\hat{p}_{2}=$ $\Delta$. Explicit solution is not known, numerical methods can be used.

The following conclusions follow from numerical studies (see Brown, Li 2003):

- If the sizes $m$ and $n$ are small, then the Wald confidence interval has confidence coefficient smaller than its nominal value. However, its length is short.
- Score and Newcomb intervals behave similarly and have good properties.
- If $\min (m, n) \geq 50$, then all confidence intervals give good results.

Thus Brown, Li (2003) apart from the test suggested in their paper and called recentred recommend to use score and Newcomb intervals. Because there exists explicit formula for the Newcomb interval, its use can be especially recommended.

### 14.3 Confidence interval for ratio of probabilities

Let $X \sim \operatorname{Bi}\left(n_{1}, p_{1}\right)$ and $Y \sim \operatorname{Bi}\left(n_{2}, p_{2}\right)$. Assume that $X$ and $Y$ are independent variables. Denote

$$
\theta=\frac{p_{1}}{p_{2}}, \quad q_{1}=1-p_{1}, \quad q_{2}=1-p_{2}, \quad x=\frac{X}{n_{1}}, \quad y=\frac{Y}{n_{2}} .
$$

It is known that

$$
\mathrm{E} x=p_{1}, \quad \mathrm{E} y=p_{2}, \quad \operatorname{var} x=\frac{p_{1} q_{1}}{n_{1}}, \quad \operatorname{var} y=\frac{p_{2} q_{2}}{n_{2}}
$$

Introduce function $g(u, v)=u / v$. The value $g(x, y)=x / y$ can be expressed using Taylor expansion around the point $\left(p_{1}, p_{2}\right)$. If we neglect the remaining term we have

$$
g(x, y)=g\left(p_{1}, p_{2}\right)+\frac{1}{p_{2}}\left(x-p_{1}\right)-\frac{p_{1}}{p_{2}^{2}}\left(y-p_{2}\right) .
$$

In the frame of this approximation we have

$$
\begin{aligned}
\mathrm{E} \frac{x}{y} & =\frac{p_{1}}{p_{2}} \\
\mathrm{E} \frac{x^{2}}{y^{2}} & =\frac{p_{1}^{2}}{p_{2}^{2}}+\frac{1}{p_{2}^{2}} \frac{p_{1} q_{1}}{n_{1}}+\frac{p_{1}^{2}}{p_{2}^{4}} \frac{p_{2} q_{2}}{n_{2}} \\
\operatorname{var} \frac{x}{y} & =\mathrm{E} \frac{x^{2}}{y^{2}}-\left(\mathrm{E} \frac{x}{y}\right)^{2}=\frac{p_{1}^{2}}{p_{2}^{2}}\left(\frac{q_{1}}{p_{1} n_{1}}+\frac{q_{2}}{p_{2} n_{2}}\right) .
\end{aligned}
$$

It can be proved that for $n_{1} \rightarrow \infty, n_{2} \rightarrow \infty$ the ratio $x / y$ has asymptotically normal distribution and

$$
U^{*}=\frac{\frac{x}{y}-\frac{p_{1}}{p_{2}}}{\frac{p_{1}}{p_{2}} \sqrt{\frac{q_{1}}{p_{1} n_{1}}+\frac{q_{2}}{p_{2} n_{2}}}}
$$

has asymptotically $N(0,1)$ distribution. An exact proof of this assertion can be performed using delta method. In the denominator $p_{1}$ is approximated using $x$, then $p_{2}$ using $y, q_{1}$ using $1-x$ and $q_{2}$ using $1-y$. Then

$$
U=\frac{\frac{x}{y}-\theta}{\frac{x}{y} \sqrt{\frac{1-x}{x n_{1}}+\frac{1-y}{y n_{2}}}}
$$

has asymptotically $\mathrm{N}(0,1)$ distribution, so that the event

$$
\frac{\left|\frac{x}{y}-\theta\right|}{\frac{x}{y} \sqrt{\frac{1-x}{x n_{1}}+\frac{1-y}{y n_{2}}}} \leq u_{\alpha / 2}
$$

has asymptotically probability $1-\alpha$. This implies that

$$
\frac{x}{y}\left(1 \pm u_{\alpha / 2} \sqrt{\frac{1-x}{x n_{1}}+\frac{1-y}{y n_{2}}}\right)
$$

are endpoints of the confidence interval for $\theta=p_{1} / p_{2}$ with confidence coefficient which is asymptotically equal to $1-\alpha$. A detailed derivation of this confidence interval and some other intervals can be found in the paper Noether (1957).

### 14.4 Test of hypothesis $\lambda_{1} / \lambda_{2}=r$

Let $X_{1}$ and $X_{2}$ be independent random variables such that $X_{1} \sim \operatorname{Po}\left(\lambda_{1}\right), X_{2} \sim \operatorname{Po}\left(\lambda_{2}\right)$. Denote $\gamma=\lambda_{1} / \lambda_{2}$. Consider a test of hypothesis $H_{0}: \gamma=r$ against several alternatives.

We have $\lambda_{1}=\gamma \lambda_{2}$. Since $X_{1}+X_{2} \sim \operatorname{Po}\left(\lambda_{1}+\lambda_{2}\right)=\operatorname{Po}\left(\gamma \lambda_{2}+\lambda_{2}\right)$, we obtain

$$
\begin{aligned}
\mathrm{P}\left(X_{1}=x_{1}, X_{2}=x_{2} \mid X_{1}+X_{2}=x_{1}+x_{2}\right) & =\frac{\frac{\left(\gamma \lambda_{2}\right)^{x_{1}}}{x_{1}!} \mathrm{e}^{-\gamma \lambda_{2}} \frac{\lambda_{2}^{x_{2}}}{x_{2}!} \mathrm{e}^{-\gamma_{2}}}{\frac{\left(\gamma \lambda_{2}+\lambda_{2}\right)^{x_{1}+x_{2}}}{\left(x_{1}+x_{2}\right)!} \mathrm{e}^{-\left(\gamma \lambda_{2}+\lambda_{2}\right)}} \\
& =\binom{x_{1}+x_{2}}{x_{1}}\left(\frac{\gamma}{\gamma+1}\right)^{x_{1}}\left(1-\frac{\gamma}{\gamma+1}\right)^{x_{2}} .
\end{aligned}
$$

Conditional distribution is binomial. When testing $H_{0}$ against the alternative $H_{1}$ : $\gamma>r$, then $H_{0}$ will be rejected in the case

$$
\begin{equation*}
\sum_{i=x_{1}}^{x_{1}+x_{2}}\binom{x_{1}+x_{2}}{i}\left(\frac{r}{r+1}\right)^{i}\left(1-\frac{r}{r+1}\right)^{x_{1}+x_{2}-i} \leq \alpha \tag{14.4}
\end{equation*}
$$

Similarly, when testing $H_{0}$ against $H_{1}^{\prime}: \gamma<r$ we reject $H_{0}$ in the case that

$$
\begin{equation*}
\sum_{i=0}^{x_{1}}\binom{x_{1}+x_{2}}{i}\left(\frac{r}{r+1}\right)^{i}\left(1-\frac{r}{r+1}\right)^{x_{1}+x_{2}-i} \leq \alpha \tag{14.5}
\end{equation*}
$$

Test $H_{0}$ against $H_{1}^{*}: \gamma \neq r$ is usually carried out so that it is found out if at least one of inequalities (14.4) and (14.5) holds when $\alpha$ is substituted by the number $\alpha / 2$. There exist also other variants of the two-sided test.

Example 14.3 We introduce an example which is presented in the book Hátle, Likeš (1972), p. 334. It is known that the number of failures of an equipment during 100 hours of operation is a random variable with Poisson distribution. Equipment A had 8 failures and equipment B 5 failures. If $\mathrm{A} \sim \operatorname{Po}\left(\lambda_{1}\right)$ and $\mathrm{B} \sim \operatorname{Po}\left(\lambda_{2}\right)$ and failures occur independently, we want to test $H_{0}: \lambda=1$ against $H_{1}: \lambda>1$. This can be done using program
library(stats)
poisson.test(c(8,5), r=1, alternative="greater")
Comparison of Poisson rates
data: $c(8,5)$
time base: 1
count1 $=8$, expected count1 $=6.5, \mathrm{p}$-value $=0.2905$
alternative hypothesis: true rate ratio is greater than 1
95 percent confidence interval:
0.5499053 Inf
sample estimates: rate ratio
1.6

Right hand side confidence interval for $\lambda$ is $(0.5499, \infty), p$-value is 0.2905 . Hypothesis $H_{0}: \lambda=1$ is not rejected.

Another program can be based on function poisson. exact in library exactci. Onesided tests in both cases give the same result, but the function poisson. exact in twosided test presents three different variants.

## Chapter 15

## Problem of $k$ samples

### 15.1 Linear model

This section is an introduction and it serves as theoretical background for methods of analysis of variance described later in this chapter. The results will be also used in the chapter devoted to regression analysis.

Let $\boldsymbol{Y}=\left(Y_{1}, \ldots, Y_{n}\right)^{\prime}$ be a random vector and $\boldsymbol{X}_{n \times k}$ a matrix of given numbers. Assume that $\boldsymbol{Y}$ follows linear model

$$
\begin{equation*}
\boldsymbol{Y}=\boldsymbol{X} \boldsymbol{\beta}+\boldsymbol{e} \tag{15.1}
\end{equation*}
$$

where $\boldsymbol{\beta}=\left(\beta_{1}, \ldots, \beta_{k}\right)^{\prime}$ is a vector of unknown parameters and $\boldsymbol{e}=\left(e_{1}, \ldots, e_{n}\right)^{\prime}$ is a vector of random variables satisfying conditions

$$
\mathrm{E} \boldsymbol{e}=\mathbf{0}, \quad \operatorname{var} \boldsymbol{e}=\sigma^{2} \boldsymbol{I}
$$

The parameter $\sigma^{2}>0$ is also not known. However, the vector $\boldsymbol{Y}$ is observable. It can be characterized as vector of errors. Under the term "errors" they are understood errors which follow from inaccuracies when the vector $\boldsymbol{Y}$ is measured, sometimes the errors include deviations from the exact linear dependence $\boldsymbol{Y}=\boldsymbol{X} \boldsymbol{\beta}$. The vector $\boldsymbol{e}$ is not observable. The assumption $\mathrm{E} \boldsymbol{e}=\mathbf{0}$ reflect the fact that observations of vector $\boldsymbol{Y}$ do not include systematic errors. The relation var $\boldsymbol{e}=\sigma^{2} \boldsymbol{I}$ says that the measurements of different components of the vector $\boldsymbol{Y}$ are made with equal precision, and the errors of measurements of different components of the vector $\boldsymbol{Y}$ are uncorrelated.

For simplicity we assume in this section that the rank of the matrix $\boldsymbol{X}$ is $k$ and that $n>k$. Linear model (15.1) which fulfills these additional assumptions is called regression model.

It follows from our assumptions that $\mathbf{E} \boldsymbol{Y}=\boldsymbol{X} \boldsymbol{\beta}, \operatorname{var} \boldsymbol{Y}=\sigma^{2} \boldsymbol{I}$. Vector $\boldsymbol{\beta}$ is estimated using least squares method, i.e. from the condition that the expression

$$
S(\boldsymbol{\beta})=(\boldsymbol{Y}-\boldsymbol{X} \boldsymbol{\beta})^{\prime}(\boldsymbol{Y}-\boldsymbol{X} \boldsymbol{\beta})
$$

is minimal. This estimator is denoted by $\boldsymbol{b}=\left(b_{1}, \ldots, b_{k}\right)^{\prime}$.
It is known that for every matrix $\boldsymbol{A}$ it holds $h(\boldsymbol{A})=h\left(\boldsymbol{A} \boldsymbol{A}^{\prime}\right)=h\left(\boldsymbol{A}^{\prime} \boldsymbol{A}\right)$, where $h(\boldsymbol{A})$ denotes the rank of he matrix $\boldsymbol{A}$. Since $h(\boldsymbol{X})=k$ and the matrix $\boldsymbol{X}^{\prime} \boldsymbol{X}$ is of type $k \times k$, we conclude that the matrix $\boldsymbol{X}^{\prime} \boldsymbol{X}$ is regular.

Theorem 15.1 It holds $\boldsymbol{b}=\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{X}^{\prime} \boldsymbol{Y}$.
Proof. First, we verify that the vector $\boldsymbol{b}$ introduced in assertion of the theorem fulfills the condition $\boldsymbol{X}^{\prime}(\boldsymbol{Y}-\boldsymbol{X} \boldsymbol{b})=\mathbf{0}$. Then we write $S(\boldsymbol{\beta})$ in the form

$$
S(\boldsymbol{\beta})=[(\boldsymbol{Y}-\boldsymbol{X} \boldsymbol{b})+(\boldsymbol{X} \boldsymbol{b}-\boldsymbol{X} \boldsymbol{\beta})]^{\prime}[(\boldsymbol{Y}-\boldsymbol{X} \boldsymbol{b})+(\boldsymbol{X} \boldsymbol{b}-\boldsymbol{X} \boldsymbol{\beta})] .
$$

Using the condition $\boldsymbol{X}^{\prime}(\boldsymbol{Y}-\boldsymbol{X} \boldsymbol{b})=\mathbf{0}$ we get

$$
S(\boldsymbol{\beta})=(\boldsymbol{Y}-\boldsymbol{X} \boldsymbol{b})^{\prime}(\boldsymbol{Y}-\boldsymbol{X} \boldsymbol{b})+(\boldsymbol{b}-\boldsymbol{\beta})^{\prime} \boldsymbol{X}^{\prime} \boldsymbol{X}(\boldsymbol{b}-\boldsymbol{\beta}) .
$$

It follows from the assumption $h(\boldsymbol{X})=k$ that the matrix $\boldsymbol{X}^{\prime} \boldsymbol{X}$ is positive definite. Thus

$$
(\boldsymbol{b}-\boldsymbol{\beta})^{\prime} \boldsymbol{X}^{\prime} \boldsymbol{X}(\boldsymbol{b}-\boldsymbol{\beta}) \geq 0
$$

and equality holds if and only if $\boldsymbol{\beta}=\boldsymbol{b}$.
The vector $\boldsymbol{b}$ can be calculated from the system of normal equations $\boldsymbol{X}^{\prime} \boldsymbol{X} \boldsymbol{b}=\boldsymbol{X}^{\prime} \boldsymbol{Y}$. The expression

$$
R=(\boldsymbol{Y}-\boldsymbol{X} \boldsymbol{b})^{\prime}(\boldsymbol{Y}-\boldsymbol{X} \boldsymbol{b})
$$

is called residual sum of squares and it plays an important role in statistical tests. Quite often instead of $R$ the denotation $S_{e}$ is used. We shall also write $\hat{\boldsymbol{Y}}=\boldsymbol{X} \boldsymbol{b}$.

Theorem 15.2 The estimator $\boldsymbol{b}$ satisfies $\mathrm{E} \boldsymbol{b}=\boldsymbol{\beta}, \operatorname{var} \boldsymbol{b}=\sigma^{2}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1}$.
Proof. We have

$$
\begin{aligned}
\mathrm{E} \boldsymbol{b} & =\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{X}^{\prime} E \boldsymbol{Y}=\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{X}^{\prime} \boldsymbol{X} \boldsymbol{\beta}=\boldsymbol{\beta}, \\
\operatorname{var} \boldsymbol{b} & =\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{X}^{\prime} \sigma^{2} \boldsymbol{I} \boldsymbol{X}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1}=\sigma^{2}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1}
\end{aligned}
$$

Theorem 15.3 It holds

$$
R=\boldsymbol{Y}^{\prime}\left[\boldsymbol{I}-\boldsymbol{X}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{X}^{\prime}\right] \boldsymbol{Y}, \quad R=\boldsymbol{Y}^{\prime} \boldsymbol{Y}-\boldsymbol{b}^{\prime} \boldsymbol{X}^{\prime} \boldsymbol{Y}
$$

Proof. Denote $\boldsymbol{M}=\boldsymbol{I}-\boldsymbol{X}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{X}^{\prime}$. We can write

$$
\boldsymbol{Y}-\boldsymbol{X} \boldsymbol{b}=\boldsymbol{Y}-\boldsymbol{X}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{X}^{\prime} \boldsymbol{Y}=\boldsymbol{M} \boldsymbol{Y}
$$

The matrix $\boldsymbol{M}$ is symmetric and idempotent, so that $\boldsymbol{M}^{2}=\boldsymbol{M}$. Thus

$$
R=(\boldsymbol{Y}-\boldsymbol{X} \boldsymbol{b})^{\prime}(\boldsymbol{Y}-\boldsymbol{X} \boldsymbol{b})=\boldsymbol{Y}^{\prime} \boldsymbol{M}^{\prime} \boldsymbol{M} \boldsymbol{Y}=\boldsymbol{Y}^{\prime} \boldsymbol{M} \boldsymbol{Y}
$$

The first formula is proved. The second formula follows from the first one.
Further we shall use the following auxiliary theorem.
Theorem 15.4 Let the random vector $\boldsymbol{Z}=\left(Z_{1}, \ldots, Z_{n}\right)^{\prime}$ have finite second moments and let $\mathrm{E} \boldsymbol{Z}=\boldsymbol{\mu}, \operatorname{var} \boldsymbol{Z}=\boldsymbol{V}$. Then for arbitrary matrix $\boldsymbol{A}_{n \times n}$ we have $\mathrm{E} \boldsymbol{Z}^{\prime} \boldsymbol{A} \boldsymbol{Z}=$ $\operatorname{Tr} \boldsymbol{A} \boldsymbol{V}+\boldsymbol{\mu}^{\prime} \boldsymbol{A} \boldsymbol{\mu}$.

Proof. Since var $\boldsymbol{Z}=\mathrm{E}(\boldsymbol{Z}-\boldsymbol{\mu})(\boldsymbol{Z}-\boldsymbol{\mu})^{\prime}=\mathrm{E} \boldsymbol{Z} \boldsymbol{Z}^{\prime}-\boldsymbol{\mu} \boldsymbol{\mu}^{\prime}$, we obtain

$$
\mathrm{E} \boldsymbol{Z}^{\prime} \boldsymbol{A} \boldsymbol{Z}=\mathrm{E} \operatorname{Tr} \boldsymbol{A} \boldsymbol{Z} \boldsymbol{Z}^{\prime}=\operatorname{Tr} \boldsymbol{A} \mathrm{E} \boldsymbol{Z} \boldsymbol{Z}^{\prime}=\operatorname{Tr} \boldsymbol{A}\left(\boldsymbol{V}+\boldsymbol{\mu} \boldsymbol{\mu}^{\prime}\right)=\operatorname{Tr} \boldsymbol{A} \boldsymbol{V}+\boldsymbol{\mu}^{\prime} \boldsymbol{A} \boldsymbol{\mu}
$$

Theorem 15.5 Denote $s^{2}=R /(n-k)$. Then $\mathrm{E} s^{2}=\sigma^{2}$.
Proof. We use theorems 15.3 and 15.4. Since E $\boldsymbol{Y}=\boldsymbol{X} \boldsymbol{\beta}$ and $\boldsymbol{M} \boldsymbol{X}=\mathbf{0}$, we obtain

$$
\mathrm{E} R=\mathrm{E} \boldsymbol{Y}^{\prime} \boldsymbol{M} \boldsymbol{Y}=\operatorname{Tr} \boldsymbol{M} \sigma^{2} \boldsymbol{I}+\boldsymbol{\beta}^{\prime} \boldsymbol{X}^{\prime} \boldsymbol{M} \boldsymbol{X} \boldsymbol{\beta}=\sigma^{2} \operatorname{Tr} \boldsymbol{M}=(n-k) \sigma^{2}
$$

Variable $s^{2}$ is called residual variance. We proved that $s^{2}$ is unbiased estimator of the parameter $\sigma^{2}$.

Now, we shall also assume that the vector $\boldsymbol{e}$ is normally distributed. This implies immediately that $\boldsymbol{Y} \sim \mathrm{N}\left(\boldsymbol{X} \boldsymbol{\beta}, \sigma^{2} \boldsymbol{I}\right)$.

Theorem 15.6 Under assumption of normal distribution we have
(a) $\boldsymbol{b} \sim \mathrm{N}\left[\boldsymbol{\beta}, \sigma^{2}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1}\right]$,
(b) $\frac{R}{\sigma^{2}} \sim \chi_{n-k}^{2}$,
(c) $\boldsymbol{b}$ and $R$ are independent.

Proof. Assertion (a) follows from theorem 15.1 because linear transformation of normally distributed vector is again a vector with normal distribution.

Now, we prove (b). It is known that rank of an idempotent matrix is equal to its trace. The trace of matrix $\boldsymbol{A}$ will be denoted by $\operatorname{Tr} \boldsymbol{A}$. For arbitrary matrices $\boldsymbol{K}$ a $\boldsymbol{L}$, such that their product is a square matrix we have $\operatorname{Tr} \boldsymbol{K} \boldsymbol{L}=\operatorname{Tr} \boldsymbol{L} \boldsymbol{K}$. Define $\boldsymbol{\xi}=(\boldsymbol{Y}-\boldsymbol{X} \boldsymbol{b}) / \sigma$. We insert for $\boldsymbol{b}$ and obtain $\boldsymbol{\xi}=\sigma^{-1} \boldsymbol{M} \boldsymbol{Y}$, where $\boldsymbol{M}=\boldsymbol{I}-\boldsymbol{X}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right) \boldsymbol{X}^{\prime}$. Thus $\boldsymbol{\xi} \sim \mathrm{N}(\mathbf{0}, \boldsymbol{M})$. Matrix $\boldsymbol{M}$ is idempotent and its rank equals to

$$
\begin{aligned}
h(\boldsymbol{M}) & =\operatorname{Tr}\left[\boldsymbol{I}-\boldsymbol{X}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{X}^{\prime}\right]=\operatorname{Tr} \boldsymbol{I}-\operatorname{Tr} \boldsymbol{X}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{X}^{\prime} \\
& =n-\operatorname{Tr}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{X}^{\prime} \boldsymbol{X}=n-k .
\end{aligned}
$$

Since $R / \sigma^{2}=\boldsymbol{\xi}^{\prime} \boldsymbol{\xi}$, property (b) follows from theorem 3.8 on p. 39 .
Finally, we calculate

$$
\operatorname{cov}(\boldsymbol{b}, \boldsymbol{\xi})=\operatorname{cov}\left[\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{X}^{\prime} \boldsymbol{Y}, \sigma^{-1} \boldsymbol{M} \boldsymbol{Y}\right]=\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{X}^{\prime} \sigma^{2} \boldsymbol{I} \sigma^{-1} \boldsymbol{M}=\mathbf{0}
$$

Vectors $\boldsymbol{b}$ and $\boldsymbol{\xi}$ are uncorrelated. Since

$$
\binom{\boldsymbol{b}}{\boldsymbol{\xi}}=\left[\begin{array}{c}
\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{X}^{\prime} \\
\sigma^{-1} \boldsymbol{M}
\end{array}\right] \boldsymbol{Y}
$$

they have simultaneous normal distribution. Thus $\boldsymbol{b}$ and $\sigma^{2} \boldsymbol{\xi}^{\prime} \boldsymbol{\xi}=R$ are also independent.

Theorem 15.7 Let $v_{i j}$ be $(i, j)$-th element of the matrix $\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1}$. Then for every $i=$ $1, \ldots, k$ the random variable

$$
T_{i}=\frac{b_{i}-\beta_{i}}{\sqrt{s^{2} v_{i i}}}
$$

has the distribution $\mathrm{t}_{n-k}$.

Proof. It follows from theorem 15.6 (a) that $b_{i} \sim \mathrm{~N}\left(\beta_{i}, \sigma^{2} v_{i i}\right)$. Define

$$
U_{i}=\frac{b_{i}-\beta_{i}}{\sigma \sqrt{v_{i i}}}
$$

We can see that $U_{i} \sim \mathrm{~N}(0,1)$. Theorem 15.6 (b) gives that the variable $Z=(n-k) s^{2} / \sigma^{2}$ has distribution $\chi_{n-k}^{2}$. Finally, assertion (c) from theorem 15.6 ensures independence $U_{i}$ and $Z$. We know from theorem 3.10 that

$$
T_{i}=\frac{U_{i}}{\sqrt{Z /(n-k)}} \sim \mathrm{t}_{n-k} .
$$

Theorem 15.8 Let $\boldsymbol{c}=\left(c_{1}, \ldots, c_{k}\right)^{\prime} \neq \mathbf{0}$ be a given vector. Then $\mathbf{E} \boldsymbol{c}^{\prime} \boldsymbol{b}=\boldsymbol{c}^{\prime} \boldsymbol{\beta}$ and

$$
T=\frac{\boldsymbol{c}^{\prime} \boldsymbol{b}-\boldsymbol{c}^{\prime} \boldsymbol{\beta}}{\sqrt{s^{2} \boldsymbol{c}^{\prime}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{c}}} \sim \mathrm{t}_{n-k}
$$

Proof. The unbiasednes of the estimator $\boldsymbol{c}^{\prime} \boldsymbol{b}$ is obvious. From theorem 15.2 we obtain

$$
\operatorname{var} \boldsymbol{c}^{\prime} \boldsymbol{b}=\sigma^{2} \boldsymbol{c}^{\prime}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{c}
$$

Thus

$$
U=\frac{\boldsymbol{c}^{\prime} \boldsymbol{b}-\boldsymbol{c}^{\prime} \boldsymbol{\beta}}{\sqrt{\sigma^{2} \boldsymbol{c}^{\prime}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{c}}} \sim \mathrm{~N}(0,1)
$$

Since $U$ depends only on $\boldsymbol{b}$, it does not depend on $Z=(n-k) s^{2} / \sigma^{2}$. It is easy to see that

$$
T=\frac{U}{\sqrt{Z /(n-k)}}
$$

Theorem 3.10 ensures that $T \sim \mathrm{t}_{n-k}$.
Let us remark that theorem 15.7 is special case of theorem 15.8. It suffices to choose vector $\boldsymbol{c}$ in such a way that its $i$-th component equals to 1 and the remaining components are all 0 .

Vector $\boldsymbol{u}=\boldsymbol{Y}-\hat{\boldsymbol{Y}}$ is called vector of residuals. It is easy to check that

$$
\boldsymbol{u}=\boldsymbol{M} \boldsymbol{Y}, \quad \mathrm{E} \boldsymbol{u}=\mathbf{0}, \quad \operatorname{var} \boldsymbol{u}=\sigma^{2} \boldsymbol{M}
$$

Let $m_{i j}$ be elements of the matrix $\boldsymbol{M}$ and $h_{i j}$ elements of the matrix $\boldsymbol{H}=\boldsymbol{X}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{X}^{\prime}$. We see that the matrix var $\boldsymbol{e}$ is diagonal with equal elements on the diagonal, the matrix $\operatorname{var} \boldsymbol{u}$ has not this property. From this reason normed residuals

$$
v_{t}=\frac{u_{t}}{s \sqrt{m_{t t}}}=\frac{u_{t}}{s \sqrt{1-h_{t t}}}
$$

are used. The observation $Y_{i}$ is influential if its small change leads to rather large change of vector $\hat{\boldsymbol{Y}}$. The influential observations can be detected by diagonal elements $h_{i i}$ of the matrix $\boldsymbol{H}$. The elements $h_{i i}$ are called leverages, i.e. influences. It can be proved that $\sum h_{i i}=k, h_{i i} \geq 1 / n$ for every $i$. If $h_{i i}>2 k / n$ then such observation is influential. The influence of individual observations is measured using Cook statistics

$$
D_{i}=\frac{\left(\boldsymbol{b}-\boldsymbol{b}_{(i)}\right)^{\prime} \boldsymbol{X}^{\prime} \boldsymbol{X}\left(\boldsymbol{b}-\boldsymbol{b}_{(i)}\right)}{k s^{2}}
$$

where $\boldsymbol{b}_{(i)}$ is estimator of the vector $\boldsymbol{\beta}$ when the $i$-th observation is excluded.

### 15.2 Weighted average

In some cases it is necessary to apply the least squares method, although the observations have not the same variances. A model for such situation we investigate in this section.

Theorem 15.9 Let $Y_{1}, \ldots, Y_{n}$ be independent random variables. Assume that $\mathrm{E} Y_{i}=\beta$, $\operatorname{var} Y_{i}=\sigma_{i}^{2}>0$, where $\beta$ is an unknown parameter and $\sigma_{1}^{2}, \ldots, \sigma_{n}^{2}$ are known numbers. Then the estimator $b$ of the parameter $\beta$ by the least squares method is

$$
\begin{equation*}
b=\frac{\sum_{j=1}^{n} \sigma_{j}^{-2} Y_{j}}{\sum_{i=1}^{n} \sigma_{i}^{-2}} \tag{15.2}
\end{equation*}
$$

and it holds

$$
\mathrm{E} b=\beta, \quad \operatorname{var} b=\left(\sum_{i=1}^{n} \sigma_{i}^{-2}\right)^{-1}
$$

Proof. Variables $Y_{i}$ correspond to the model

$$
\begin{equation*}
Y_{i}=\beta+e_{i}, \quad i=1, \ldots, n \tag{15.3}
\end{equation*}
$$

where $e_{i}$ are independent variables with moments $\operatorname{Ee} e_{i}=0$, var $e_{i}=\sigma_{i}^{2}$. Variables $e_{i}$ have not equal variances so that it is not possible to use results derived in section 15.1. If we multiply (15.3) by expression $\sigma_{i}^{-1}$, we get

$$
\begin{equation*}
Z_{i}=\sigma_{i}^{-1} \beta+e_{i}^{*}, \quad i=1, \ldots, n, \tag{15.4}
\end{equation*}
$$

where $Z_{i}=\sigma_{i}^{-1} Y_{i}$ and $e_{i}^{*}=\sigma_{i}^{-1} e_{i}$. Now, the variables $e_{i}^{*}$ are not only independent with vanishing expectations, but they have the same variances var $e_{i}^{*}=1$. Thus we can write (15.4) in the form $\boldsymbol{Z}=\boldsymbol{X} \beta+\boldsymbol{e}^{*}$, where

$$
\boldsymbol{Z}=\left(Z_{1}, \ldots, Z_{n}\right)^{\prime}, \quad \boldsymbol{X}=\left(\sigma_{1}^{-1}, \ldots, \sigma_{n}^{-1}\right)^{\prime}, \quad \boldsymbol{e}^{*}=\left(e_{1}^{*}, \ldots, e_{n}^{*}\right)^{\prime}
$$

From theorem 15.1 we get for arbitrary $\beta$ least squares estimator

$$
b=\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{X}^{\prime} \boldsymbol{Z}=\frac{\sum_{j=1}^{n} \sigma_{j}^{-2} Y_{j}}{\sum_{i=1}^{n} \sigma_{i}^{-2}}
$$

Unbiasednes of the estimator $b$ and the formula for $\operatorname{var} b$ follow from theorem 15.2.
It can be proved that $b$ is the best linear unbiased estimator - BLUE - of the parameter $\beta$.

Theorem 15.10 Let the variables $Y_{i}$ fulfil assumptions of theorem 15.9 and, moreover, have normal distribution. Then the estimator $b$ is also normally distributed and the random variable

$$
Q=\sum_{i=1}^{n} \frac{\left(Y_{i}-b\right)^{2}}{\sigma_{i}^{2}}
$$

has $\chi_{n-1}^{2}$ distribution.

Proof. It is obvious that $b$ has normal distribution, since $b$ in view of (15.2) is a linear function of normally distributed vector $\boldsymbol{Y}$. Further we get

$$
\begin{align*}
Q & =\sum_{i} \sigma_{i}^{-2} Y_{i}^{2}-\left(\sum_{i} \sigma_{i}^{-2}\right)^{-1} \sum_{j} \sigma_{j}^{-2} Y_{j} \sum_{k} \sigma_{k}^{-2} Y_{k}  \tag{15.5}\\
& =\sum_{i} Z_{i}^{2}-\left(\sum_{i} \sigma_{i}^{-2}\right)^{-1} \sum_{j} \sigma_{j}^{-1} Z_{j} \sum_{k} \sigma_{k}^{-1} Z_{k},
\end{align*}
$$

where $Z_{i}=\sigma_{i}^{-1} Y_{i}$. We can see that $Q=\boldsymbol{Z}^{\prime} \boldsymbol{A} \boldsymbol{Z}$, with

$$
\boldsymbol{A}=\boldsymbol{I}-\left(\sum_{i} \sigma_{i}^{-2}\right)^{-1}\left(\begin{array}{c}
\sigma_{1}^{-1} \\
\vdots \\
\sigma_{n}^{-1}
\end{array}\right)\left(\sigma_{1}^{-1}, \ldots, \sigma_{n}^{-1}\right)
$$

Matrix $\boldsymbol{A}$ is idempotent and its rank (which is equal to its trace) equals to $n-1$. Expectation of the vector $\boldsymbol{Z}$ is

$$
\mathbf{E} \boldsymbol{Z}=\left(\sigma_{1}^{-1}, \ldots, \sigma_{n}^{-1}\right)^{\prime} \beta
$$

Vector $\boldsymbol{Z}-\mathrm{E} \boldsymbol{Z}$ has distribution $\mathrm{N}(\mathbf{0}, \boldsymbol{I})$. It can be checked that

$$
Q=\boldsymbol{Z}^{\prime} \boldsymbol{A} \boldsymbol{Z}=(\boldsymbol{Z}-\mathrm{E} \boldsymbol{Z})^{\prime} \boldsymbol{A}(\boldsymbol{Z}-\mathrm{E} \boldsymbol{Z})
$$

Theorem 3.9 implies that $Q \sim \chi_{n-1}^{2}$.
Theorem 15.10 can be used for testing hypothesis $H_{0}$, that all variables in model (15.3) have equal expectation. If $H_{0}$ does not hold, then $Q$ is large. Thus $H_{0}$ is rejected when $Q \geq \chi_{n-1}^{2}(\alpha)$.

### 15.3 Extrapolation in linear model

Assume that the model (15.1) holds. We expect that a new observation $Y_{0}$ will be realized, which will correspond to a new row of the matrix $\boldsymbol{X}$, say $\boldsymbol{x}_{0}^{\prime}=\left(x_{01}, \ldots, x_{0 k}\right)$. The new variable $Y_{0}$ follows the model $Y_{0}=\boldsymbol{x}_{0}^{\prime} \boldsymbol{\beta}+e_{0}$, where $e_{0}$ is a random variable with vanishing mean and with variance $\sigma^{2}$, which is independent of the vector of errors $\boldsymbol{e}$. We want to estimate the variable $Y_{0}$, i.e. to calculate its extrapolation. We intend to calculate a point estimator and an interval estimator. Obviously, $\hat{Y}_{0}=\boldsymbol{x}_{0}^{\prime} \boldsymbol{b}$ can serve as the point estimator. The interval estimator will be calculated under assumption of normality. Thus let $\boldsymbol{Y}$ be normal and $e_{0} \sim \mathbf{N}\left(0, \sigma^{2}\right)$. Then $Y_{0} \sim \mathbf{N}\left(\boldsymbol{x}_{0}^{\prime} \boldsymbol{\beta}, \sigma^{2}\right)$. We are interested in the difference

$$
\hat{Y}_{0}-Y_{0}=\boldsymbol{x}_{0}^{\prime} \boldsymbol{b}-\boldsymbol{x}_{0}^{\prime} \boldsymbol{\beta}-e_{0}=\boldsymbol{x}_{0}^{\prime}(\boldsymbol{b}-\boldsymbol{\beta})-e_{0} .
$$

Calculate its expectation and variance. We have

$$
\begin{aligned}
\mathrm{E}\left(\hat{Y}_{0}-Y_{0}\right) & =\mathrm{E}\left[\boldsymbol{x}_{0}^{\prime}(\boldsymbol{b}-\boldsymbol{\beta})-e_{0}\right]=0, \\
\operatorname{var}\left(\hat{Y}_{0}-Y_{0}\right) & =\operatorname{var}\left[\boldsymbol{x}_{0}^{\prime}(\boldsymbol{b}-\boldsymbol{\beta})-e_{0}\right]=\operatorname{var} \boldsymbol{x}_{0}^{\prime}(\boldsymbol{b}-\boldsymbol{\beta})-2 \operatorname{cov}\left[\boldsymbol{x}_{0}^{\prime}(\boldsymbol{b}-\boldsymbol{\beta}), e_{0}\right]+\operatorname{var} e_{0} .
\end{aligned}
$$

Since $\boldsymbol{b}$ and $e_{0}$ are independent, we have $\operatorname{cov}\left[\boldsymbol{x}_{0}^{\prime}(\boldsymbol{b}-\boldsymbol{\beta}), e_{0}\right]=0$. This gives

$$
\operatorname{var}\left(\hat{Y}_{0}-Y_{0}\right)=\boldsymbol{x}_{0}^{\prime}(\operatorname{var} \boldsymbol{b}) \boldsymbol{x}_{0}+\sigma^{2}=\sigma^{2} \boldsymbol{x}_{0}^{\prime}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{x}_{0}+\sigma^{2} .
$$

Denote

$$
\xi=\frac{\hat{Y}_{0}-Y_{0}}{\sigma \sqrt{\boldsymbol{x}_{0}^{\prime}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{x}_{0}+1}}, \quad \eta=\frac{(n-k) s^{2}}{\sigma^{2}}
$$

It was proved that $\xi \sim \mathbf{N}(0,1), \eta \sim \chi_{n-k}^{2}$ and that $\xi$ and $\eta$ are independent. Thus

$$
T=\frac{\xi}{\sqrt{\eta /(n-k)}} \sim \mathrm{t}_{n-k}
$$

This can be written in the form

$$
T=\frac{\hat{Y}_{0}-Y_{0}}{s \sqrt{\boldsymbol{x}_{0}^{\prime}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{x}_{0}+1}}
$$

and it follows from formula $\mathrm{P}\left\{|T| \leq t_{n-k}(\alpha)\right\}=1-\alpha$ that

$$
\begin{align*}
\mathrm{P}\left\{\hat{Y}_{0}-t_{n-k}(\alpha) s \sqrt{\boldsymbol{x}_{0}^{\prime}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{x}_{0}+1}\right. & \leq Y_{0}  \tag{15.6}\\
& \left.\leq \hat{Y}_{0}+t_{n-k}(\alpha) s \sqrt{\boldsymbol{x}_{0}^{\prime}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{x}_{0}+1}\right\}=1-\alpha .
\end{align*}
$$

Thus we derived confidence interval for $Y_{0}$ with confidence coefficient $1-\alpha$.

### 15.4 Submodel of the linear model

We say that the linear model

$$
\begin{equation*}
\boldsymbol{Y}=\boldsymbol{U} \boldsymbol{\gamma}+\boldsymbol{e} \tag{15.7}
\end{equation*}
$$

is submodel of the model (15.1), if the columns of the matrix $\boldsymbol{U}_{n \times l}$ are linear combinations of the columns of the matrix $\boldsymbol{X}$ and in the same time $h(\boldsymbol{U})=l<k$. Also here we shall deal only with such matrices $\boldsymbol{U}$, which have full column rank. It happens quite often that the submodel (15.7) arises from the model (15.1) by the omitting some columns of the matrix $\boldsymbol{X}$. It corresponds to the procedure where we define the corresponding components of the parameter $\boldsymbol{\beta}$ as zero. We show generally that linear bindings among the components of the vector $\boldsymbol{\beta}$ always lead to the submodel (15.7).

Theorem 15.11 Let the components of the vector $\boldsymbol{\beta}$ fulfil the condition $\boldsymbol{G} \boldsymbol{\beta}=\mathbf{0}$, where $h\left(\boldsymbol{G}_{t \times k}\right)=t<k$. Define $l=k-t$. Then there exists such a matrix $\boldsymbol{Q}_{l \times k}$ of rank $l$ and such a matrix $\boldsymbol{U}_{n \times l}$ of rank l, that the columns of the matrix $\boldsymbol{U}$ are linear combinations of the columns of the matrix $\boldsymbol{X}$ and it holds $\boldsymbol{X} \boldsymbol{\beta}=\boldsymbol{U} \boldsymbol{\gamma}$, where $\boldsymbol{\gamma}=\boldsymbol{Q} \boldsymbol{\beta}$.

Proof. Since $h\left(\boldsymbol{G}_{t \times k}\right)=t$, there exists such a matrix $\boldsymbol{Q}_{l \times k}$ that the matrix

$$
A=\binom{\boldsymbol{Q}}{\boldsymbol{G}}
$$

is regular. We shall write the matrix $\boldsymbol{X} \boldsymbol{A}^{-1}$ in the form $\boldsymbol{X} \boldsymbol{A}^{-1}=(\boldsymbol{U}, \boldsymbol{T})$, where $\boldsymbol{U}$ is of type $n \times l$ and $\boldsymbol{T}$ is of type $n \times t$. We have

$$
\boldsymbol{X} \boldsymbol{\beta}=\boldsymbol{X} \boldsymbol{A}^{-1} \boldsymbol{A} \boldsymbol{\beta}=\boldsymbol{X} \boldsymbol{A}^{-1}\binom{\boldsymbol{Q} \boldsymbol{\beta}}{\boldsymbol{G} \boldsymbol{\beta}}=(\boldsymbol{U}, \boldsymbol{T})\binom{\boldsymbol{Q} \boldsymbol{\beta}}{\mathbf{0}}=\boldsymbol{U} \boldsymbol{Q} \boldsymbol{\beta}=\boldsymbol{U} \boldsymbol{\gamma}
$$

It is important to realize that if the submodel (15.7) holds, then the model (15.1) holds, too. The estimator of the vector $\gamma$ using the least squares method is

$$
\boldsymbol{g}=\left(\boldsymbol{U}^{\prime} \boldsymbol{U}\right)^{-1} \boldsymbol{U}^{\prime} \boldsymbol{Y}
$$

and the residual variance $R_{1}$ in case of the submodel (15.7) is

$$
R_{1}=(\boldsymbol{Y}-\boldsymbol{U} \boldsymbol{g})^{\prime}(\boldsymbol{Y}-\boldsymbol{U} \boldsymbol{g})=\boldsymbol{Y}^{\prime}\left[\boldsymbol{I}-\boldsymbol{U}\left(\boldsymbol{U}^{\prime} \boldsymbol{U}\right)^{-1} \boldsymbol{U}^{\prime}\right] \boldsymbol{Y}
$$

At the same time it holds $R_{1} \geq R$, since $R$ is the minimum of the function $S(\boldsymbol{\beta})$ without any restriction on the vector $\boldsymbol{\beta}$, whereas $R_{1}$ is minimum of the function $S(\boldsymbol{\beta})$ under some subsidiary conditions (e.g. under condition $\boldsymbol{H} \boldsymbol{\beta}=\mathbf{0}$ ). Test of the hypothesis that the vector $\boldsymbol{\beta}$ fufills the subsidiary conditions, is the test of hypothesis that the model (15.1) can be reduced to the submodel (15.7). The test is based on the following theorem.

Theorem 15.12 If the submodel (15.7) holds (i.e. when the vector $\boldsymbol{\beta}$ is tied by $t=k-l$ linearly independent relations) then the random variable

$$
F=\frac{(n-k)\left(R_{1}-R\right)}{t R}
$$

has $\mathrm{F}_{t, n-k}$ distribution.

Proof. Again, denote $\boldsymbol{M}=\boldsymbol{I}-\boldsymbol{X}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{X}^{\prime}$ and $\boldsymbol{\xi}=\sigma^{-1} \boldsymbol{M} \boldsymbol{Y}$. In the proof of theorem 15.6 (c) it was derived that $\sigma^{2} \boldsymbol{\xi}^{\prime} \boldsymbol{\xi}=R$, and it follows from theorem 15.6 (b) that $\boldsymbol{\xi}^{\prime} \boldsymbol{\xi} \sim \chi_{n-k}^{2}$.

Denote $\boldsymbol{B}=\boldsymbol{X}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{X}^{\prime}-\boldsymbol{U}\left(\boldsymbol{U}^{\prime} \boldsymbol{U}\right)^{-1} \boldsymbol{U}^{\prime}$. Then $R_{1}-R=\boldsymbol{Y}^{\prime} \boldsymbol{B} \boldsymbol{Y}$. Let $\boldsymbol{\eta}=$ $\sigma^{-1} \boldsymbol{B} \boldsymbol{Y}$. Since the columns of the matrix $\boldsymbol{U}$ are linear combinations of the columns of matrix $\boldsymbol{X}$, there exists a matrix $\boldsymbol{K}_{k \times l}$ such that $\boldsymbol{U}=\boldsymbol{X} \boldsymbol{K}$. Matrix $\boldsymbol{B}$ is symmetric and idempotent. If (15.7) holds, we have $\boldsymbol{\eta} \sim \mathrm{N}(\mathbf{0}, \boldsymbol{B})$. The rank of the matrix $\boldsymbol{B}$ is equal to its trace $k-l=t$. The trace can be derived similarly as in the proof of theorem 15.6 (b). Theorem 3.8 on p. 39 implies that $\boldsymbol{\eta}^{\prime} \boldsymbol{\eta} \sim \chi_{t}^{2}$. We have

$$
\operatorname{cov}(\boldsymbol{\xi}, \boldsymbol{\eta})=\operatorname{cov}\left(\sigma^{-1} \boldsymbol{M} \boldsymbol{Y}, \sigma^{-1} \boldsymbol{B} \boldsymbol{Y}\right)=\sigma^{-2} \boldsymbol{M} \sigma^{2} \boldsymbol{I} \boldsymbol{B}=\boldsymbol{M} \boldsymbol{B}=\mathbf{0}
$$

Thus the vectors $\boldsymbol{\xi}$ and $\boldsymbol{\eta}$ are uncorrelated. Because thy are normally distributed, they are independent. Then the variables $\boldsymbol{\eta}^{\prime} \boldsymbol{\eta}$ a $\boldsymbol{\xi}^{\prime} \boldsymbol{\xi}$ are also independent. Using theorem 3.11 on p. 40 we obtain

$$
\frac{\boldsymbol{\eta}^{\prime} \boldsymbol{\eta} / t}{\boldsymbol{\xi}^{\prime} \boldsymbol{\xi} /(n-k)} \sim \mathrm{F}_{t, n-k}
$$

### 15.5 One-way analysis of variance

The problem is similar as in the case of two-sample $t$ test, but now it is more complicated because we have more samples. Assume that

$$
Y_{11}, \quad \ldots, \quad Y_{1 n_{1}} \quad \text { is the sample from } \mathrm{N}\left(\mu_{1}, \sigma^{2}\right)
$$

etc. and

$$
Y_{I 1}, \quad \ldots, \quad Y_{I n_{I}} \quad \text { is the sample from } \mathrm{N}\left(\mu_{I}, \sigma^{2}\right) .
$$

Let the samples be independent. Such a model is called one-way analysis of variance. We want to test hypothesis $H_{0}: \mu_{1}=\cdots=\mu_{I}$ against the alternative $H_{1}$, that some of the means $\mu_{1}, \ldots, \mu_{I}$ are different. Let us remark that if $H_{0}$ is rejected it is necessary to find all pairs $\mu_{i}, \mu_{j}$, which caused this rejection, i.e. for which it can be statistically proved that $\mu_{i} \neq \mu_{j}$.

Seemingly it could be done so that all two-sample $t$ tests are calculated. However, the number of such tests is $I(I-1) / 2$. If each of them has the level $\alpha$, the level of the complete test would be substantially larger than $\alpha$. The level of each test could be smaller, say $2 \alpha /[I(I-1)]$, which would ensure that the overall level would not be larger than $\alpha$. The power of such test would nod be large enough and its real level would be considerably smaller than $\alpha$. Thus another procedure is chosen. We form one vector $\boldsymbol{Y}$ from all variables $Y_{i j}$ so that first we give all members of the first sample, then of the second and finally the last. Let

$$
n=n_{1}+\cdots+n_{I} .
$$

Our assumptions lead to the model

$$
\begin{equation*}
\boldsymbol{Y}=\boldsymbol{X} \boldsymbol{\beta}+\boldsymbol{e} \tag{15.8}
\end{equation*}
$$

where

$$
\boldsymbol{X}=\left(\begin{array}{cccc}
1 & 0 & \ldots & 0  \tag{15.9}\\
\ldots & \ldots & \ldots & \ldots \\
1 & 0 & \ldots & 0 \\
0 & 1 & \ldots & 0 \\
\ldots & \ldots & \ldots & \ldots \\
0 & 1 & \ldots & 0 \\
\ldots & \ldots & \ldots & . \\
0 & 0 & \ldots & 1 \\
\ldots & \ldots & \ldots & \ldots \\
0 & 0 & \ldots & 1
\end{array}\right) n_{2}, \quad \boldsymbol{\beta}=\left(\begin{array}{c}
\mu_{1} \\
\vdots \\
\mu_{I}
\end{array}\right) .
$$

The vector $\boldsymbol{e}$ has $n$ components and it holds $\boldsymbol{e} \sim \mathbf{N}\left(\mathbf{0}, \sigma^{2} \boldsymbol{I}\right)$. Denote

$$
Y_{i .}=Y_{i 1}+\cdots+Y_{i n_{i}}, \quad y_{i .}=\frac{Y_{i .}}{n_{i}} \quad \text { for } \quad i=1, \ldots, I
$$

and

$$
Y_{. .}=Y_{1 .}+\cdots+Y_{I .}=\sum \sum Y_{i j}, \quad \bar{Y}=y_{. .}=\frac{Y_{. .}}{n} .
$$

Since

$$
\boldsymbol{X}^{\prime} \boldsymbol{X}=\operatorname{Diag}\left\{n_{1}, \ldots, n_{I}\right\}, \quad \boldsymbol{X}^{\prime} \boldsymbol{Y}=\left(Y_{1}, \ldots, Y_{I .}\right)^{\prime}
$$

we have

$$
\boldsymbol{b}=\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{X}^{\prime} \boldsymbol{Y}=\left(y_{1 .}, \ldots, y_{I .}\right)^{\prime}
$$

Theorem 15.3 gives that the residual sum of squares is

$$
R=\boldsymbol{Y}^{\prime} \boldsymbol{Y}-\boldsymbol{b}^{\prime} \boldsymbol{X}^{\prime} \boldsymbol{Y}=\sum_{i} \sum_{j} Y_{i j}^{2}-\sum_{i} y_{i .} Y_{i .}=\sum_{i} \sum_{j} Y_{i j}^{2}-\sum_{i} \frac{Y_{i .}^{2}}{n_{i}}
$$

If $H_{0}$ holds, we have the submodel

$$
\boldsymbol{Y}=\boldsymbol{U} \boldsymbol{\gamma}+\boldsymbol{e}
$$

where $\boldsymbol{U}_{n \times 1}=(1, \ldots, 1)^{\prime}$ and $\boldsymbol{\gamma}$ is of type $1 \times 1$. This time $\boldsymbol{U}^{\prime} \boldsymbol{U}=n, \boldsymbol{U}^{\prime} \boldsymbol{Y}=Y_{\text {.. }}$, and the estimator $\boldsymbol{g}$ of the parameter $\boldsymbol{\gamma}$ using method of least squares is

$$
\boldsymbol{g}=\left(\boldsymbol{U}^{\prime} \boldsymbol{U}\right)^{-1} \boldsymbol{U}^{\prime} \boldsymbol{Y}=y_{. .} .
$$

Residual sum of squares is

$$
R_{1}=\boldsymbol{Y}^{\prime} \boldsymbol{Y}-\boldsymbol{g}^{\prime} \boldsymbol{U}^{\prime} \boldsymbol{Y}=\sum_{i} \sum_{j} Y_{i j}^{2}-y_{. .} Y_{. .}=\sum_{i} \sum_{j} Y_{i j}^{2}-\frac{Y_{. .}^{2}}{n} .
$$

Thus

$$
R_{1}-R=\sum_{i} \frac{Y_{i .}^{2}}{n_{i}}-\frac{Y_{. .}^{2}}{n} .
$$

The rank of the matrix $\boldsymbol{X}$ is $I$, the rank of the matrix $\boldsymbol{U}$ is 1 . If $H_{0}$ holds, we get from theorem 15.12, that

$$
F_{A}=\frac{(n-I)\left(R_{1}-R\right)}{(I-1) R} \sim \mathrm{~F}_{I-1, n-I}
$$

In practical calculations the total sum of squares is calculated first

$$
S_{T}=\sum_{i} \sum_{j} Y_{i j}^{2}-\frac{Y_{.}^{2}}{n} .
$$

Then the sum of squares $R_{1}-R$ is calculated. It is

$$
S_{A}=\sum_{i} \frac{Y_{i .}^{2}}{n_{i}}-\frac{Y_{. .}^{2}}{n} .
$$

Residual sum of squares is usually denoted $S_{e}$ instead of $R$ and it is calculated from the formula

$$
S_{e}=S_{T}-S_{A}
$$

The variable $s^{2}=S_{e} /(n-I)$ is residual variance.
The results are written in the table of analysis of variance (see tab. 15.1). Sum of squares is denoted $S S$, degrees of freedom are $d f$ and the ratio (mean square) is MS.

In the case that $F_{A} \geq F_{I-1, n-I}(\alpha)$ we reject the hypothesis $H_{0}$. Then it is necessary to decide which pairs of indices satisfy $\mu_{i} \neq \mu_{j}$. Since $y_{i}$. is an estimator of $\mu_{i}$, the table of differences $y_{i}$. $y_{j}$. is calculated (see tab. 15.2).

Here we introduce only Tukey method of multiple comparisons, since it is one of the most sensitive.

Table 15.1: One-way analysis of variance

| Source | Sum <br> squares <br> $S S$ | Degrees of <br> freedom <br> $d f$ | $M S=\frac{S S}{d f}$ | Test <br> statistic <br> $F=\frac{M S}{s^{2}}$ |
| :--- | :---: | :---: | :---: | :---: |
| Groups | $S_{A}$ | $f_{A}=I-1$ | $S_{A} / f_{A}$ | $F_{A}$ |
| Residual | $S_{e}$ | $f_{e}=n-I$ | $s^{2}=S_{e} / f_{e}$ | - |
| Total | $S_{T}$ | $f_{T}=n-1$ | - | - |

Table 15.2: Differences of means

|  | $j$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| $i$ | 2 | 3 | $I$ |  |
| 1 | $\begin{array}{rlll} y_{1 .}-y_{2 .} . & y_{1 .}-y_{3 .} & \cdots & y_{1 .}-y_{I .} . \\ & y_{2 .}-y_{3 .} & \cdots & y_{2 .}-y_{I .} . \end{array}$ |  |  |  |
| 2 |  |  |  |  |
| $I-1$ | $y_{I-1, .}-y_{I}$ |  |  |  |

Lemma 15.13 Let $X_{1}, \ldots, X_{m}$ be random sample from the distribution $\mathbf{N}\left(\mu, \sigma^{2}\right)$, where $\sigma>0$. Denote $R=\max X_{i}-\min X_{i}$ the range. Let $s^{2}$ be an independent estimator for $\sigma^{2}$ with $\nu$ degrees of freedom; it means that $\nu s^{2} / \sigma^{2} \sim \chi_{\nu}^{2}$ and that $s^{2}$ and $\boldsymbol{X}=\left(X_{1}, \ldots, X_{m}\right)^{\prime}$ are independent. Denote $Q=R / s$ random variable called studentized range. Then the distribution of the random variable $Q$, which is denoted by symbol $q_{m, \nu}$, does not depend on $\mu$ and $\sigma$.

Proof. It holds

$$
\begin{equation*}
Q=\frac{\max \left(X_{i}-\mu\right) / \sigma-\min \left(X_{i}-\mu\right) / \sigma}{s / \sigma} . \tag{15.10}
\end{equation*}
$$

Variables $\left(X_{i}-\mu\right) / \sigma(i=1, \ldots, m)$ are independent with distribution $\mathrm{N}(0,1)$. Thus the distribution of the expression in the numerator of formula (15.10) does not depend on $\mu$ and $\sigma$. The distribution of the variable $s / \sigma$ does not depend on $\mu$ and $\sigma$, too. Since numerator and denominator of the formula (15.10) are independent variables, the distribution of the variable $Q$ does not depend on $\mu$ and $\sigma$.

We will not derive the density of the variable $Q$ here. The critical value $q_{m, \nu}(\alpha)$ is defined as the number satisfying $\operatorname{P}\left\{Q>q_{m, \nu}(\alpha)\right\}=\alpha$.

Theorem 15.14 (Tukey) Let $X_{1}, \ldots, X_{m}$ be independent random variables and let $X_{i} \sim \mathrm{~N}\left(\mu_{i}, b^{2} \sigma^{2}\right), i=1, \ldots, m$, where $b$ is a known positive constant. Let $s^{2}$ be independent estimator for $\sigma^{2}$ with $\nu$ degrees of freedom; it means that $\nu s^{2} / \sigma^{2} \sim \chi_{\nu}^{2}$ and that $s^{2}$ and $\boldsymbol{X}$ are independent. Then probability that

$$
X_{i}-X_{j}-b s q_{m, \nu}(\alpha) \leq \mu_{i}-\mu_{j} \leq X_{i}-X_{j}+b s q_{m, \nu}(\alpha)
$$

holds for all pairs $(i, j)$ simultaneously, equals to $1-\alpha$.

Proof. Denote $Z_{i}=X_{i}-\mu_{i}$. Variables $Z_{i}$ are independent and each of them has distribution $\mathrm{N}\left(0, b^{2} \sigma^{2}\right)$. Vector $\left(Z_{1}, \ldots, Z_{m}\right)^{\prime}$ does not depend on $s^{2}$. It is clear that $b^{2} s^{2}$ is independent estimator for the variance $b^{2} \sigma^{2}$ with $\nu$ degrees of freedom, since $\nu b^{2} s^{2} / b^{2} \sigma^{2} \sim \chi_{\nu}^{2}$. It follows from lemma 15.13 that

$$
\mathrm{P}\left\{\frac{\max Z_{i}-\min Z_{i}}{b s} \leq q_{m, \nu}(\alpha)\right\}=1-\alpha .
$$

This is equivalent to the formula

$$
\mathrm{P}\left\{\left|Z_{i}-Z_{j}\right| \leq b s q_{m, \nu}(\alpha) \quad \text { for all pairs }(i, j)\right\}=1-\alpha .
$$

Inserting for $Z_{i}$ and $Z_{j}$ we get the assertion of the theorem.
Tukey theorem is used in connection with testing hypothesis $H_{0}: \mu_{1}=\cdots=\mu_{m}$. If $H_{0}$ holds, then all intervals $\left[X_{i}-X_{j}-b s q_{m, \nu}(\alpha), X_{i}-X_{j}+b s q_{m, \nu}(\alpha)\right]$ overlap zero with probability $1-\alpha$. If some of them does not cover zero, i.e. if

$$
\begin{equation*}
\left|X_{i_{0}}-X_{j_{0}}\right|>b s q_{m, \nu}(\alpha) \tag{15.11}
\end{equation*}
$$

holds for a pair (or for some pairs) $\left(i_{0}, j_{0}\right)$, then it leads to the conclusion that we have $\mu_{i_{0}} \neq \mu_{j_{0}}$. This procedure has an advantage that probability of the error of the first kind equals $\alpha$ and the rejection of $H_{0}$ shows directly to the pair or pairs responsible for this rejection.

Tukey method can be applied in the one-way analysis of variance if $y_{1 .}, \ldots, y_{I}$. have equal variances. It comes in the case that $n_{1}=\cdots=n_{I}$. If this condition is satisfied, we say, that the model is balanced. In such a case we denote size of each sample by $P$ (i.e., $\left.P=n_{1}=\cdots=n_{I}\right)$. Then $y_{i .} \sim \mathrm{N}\left(\mu_{i}, \sigma^{2} / P\right)$. In theorem 15.14 we have $b^{2}=1 / P$. According to theorem 15.11 the equality of expectations of $i$-th and $j$-th sample is rejected, if

$$
\left|y_{i .}-y_{j .}\right|>\frac{s}{\sqrt{P}} q_{I, n-I}(\alpha) .
$$

Tukey method can be modified to the case of unbalanced classification. It was proved (see Hayter 1984), that

$$
\mathrm{P}\left\{\left|y_{i .}-y_{j} .\right|<s q_{I, n-I}(\alpha) \sqrt{\frac{1}{2}\left(\frac{1}{n_{i}}+\frac{1}{n_{j}}\right)} \quad \text { for all } \quad i, j\right\} \geq 1-\alpha
$$

If we get

$$
\left|y_{i .}-y_{j .}\right|>s q_{I, n-I}(\alpha) \sqrt{\frac{1}{2}\left(\frac{1}{n_{i}}+\frac{1}{n_{j}}\right)}
$$

then we reject the hypothesis about equality $\mu_{i}=\mu_{j}$. This modification in programs is called Tukey HSD. The abbreviation HSD means honest significant difference.

In tab. 15.2 to each difference which is statistically significant on the level 0.05 , a star as the upper index is added. If significance is on level 0.01 , two stars are added and for significance on level 0.001 three stars. This holds also for other tests.

At the beginning of this section we introduced the model of one-way analysis of variance in the form (15.8) and (15.9). Writing it in components we get

$$
Y_{i j}=\mu_{i}+e_{i j}, \quad i=1, \ldots, I, \quad j=1, \ldots, n_{i}
$$

This form simplifies the derivation of the procedure, since the matrix $\boldsymbol{X}$ in (15.9) has full rank. However, usually this model is applied in the form

$$
Y_{i j}=\mu+\alpha_{i}+e_{i j} .
$$

New matrix $\boldsymbol{X}$, which now corresponds to parameters $\mu, \alpha_{1}, \ldots, \alpha_{I}$, is of type $n \times(I+1)$, but it has rank $I$. Null hypothesis was $\mu_{1}=\cdots=\mu_{I}$, but now it has the form $\alpha_{1}=$ $0, \ldots, \alpha_{I}=0$. Both models are equivalent and lead to the same formulas. Only the methods of derivations are different.

Example 15.15 Four sorts of potatoes, namely A, B, C, and D, were cultivated. Each sort was cultivated on 7 fields of equal area. The yields in ton/hectare are introduced in tab. 15.3.

Table 15.3: Yields of potatoes in $\mathrm{t} / \mathrm{ha}$

| Sort | Yield |  |  |  |  |  |  | Average |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| A | 19.3 | 18.0 | 21.6 | 22.4 | 20.9 | 20.1 | 24.0 | 20.9 |
| B | 23.1 | 26.5 | 25.2 | 25.0 | 24.3 | 21.4 | 26.7 | 24.6 |
| C | 23.7 | 20.8 | 19.8 | 24.1 | 22.2 | 22.6 | 22.9 | 22.3 |
| D | 17.2 | 16.6 | 16.9 | 17.7 | 21.3 | 15.2 | 19.0 | 17.7 |

The results of analysis of variance are in tab. 15.4.

Table 15.4: Analysis of variance

| Source | Sum <br> of squares <br> $S S$ | Degrees of <br> freedom <br> $d f$ | Ratio <br> $M S=\frac{S S}{d f}$ | Test <br> statistic <br> $F=\frac{M S}{s^{2}}$ |
| :--- | :---: | :---: | :---: | :---: |
| Sorts | 174.9125 | 3 | 58.3042 | $17.0148^{*}$ |
| Residual | 82.2400 | 24 | 3.4267 | - |
| Total | 257.1525 | 27 | - | - |

Since $F_{A}=17.0148 \geq F_{3,24}(0.05)=3.01$, we reject the hypothesis that the sorts do not influence the yield of potatoes. The differences among means are compared with the critical value

$$
\sqrt{3.4267} q_{4,24}(0.05) \sqrt{\frac{1}{2}\left(\frac{1}{7}+\frac{1}{7}\right)}=2.73
$$

We prepare table of differences of means (tab. 15.5).
Then the means are ordered and with the continuous line are underlined the groups of means the members of which are not significantly different. We get tab. 15.6

We can see that the yield of the sort D differs from the yield of all other sorts. Further it is proved that the yields of the sorts A and B are different. On the other side it was not proved that the yields of the sorts A and C and sorts C and B are different.

Program R gives

Table 15.5: Differences of means

|  | B | C | D |
| :--- | ---: | ---: | :--- |
| A | $-3.7^{*}$ | -1.4 | $3.2^{*}$ |
| B |  | 2.3 | $6.9^{*}$ |
| C |  |  | $4.6^{*}$ |

Table 15.6: Sorted means

| D | A | C | B |
| :---: | :---: | :---: | :---: |
| 17.7 | $\underline{20.9}$ | 22.3 | 24.6 |

> vynos <- c(19.3, 18.0, 21.6, 22.4, 20.9, 20.1, 24.0, $23.1,26.5,25.2,25.0,24.3,21.4,26.7$, $23.7,20.8,19.8,24.1,22.2,22.6,22.9$, $17.2,16.6,16.9,17.7,21.3,15.2,19.0)$
odruda <- factor (c(rep("A",7), rep("B",7), rep("C",7), rep("D",7))) tapply(vynos, odruda, mean) \# calculation of averages
A B C D
20.924 .622 .317 .7
bram.aov <- aov(vynos ~ odruda) \# analysis of variance summary (bram.aov)


```
    Df F value Pr(>F)
group 3 0.1209 0.9469
    24
leveneTest(vynos, odruda, center=mean)
Levene's Test for Homogeneity of Variance (center = mean)
    Df F value Pr(>F)
group 3 0.126 0.9438
    24
```

95\% family-wise confidence level


Figure 15.1: Tukey method

When applying Tukey method we look which interval does not contain zero. It corresponds to the significant difference. This is easy using the graph (see fig. 15.1). Also Bartlett test and Levene test were performed. These tests will be explained in the next section.

### 15.6 Tests of homogeneity of variances

One of assumptions which we used in derivation of formulas for one-way analysis of variance was that variances of all $I$ normal distributions are the same. If we admit that $Y_{i 1}, \ldots, Y_{i n_{i}}$ is the sample from the distribution $\mathrm{N}\left(\mu_{i}, \sigma_{i}^{2}\right)$ for $i=1, \ldots, I$, the problem arises how to test the hypothesis

$$
H_{0}: \sigma_{1}^{2}=\cdots=\sigma_{I}^{2}
$$

against alternative $H_{1}$, that $H_{0}$ does not hold.
Several tests of the hypothesis $H_{0}$ has been derived. First, we describe Bartlett test. The denotation will be the same as in sec. 15.3.

Define

$$
\begin{aligned}
s_{i}^{2} & =\frac{1}{n_{i}-1}\left(\sum_{j=1}^{n_{i}} Y_{i j}^{2}-n_{i} y_{i .}^{2}\right), \\
s^{2} & =\frac{1}{n-I} \sum_{i=1}^{I}\left(n_{i}-1\right) s_{i}^{2} \\
C & =1+\frac{1}{3(I-1)}\left(\sum_{i=1}^{I} \frac{1}{n_{i}-1}-\frac{1}{n-I}\right), \\
B & =\frac{1}{C}\left[(n-I) \ln s^{2}-\sum_{i=1}^{I}\left(n_{i}-1\right) \ln s_{i}^{2}\right] .
\end{aligned}
$$

We have $s^{2}=S_{e} / f_{e}$, where $S_{e}$ and $f_{e}$ are introduced in tab. 15.1. If $H_{0}$ holds, then the random variable $B$ has approximately $\chi_{I-1}^{2}$ distribution. Thus $H_{0}$ is rejected in the case that $B \geq \chi_{I-1}^{2}(\alpha)$. However, this result can be used only in the case that the sizes $n_{1}, \ldots, n_{I}$ are sufficiently large. In textbooks is usually introduce that it must hold $n_{i}>6$ for all $i=1, \ldots, I$. Glaser (1976)published exact critical values. In the case $I=2$ Bartlett test can be used as the test for homogeneity of two variances instead common $F$ test. Manoukian a kol. (1986) published exact critical values for this case. Some other results about Bartlett test can be found in paper Nagarsenker (1984).

Unfortunately, Bartlett test is sensitive to violation of the assumption of normality (Box 1953, Box, Andersen 1955). The robust tests were suggested instead of it, see Layard 1973, Brown, Forsythe 1974.

Probably most often the Levene test (Levene 1960) is used for testing homogeneity of variances. The $I$ groups of random variables introduced in rows of tab. 15.7 is created.

Table 15.7: Levene test

$$
\begin{aligned}
& \left|Y_{11}-y_{1 .}\right|, \ldots,\left|Y_{1 n_{1}}-y_{1 .}\right| \\
& \left|\ddot{Y}_{I 1}-y_{I .}\right|, \ldots,\left|\ddot{Y}_{I n_{I}}-y_{I .}\right|
\end{aligned}
$$

Analysis of variance or Kruskal-Wallis test are applied to the variables in tab. 15.7. Nowadays in tab. 15.7 instead of means the medians are subtracted. Levene test can be found in the library car as the function leveneTest.

If we get a significant result, we reject the hypothesis about homogeneity of variances. This test is only approximate, since the assumptions of analysis of variance or its nonparametric variant are not fulfilled. The variables $Y_{i 1}-y_{i,}, \ldots, Y_{i n_{i}}-y_{i}$. are not independent and their absolute values have not a normal distribution. In spite of this Levene test is one of the best. It is shown in the paper Conover et al. (1981).

Example 15.16 We use data from example 15.15. We get

$$
\begin{array}{llll}
s_{1}^{2}=3,9933, & s_{2}^{2}=3,5200, & s_{3}^{2}=2,3600, & s_{4}^{2}=3,8333, \\
s^{2}=3,4266, & C=1,0694, & B=0,4537 . &
\end{array}
$$

Since $B<\chi_{3}^{2}(0,05)=7,81$, Bartlett test does not reject hypothesis of homogeneity of variances in the fourth partial samples.

Levene test based on Kruskal-Wallis test gives test statistic $Q=0.426$ with three degrees of freedom, which asymptotically corresponds to the level $p=0.935$. Levene test based on analysis of variance when medians are subtracted gives $F$ statistic 0.121 and the level of the test is $p=0.947$. When the averages are subtracted, then we get $F=0.126$ and $p$-value 0.9438 . None of the tests leads to the rejection of the hypothesis about homogeneity of variances.

### 15.7 Analysis when variances are not equal

Let $Y_{i 1}, \ldots, Y_{i n_{i}}$ be a sample from $\mathrm{N}\left(\mu_{i}, \sigma_{i}^{2}\right), i=1, \ldots, I$. Assume that the samples are independent. Let $n_{i} \geq 2, \sigma_{i}^{2}>0$. Denote

$$
y_{i}=\frac{1}{n_{i}} \sum_{j=1}^{n_{i}} Y_{i j}, \quad f_{i}=n_{i}-1, \quad s_{i}^{2}=\frac{1}{f_{i}} \sum_{j=1}^{n_{i}}\left(Y_{i j}-y_{i}\right)^{2}, \quad \lambda_{i}=\frac{1}{n_{i}} .
$$

We know that $y_{i} \sim \mathrm{~N}\left(\mu_{i}, \lambda_{i} \sigma_{i}^{2}\right)$. We shall test the hypothesis $H_{0}: \mu_{1}=\cdots=\mu_{I}$. The common (but unknown) value of parameters $\mu_{1}, \ldots, \mu_{I}$ will be denoted $\mu$. We use the results derived in section about weighted mean (see sec. 15.2 on p. 133). If $H_{0}$ holds, then NNLO $\hat{\mu}$ of the parameter $\mu$ equals to

$$
\hat{\mu}=\frac{1}{\sum_{i} \frac{1}{\lambda_{i} \sigma_{i}^{2}}} \sum_{j} \frac{1}{\lambda_{j} \sigma_{j}^{2}} y_{j}
$$

and it holds

$$
Z^{*}=\sum_{i} \frac{1}{\lambda_{i} \sigma_{i}^{2}}\left(y_{i}-\hat{\mu}\right)^{2} \sim \chi_{I-1}^{2}
$$

Usually, the variances $\sigma_{1}^{2}, \ldots, \sigma_{I}^{2}$ are not known. Thus we substitute $\sigma_{i}^{2}$ by unbiased estimator $s_{i}^{2}$. Define

$$
w_{i}=\frac{1}{\lambda_{i} s_{i}^{2}}, \quad \hat{y}=\frac{1}{\sum_{i} w_{i}} \sum_{j} w_{j} y_{j}, \quad Z=\sum_{i} w_{i}\left(y_{i}-\hat{y}\right)^{2} .
$$

Then $Z$ can be used as the test statistic for testing $H_{0}$. James (1951) approximated the critical value of the variable $Z$ by

$$
h(w)=\chi_{I-1}^{2}(\alpha)\left[1+\frac{3 \chi_{I-1}^{2}(\alpha)+I+1}{2\left(I^{2}-1\right)} \sum_{i} \frac{1}{f_{i}}\left(1-\frac{w_{i}}{\sum_{j} w_{j}}\right)^{2}\right]
$$

Thus it holds (approximately)

$$
\mathrm{P}\{Z>h(w)\}=\alpha
$$

Welch (1951) denoted

$$
\hat{f}_{1}=I-1, \quad \hat{f}_{2}=\left[\frac{3}{I^{2}-1} \sum_{i} \frac{1}{f_{i}}\left(1-\frac{w_{i}}{\sum_{j} w_{j}}\right)^{2}\right]^{-1}
$$

and proposed to use

$$
v^{2}=\frac{(I-1)^{-1} \sum_{i} w_{i}\left(y_{i}-\hat{y}\right)^{2}}{1+2(I-2)\left(I^{2}-1\right)^{-1} \sum_{i} \frac{1}{f_{i}}\left(1-\frac{w_{i}}{\sum_{j} w_{j}}\right)^{2}}
$$

as the test statistic. He proved that when $H_{0}$ holds then the variable $v^{2}$ has approximately distribution $\mathrm{F}_{\hat{f}_{1}, \hat{f}_{2}}$. His method is used in program $R$ in function oneway.test.

Example 15.17 We use data introduced in example 15.15. We get

```
oneway.test(vynos ~ odruda)
    One-way analysis of means (not assuming equal variances)
data: vynos and odruda
F = 14.5298, num df = 3.000, denom df = 13.256, p-value = 0.0001764
```

It means that the difference is significant.

### 15.8 Kruskal-Wallis test

Kruskal-Wallis test is a nonparametric analogue of one-way analysis of variance and it is a generalization of two-sample Wilcoxon test. It is used mainly in the situations when the samples are from very non-normal populations.

Let $Y_{i 1}, \ldots, Y_{i n_{i}}$ be a sample from a distribution with a continuous distribution function $F_{i}, i=1, \ldots, I$. Let all the samples be independent. We are going to test the hypothesis

$$
H_{0}: F_{1}(x)=\cdots=F_{I}(x) \quad \text { for all } x
$$

against the alternative $H_{1}$, that $H_{0}$ does not hold. All variables $Y_{i j}$ together form the pooled sample with size $n=n_{1}+\cdots+n_{I}$. They are ordered into increasing sequence and the rank $R_{i j}$ of each variable $Y_{i j}$ in the pooled sample is determined. This rank can be written in tab. 15.8.

Table 15.8: Kruskal-Wallis test

| Sample | Rank of variables in pooled <br> random sample |  |  | Sum <br> of ranks |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | $R_{11}$ | $R_{12}$ | $\ldots$ | $R_{1 n_{1}}$ | $T_{1}$ |
| 2 | $R_{21}$ | $R_{22}$ | $\ldots$ | $R_{2 n_{2}}$ | $T_{2}$ |
| $\ldots \ldots \ldots$ | $\ldots \ldots$ | $\ldots \ldots$ | $\ldots$ | $\ldots$ | $\ldots \ldots$ |
| $I$ | $R_{I 1}$ | $R_{I 2}$ | $\ldots$ | $R_{I n_{I}}$ | $T_{I}$ |

Proposed test statistic is

$$
Q^{*}=\sum_{i=1}^{I} \frac{1}{n_{i}}\left(T_{i}-\mathrm{E} T_{i}\right)^{2}
$$

Since

$$
\mathrm{E} R_{i j}=\frac{1}{N} \sum_{k=1}^{N} k=\frac{N+1}{2},
$$

we have

$$
\mathrm{E} T_{i}=\mathrm{E} \sum_{j=1}^{n_{i}} R_{i j}=n_{i} \frac{N+1}{2}
$$

From this formula we obtain

$$
Q^{*}=\sum_{i=1}^{I} \frac{1}{n_{i}} T_{i}^{2}-\frac{1}{4} N(N+1)^{2} .
$$

Define $\sigma_{a}^{2}=\frac{1}{12}(N+1)(N-1)$. Instead of $Q^{*}$ the test statistic

$$
Q=\frac{N-1}{N \sigma_{a}^{2}} Q^{*}=\frac{12}{n(n+1)} \sum_{i=1}^{I} \frac{T_{i}^{2}}{n_{i}}-3(n+1)
$$

is often used. It can be proved that $\mathrm{E} Q=I-1$.
Instead of $Q$ the symbol $H$ is written and one speaks about $H$ test. If data contain more than $25 \%$ ties, we should calculate corrected statistic

$$
Q_{\text {korig }}=\frac{Q}{1-\left(n^{3}-n\right)^{-1} \sum\left(t_{i}^{3}-t_{i}\right)},
$$

where $t_{1}, t_{2}, \ldots$ are numbers of ties in groups with the same value.
It can be proved (see Hájek, Sidák 1967), that under $H_{0}$ the hypothesis $Q$ has asymptotically $\chi^{2}$ distribution, when all $n_{i}$ tend to infinity. Since $\mathrm{E} Q=I-1$, we will have asymptotically $\chi^{2}$ distribution with $I-1$ degrees of freedom. Thus we reject hypothesis $H_{0}$ when $Q \geq \chi_{I-1}^{2}(\alpha)$.

Kruskal-Wallis test is sensitive especially in the cases when the distribution functions differs by shift. If we reject $H_{0}$, it is worth to decide which pairs of samples significantly differ. In analysis of variance Tukey method was used. Kruskal-Wallis test can be supplemented as follows (see Miller 1966). Denote $t_{i}=T_{i} / n_{i}, i=1, \ldots, I$. Let $h_{I-1}(\alpha)$ be critical value of Kruskal-Wallis test on level $\alpha$. If the sizes of samples are small, $h_{I-1}(\alpha)$ can be found in special tables and in greater sizes the approximation $h_{I-1}(\alpha) \doteq \chi_{I-1}^{2}(\alpha)$ can be used. We decide that the distribution functions of the $i$-th and the $j$-th sample significantly differ if it holds

$$
\begin{equation*}
\left|t_{i}-t_{j}\right|>\sqrt{\frac{1}{12}\left(\frac{1}{n_{i}}+\frac{1}{n_{j}}\right) n(n+1) h_{I-1}(\alpha)} . \tag{15.12}
\end{equation*}
$$

Probability that at least two of $I(I-1) / 2$ distribution functions $F_{i}, F_{j}$ will be declared that they are significantly different, although $H_{0}$ holds, is not greater than $\alpha$.

If the sizes of all samples are the same, say $n_{1}=\cdots=n_{I}=m$, then procedures of multiple comparisons can be based on Tukey idea which was applied in one-way analysis of variance (see Neményi 1963 and Miller 1966). For small values $m$ and $I$ are critical values for $\left|T_{i}-T_{j}\right|$ tabulated. If $m$ and $I$ are large, we use the following method. Let
$q_{I, \infty}(\alpha)$ be critical value of the range of $I$ independent random variables with distribution defined as follows. If $\xi_{1}, \ldots, \xi_{I}$ is the sample from $\mathrm{N}(0,1)$, we denote $R=\xi_{(I)}-\xi_{(1)}$ its range. Then $q_{I, \infty}(\alpha)$ is defined by the condition

$$
\mathrm{P}\left[R \geq q_{I, \infty}(\alpha)\right]=\alpha
$$

We declare that $F_{i}$ and $F_{j}$ significantly differ if

$$
\begin{equation*}
\left|t_{i}-t_{j}\right|>q_{I, \infty}(\alpha) \sqrt{\frac{1}{12} I(I m+1)} \tag{15.13}
\end{equation*}
$$

If possible, we prefer Neményi method, since it is more sensitive.
Other tests, which can be used instead of Kruskal-Wallis test, are described in the paper Bhapkar, Deshpande (1968).

It is necessary to point out that assigning ranks is monotonous transformation, but nonlinear. The nonlinearity may lead to paradoxal results, as it is shown in the next example (see Haunsperger, Saari 1991).

Example 15.18 Two workshops are in a factory, in each of them 6 identical machines. However, 2 are from producer A, 2 from B and 2 from C. The production is described in tab. 15.9-15.11.

Table 15.9: Workshop No. 1

| Producer | Productivity of machines | Rank | Sum of ranks |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A | 5.89 | 5.98 | 3 | 5 | 8 |
| B | 5.81 | 5.90 | 2 | 4 | 6 |
| C | 5.80 | 5.99 | 1 | 6 | 7 |

Table 15.10: Workshop No. 2

| Producer | Productivity of machines |  | Rank | Sum of ranks |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A | 5.69 | 5.74 | 3 | 5 | 8 |
| B | 5.63 | 5.71 | 2 | 4 | 6 |
| C | 5.62 | 6.00 | 1 | 6 | 7 |

Table 15.11: Factory

| Producer | Productivity of machines |  |  |  | Rank |  |  |  | Sum of ranks |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| A | 5.89 | 5.98 | 5.69 | 5.74 | 8 | 10 | 3 | 5 | 26 |
| B | 5.81 | 5.90 | 5.63 | 5.71 | 7 | 9 | 2 | 4 | 22 |
| C | 5.80 | 5.99 | 5.62 | 6.00 | 6 | 11 | 1 | 12 | 30 |

V workshop 1 the arrangement is $A \succ C \succ B$. Also in the workshop 2 we have $A \succ C \succ B$. In the factory we have $C \succ A \succ B$, which is completely different.

Table 15.12: Ranks of the yields of potatoes

| Sort | Ranks |  |  |  |  |  |  |
| :---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: |
| A | 8 | 6 | 15 | 17 | 12 | 10 | 22 |
| B | 20 | 27 | 26 | 25 | 24 | 14 | 28 |
| C | 21 | 11 | 9 | 23 | 16 | 18 | 19 |
| D | 4 | 2 | 3 | 5 | 13 | 1 | 7 |

Some paradoxes are described in papers Haunsperger (1992) and Saari (1989).
Example 15.19 We use data from example 15.15, p. 141. The numbers given in tab. 15.3 will be ordered and their ranks assigned. We get tab. 15.12.

We have $n_{i}=7$ for $i=1,2,3,4$ and further we get

$$
T_{1}=90, \quad T_{2}=164, \quad T_{3}=117, \quad T_{4}=35, \quad Q=18.369
$$

Since $Q \geq \chi_{3}^{2}(0.05)=7.81$, we reject the hypothesis that the samples arise from the distributions with identical distribution function. Now, we calculate multiple comparisons. We get

$$
t_{1}=12,857, \quad t_{2}=23.429, \quad t_{3}=16.714, \quad t_{4}=5
$$

Critical value is 12.3. In our case the samples have the same size and thus we can calculate also critical value using (15.13). The result is 11.3 . We use this second critical value, because it is smaller. The differences $t_{i}-t_{j}$ are introduced in tab. 15.13. The significance is denoted by a star.

Table 15.13: Values $t_{i}-t_{j}$

|  | $j$ |  |  |
| :---: | :---: | :---: | :---: |
| $i$ | 2 | 3 | 4 |
| 1 | -10.57 | -3.86 | 7.86 |
| 2 |  | 6.72 | $18.43^{*}$ |
| 3 |  |  | $11.71^{*}$ |

The sorts are arranged according $t_{i}$ and we underline by unbroken line the groups which do not differ significantly. We obtain tab. 15.14.

Table 15.14: Sorted means


It is proved that $D$ is significantly different from $C$ and also from $B$. These results are weaker than those obtained from the analysis of variance in example 15.15.

Using program $R$ we get

```
kruskal.test(vynos ~ odruda)
    Kruskal-Wallis rank sum test
data: vynos by odruda
Kruskal-Wallis chi-squared = 18.3695, df = 3, p-value = 0.000369
```

We obtained significant result. $\diamond$

## Chapter 16

## Discrete problem of $k$ samples

### 16.1 Testing homogeneity by method $\chi^{2}$

Test of homogeneity of two binomial distributions was described in sec. 14.1. It was proved that it corresponds to the test of homogeneity in $2 \times 2$ table. For test of homogeneity of $r$ binomial distributions we can use $\chi^{2}$ test for $r \times 2$ table.

Theorem 16.1 Let $c=2$. Then

$$
\begin{equation*}
\chi^{2}=\frac{n^{2}}{n_{.1} n_{.2}} \sum_{i=1}^{r} n_{i .}\left(\frac{n_{i 1}}{n_{i .}}-\frac{n_{.1}}{n}\right)^{2} . \tag{16.1}
\end{equation*}
$$

Proof. We use formula (10.18) for calculating $\chi^{2}$ in contingency tables. We insert $n_{i 2}=$ $n_{i .}-n_{i 1}, n_{.2}=n-n_{.1}$, and we obtain

$$
\begin{aligned}
& \chi^{2}=\sum_{i=1}^{r}\left[\frac{\left(n_{i 1}-\frac{n_{i .} n_{.1}}{n}\right)^{2}}{\frac{n_{i . n_{.1}}}{n}}+\frac{\left(n_{i 2}-\frac{n_{i . n} n_{.2}}{n}\right)^{2}}{\frac{n_{i . n_{.2}}}{n}}\right] \\
& =\frac{1}{n} \sum_{i=1}^{r}\left[\frac{\left(n n_{i 1}-n_{i .} n_{.1}\right)^{2}}{n_{i .1} n_{.1}}+\frac{\left(n n_{i 2}-n_{i .} n_{.2}\right)^{2}}{n_{i . n_{.2}}}\right] .
\end{aligned}
$$

Since

$$
n n_{i 2}-n_{i .} n_{.2}=n\left(n_{i .}-n_{i 1}\right)-n_{i . n_{.2}}=-n n_{i 1}+\left(n_{.1}+n_{.2}\right) n_{i .}-n_{i .} n_{.2}=-n n_{i 1}+n_{i .} n_{.1}
$$

we get

$$
\begin{aligned}
\chi^{2} & =\frac{1}{n} \sum_{i=1}^{r}\left(n n_{i 1}-n_{i .} n_{.1}\right)^{2}\left[\frac{1}{n_{i . n_{.1}}}+\frac{1}{n_{i . n_{.2}}}\right] \\
& =\frac{1}{n} \sum_{i=1}^{r}\left(n n_{i 1}-n_{i .} n_{.1}\right)^{2} \frac{n_{.2}+n_{.1}}{n_{i . n_{.1} n_{.2}}} \\
& =\sum_{i=1}^{r} \frac{\left(n n_{i 1}-n_{i . n_{.1}}\right)^{2}}{n_{i . n_{.1} n_{.2}}} \\
& =\frac{n^{2}}{n_{.1} n_{.2}} \sum_{i=1}^{r} n_{i .}\left(\frac{n_{i 1}}{n_{i .}}-\frac{n_{.1}}{n}\right)^{2} .
\end{aligned}
$$

Theorem 16.2 Let $c=2$. Then

$$
\begin{equation*}
\chi^{2}=\frac{n^{2}}{n_{.1} n_{.2}} \sum_{i=1}^{r} \frac{n_{i 1}^{2}}{n_{i .}}-n \frac{n_{.1}}{n_{.2}} . \tag{16.2}
\end{equation*}
$$

Proof. From formula (16.1) we obtain

$$
\begin{aligned}
\chi^{2} & =\frac{n^{2}}{n_{.1} n_{.2}} \sum_{i=1}^{r} n_{i .}\left(\frac{n_{i 1}}{n_{i .}}-\frac{n_{.1}}{n}\right)^{2}=\frac{n^{2}}{n_{.1} n_{.2}}\left(\sum_{i=1}^{r} \frac{n_{i 1}^{2}}{n_{i .}}-2 \frac{n_{.1}}{n} \sum_{i=1}^{r} n_{i 1}+\frac{n_{.1}^{2}}{n^{2}} \sum_{i=1}^{r} n_{i .}\right) \\
& =\frac{n^{2}}{n_{.1} n_{.2}} \sum_{i=1}^{r} \frac{n_{i 1}^{2}}{n_{i .}}-n \frac{n_{.1}}{n_{.2}} .
\end{aligned}
$$

Formula (16.1) can be used for calculating $\chi^{2}$ also in the case that we are interested in testing independence in table $2 \times c$. Formulas for test of independence and test for homogeneity are identical.

### 16.2 Test based on weighted average

Now, we shall consider the problem of testing homogeneity from other aspect. Let $X_{1} \sim$ $\mathrm{Bi}\left(n_{1}, p_{1}\right), \ldots, X_{k} \sim \operatorname{Bi}\left(n_{k}, p_{k}\right)$ and let the variables $X_{1}, \ldots, X_{k}$ be independent. We intend to test hypothesis of homogeneity $H_{0}: p_{1}=\cdots=p_{k}$. Denote $x_{i}=X_{i} / n_{i}$ and $N=n_{1}+\cdots+n_{k}$. We know that $\mathrm{E} x_{i}=p_{i}$, var $x_{i}=p_{i}\left(1-p_{i}\right) / n_{i}$. Assume that $H_{0}$ holds. The common value of all probabilities $p_{i}$ will be denoted by $p$, so that $p=p_{1}=\cdots=p_{k}$. Theorem 15.9 gives that

$$
\hat{p}=\frac{1}{N} \sum_{i} n_{i} x_{i}
$$

is estimator for parameter $p$ (see formula (15.2).
The central limit theorem gives that $x_{i}$ has asymptotically distribution $\mathbf{N}\left[p, \frac{p(1-p)}{n_{i}}\right]$ if hypothesis of homogeneity holds. From theorem 15.10 we get that

$$
Q=\frac{1}{p(1-p)} \sum_{i} n_{i}\left(x_{i}-\hat{p}\right)^{2}
$$

has asymptotically $\chi_{k-1}^{2}$ distribution. However, we do not know the parameter $p$. Thus we use the estimator $\hat{p}$ instead and we use $\tilde{Q}$ instead of $Q$, where

$$
\begin{equation*}
\tilde{Q}=\frac{1}{\hat{p}(1-\hat{p})} \sum_{i} n_{i}\left(x_{i}-\hat{p}\right)^{2} . \tag{16.3}
\end{equation*}
$$

It can be proved that the asymptotic distribution of the variable $\tilde{Q}$ remains the same as the asymptotic distribution of variable $Q$, namely $\chi_{k-1}^{2}$. We reject $H_{0}$ when $\tilde{Q} \geq \chi_{k-1}^{2}(\alpha)$. Since the test is asymptotical, for all $i$ it must hold $n_{i} \hat{p}>5$. Formula (16.3) can be a little simplified.

Theorem 16.3 Let $c=2$. Then

$$
\begin{equation*}
\tilde{Q}=\frac{1}{\hat{p}(1-\hat{p})} \sum_{i=1}^{k} n_{i} x_{i}^{2}-N \frac{\hat{p}}{1-\hat{p}} \tag{16.4}
\end{equation*}
$$

This formula is called Brandt-Snedecor formula.
Proof. First, we write (16.3) in the form

$$
\tilde{Q}=\frac{1}{\hat{p}(1-\hat{p})}\left(\sum_{i=1}^{k} n_{i} x_{i}^{2}-2 \hat{p} \sum_{i=1}^{k} n_{i} x_{i}+\hat{p}^{2} \sum_{i=1}^{k} n_{i} .\right)
$$

Since $\sum n_{i} x_{i}=n \hat{p}$, the formula (16.4) follows.

### 16.3 Remark on tests

Theorem 16.4 If $k=2$, then the test based on statistic $\tilde{Q}$ is identical with two-sided test which is based on $U_{b}$ defined in formula (14.2).

Proof. Since $\chi_{1}^{2}(\alpha)=\left[u\left(\frac{\alpha}{2}\right)\right]^{2}$, test based on $U_{b}$ rejects homogeneity of two binomial distributions when $U_{b}^{2} \geq \chi_{1}^{2}(\alpha)$. If we compare denotation used in (14.2) and in our theorem, we can see that

$$
x=x_{1}, \quad y=x_{2}, \quad z=\hat{p}, \quad m=n_{1}, \quad n=n_{2} .
$$

According to (16.3) and to (14.2) we have

$$
\tilde{Q}=\frac{1}{z(1-z)}\left[m(x-z)^{2}+n(y-z)^{2}\right] .
$$

Since

$$
z=\frac{m x+n y}{m+n}
$$

we obtain

$$
\tilde{Q}=\frac{1}{z(1-z)} \frac{(x-y)^{2}}{\frac{1}{m}+\frac{1}{n}}=U_{b}^{2}
$$

Similarly, for arbitrary $k \geq 2$ it holds $\tilde{Q}=\chi^{2}$, where $\chi^{2}$ is defined in formula (16.2) and $\tilde{Q}$ in (16.4).

Theorem 16.5 Let $c=2$. Then

$$
\begin{equation*}
\tilde{Q}=\frac{n^{2}}{n_{.1} n_{.2}} \sum_{i=1}^{k} \frac{n_{i 1}^{2}}{n_{i .}}-n \frac{n_{.1}}{n_{.2}} \tag{16.5}
\end{equation*}
$$

Proof. We have $\hat{p}=\frac{n_{.1}}{n}, 1-\hat{p}=\frac{n .2}{n}$. We insert into (16.4) and obtain assertion of theorem.

### 16.4 Example

Example 16.6 The Faculty of Mathematics and Physics organizes camp for students who enrolled into the first year of study. The camp is in Albeř in district Jindřichův Hradec. The students are divided into groups with respect to the branch of their study. It is Mathematics (M), Physics (F), Computer Science (I), and Teaching (U). Since 2004 the students write the same test from Mathematics. The test consists of 12 problems. Each correctly solved problem brings 1 point. The student having 9 or more points is successful. The unsuccessful solvers are recommended to attend a special introductory course in Praha. The results of the test in year 2010 are introduced in tab. 16.1.

Table 16.1: Results of test from Maths in 2010

| Year |  | Branch |  |  |  |
| :--- | :--- | ---: | ---: | ---: | ---: |
|  | Successful | 104 | 55 | 52 | 7 |
|  | Unsuccessful | 54 | 42 | 70 | 10 |

We will deal with the problem if in year 2010 were significant differences among the branches. Using program $R$ we obtain

```
usp10 <- c(104, 55, 52, 7)
neu10 <- c(54, 42, 70, 10)
tbl10 <- rbind(usp10,neu10)
colnames(tbl10) <- c("M","F","I","U")
(tbl10.am <- addmargins(tbl10))
            M F I U Sum
usp10}104\quad55\quad52 7 7 218
neu10 54 42 70 10 176
Sum 158 97 122 17 394
clk10 <- usp10+neu10
prop.test(usp10,clk10)
data: usp10 out of clk10
X-squared = 16.4601, df = 3, p-value = 0.0009125
alternative hypothesis: two.sided sample estimates:
    prop 1 prop 2 prop 3 prop 4
0.6582278 0.5670103 0.4262295 0.4117647
```

The difference in year 2010 is statistically significant. However, in other years the difference was not significant.

In case of significant result the statistician must decide which pairs are significantly different. This can be done using the following program.

```
pairwise.prop.test(usp10, clk10)
    Pairwise comparisons using Pairwise comparison of proportions
data: usp10 out of clk10
    1 2 3
20.554 - -
```

30.0010 .265 -
40.3280 .7141 .000

P value adjustment method: holm
The result is represented by the matrix of adjusted $p$-values, calculated by Holm method (see Holm 1979). It is one of the methods of multiple comparisons. We can see that there exists only one adjusted $p$-value, which is smaller than 0.05 , namely 0.001 . It corresponds to the comparison of the students of mathematics and informatics. These two groups are significantly different. No other differences were significantly different. $\diamond$

## Chapter 17

## Calculation of power of test

### 17.1 One-sample test

Let $X_{1}, \ldots, X_{n}$ be a random sample from the distribution $\mathrm{N}\left(\mu, \sigma^{2}\right)$, where $\sigma^{2}>0$. At the beginning we assume that the variance $\sigma^{2}$ is known. Test of $H_{0}: \mu=\mu_{0}$ against $H_{1}: \mu>\mu_{0}$ has critical set

$$
\frac{\bar{X}-\mu_{0}}{\sigma} \sqrt{n} \geq u(\alpha)
$$

If the true expectation is $\mu$, then the power of test (probability of rejection $H_{0}$ ) is

$$
\begin{aligned}
\beta(\mu) & =\mathrm{P}\left\{\left.\frac{\bar{X}-\mu_{0}}{\sigma} \sqrt{n} \geq u(\alpha) \right\rvert\, \mu\right\} \\
& =\mathrm{P}\left\{\left.\frac{\bar{X}-\mu}{\sigma} \sqrt{n} \geq u(\alpha)+\frac{\mu_{0}-\mu}{\sigma} \sqrt{n} \right\rvert\, \mu\right\} .
\end{aligned}
$$

Denote $\Delta=\left(\mu-\mu_{0}\right) / \sigma$. If we want that for the given $\Delta$ the test has power $\beta$, we must have

$$
\begin{equation*}
\mathbf{P}\left\{\left.\frac{\bar{X}-\mu}{\sigma} \sqrt{n} \geq u(\alpha)+\frac{\mu_{0}-\mu}{\sigma} \sqrt{n} \right\rvert\, \mu\right\}=\beta . \tag{17.1}
\end{equation*}
$$

Consider size $n$ of the sample which ensures that for the given $\Delta$ the power of test $\beta(\mu)$ will be equal to the given probability $\beta$. From (17.1) we have the condition

$$
u(\alpha)+\Delta \sqrt{n}=u(\beta),
$$

so that

$$
n=\frac{[u(\beta)-u(\alpha)]^{2}}{\Delta^{2}}
$$

We solved the right-hand side test. The results for left-hand side test and for the two-sided test can be derived analogously. For details see Hátle, Likeš (1972), p. 287.

If the variance $\sigma^{2}$ is not known, then the test of $H_{0}: \mu=\mu_{0}$ against $H_{1}: \mu>\mu_{0}$ has critical set

$$
T^{\prime}=\frac{\bar{X}-\mu_{0}}{S} \sqrt{n} \geq t_{n-1}(\alpha)
$$

If the mean value is $\mu$, then the random variable $\left(\bar{X}-\mu_{0}\right) \sqrt{n} / \sigma$ has distribution $\mathrm{N}(\delta, 1)$, where $\delta=\left(\mu-\mu_{0}\right) \sqrt{n} / \sigma$. Thus $T^{\prime}$ has non-central t distribution $\mathrm{t}_{n-1, \delta}$. The power is

$$
\beta(\mu)=\mathrm{P}\left[T^{\prime} \geq t_{n-1}(2 \alpha)\right]=1-F_{n-1, \delta}\left[t_{n-1}(2 \alpha)\right],
$$

where $F_{n-1, \delta}$ is distribution function of $\mathrm{t}_{n-1, \delta}$. The size $n$ of sample ensuring that for a given $\mu>\mu_{0}$ the power of test is $\beta$ can be obtained by solving equation $\beta(\mu)=\beta$. Similar procedure can be used for left-hand side and for two-sided test.

Example 17.1 We analyze data introduced in example 9.5, p. 74. We calculate power of two-sided test $H_{0}: \mu=0$ against alternative $H_{1}: \mu=1$. This number 1 is denoted delta. First, the data are odch <- $c(-3,2,-2,0,-1)$. Then we use sd(odch) and have standard deviation 1.923538. The unknown standard deviation $\sigma$ will be taken as 2 . Further we have

```
power.t.test(n=5, delta=1, sd=2, type="one.sample")
    One-sample t test power calculation
            n = 5
            delta = 1
            sd = 2
        sig.level = 0.05
            power = 0.1384528
alternative = two.sided
```

In this function we have sig.level $=0.05$. The power of the test is only 0.14 . If we want to have the power of test 0.9 , the sample size is obtained as follows.

```
power.t.test(power=0.9, delta=1, sd=2, type="one.sample")
    One-sample t test power calculation
            n = 43.99552
            delta = 1
            sd = 2
        sig.level = 0.05
            power = 0.9
alternative = two.sided
```

The size of the sample would be $n=44$.

### 17.2 Paired t-test

It is only a variant of one-sample t-test and so we show only an example.
Example 17.2 We use data introduced in example 11.1, p. 99. We shall calculate power of test for the case that the difference of means is delta=0.3. We have

```
ppneu <- c(1.8,1.0,2.2,0.9,1.5,1.6)
lpneu <- c(1.5,1.1,2.0,1.1,1.4,1.4)
rozdil <- ppneu-lpneu
sd(rozdil)
0.194079
```

The unknown standard deviation $\sigma$ is replaced by the number 0.2 . We obtain

```
power.t.test(n=6, delta=0.3, sd=0.2, type="paired")
    Paired t test power calculation
            n = 6
        delta = 0.3
            sd = 0.2
        sig.level = 0.05
            power = 0.8325291
        alternative = two.sided
NOTE: n is number of *pairs*, sd is std.dev. of *differences* within pairs
```

In this case the power of test is 0.83 , which is rather large.

### 17.3 Two-sample t-test

We show only a practical application of the test.

Example 17.3 Consider data from example 13.4, p. 112. The program can be applied only in the case that the sizes of both samples are equal. Assume that when the difference of means is 5 , the power should be 0.9 . We obtain

```
da<-c(62,54,55,60,53,58)
db<-c(52,56,49,50,51)
sd(da) [1]
3.577709
sd(db)
[1] 2.701851
```

Standard deviation of the first sample is 3.6, of the second 2.7. The unknown standard deviation $\sigma$ will be taken as 3 . We calculate

```
power.t.test(power=0.9, sd=3, delta=5)
    Two-sample t test power calculation
            \(\mathrm{n}=8.649245\)
            delta \(=5\)
            sd \(=3\)
        sig.level \(=0.05\)
            power \(=0.9\)
    alternative \(=\) two.sided
NOTE: \(n\) is number in *each* group
```

The required power of test would be reached in the case that the sample size in each group would be $n=9$.

### 17.4 Analysis of variance

Using function power.anova.test it is possible to calculate power of test in one-way analysis of variance when the classification is balanced, Function power. anova.test has arguments

- groups Number of groups
- n Number of observations (per group)
- between.var Between group variance
- within.var Within group variance
- sig.level Significance level (Type I error probability)
- power Power of test (1 minus Type II error probability)

Example 17.4 We calculate power of test for data in example 15.15, p. 141. Value of within.var can be estimated by residual variance 3.43, value of between.var can be estimated by variance of class averages as follows.

```
x <- c(20.9, 24.6, 22.3, 17.7) # class averages
var(x)
8.329167
```

Now, we calculate the power of the test:

```
power.anova.test(groups=4, n=7, between.var=8.33,
within.var=3.43)
    Balanced one-way analysis of variance power calculation
        groups = 4
            n = 7
between.var = 8.33
    within.var = 3.43
        sig.level = 0.05
            power = 0.9999658
```

In this case the power is very high, which corresponds to small $p$-value from example 15.15.

### 17.5 Test for homogeneity of two binomial distributions

It happens quite often that we have two binomial distributions and we want to test if probability of success is the same for both distributions. Let $X_{1} \sim \operatorname{Bi}\left(n_{1}, p_{1}\right)$ and $X_{2} \sim \operatorname{Bi}\left(n_{2}, p_{2}\right)$ be two independent random variables. If we have their realizations, we are interested in the power of test of hypothesis $H_{0}: p_{1}=p_{2}$ against the alternative that the true probabilities $p_{1}$ and $p_{2}$ are different. If we prepare the samples, we are interested in sample sizes which ensure that the power of test will be $\beta$. In the case $n_{1}=n_{2}=n$ we can use the function power. prop.test. We have

```
power.prop.test(n=NULL, p1=NULL, p2=NULL, sig.level=0.05, power=NULL,
    alternative=c("twosided","one.sided"), strict=FALSE)
```

If one of the parameters $n, p 1, p 2$, power, is unknown, then the function sig.level the parameter calculates. We introduce some examples.

Example 17.5 We restrict ourselves to the usual situation sig.level=0.05. If $n=50$, $p 1=0.5, p 2=0.6$, then we get

```
power.prop.test(n = 50, p1 = .5, p2 = .6)
    Two-sample comparison of proportions power calculation
                        n = 50
            p1 = 0.5
            p2 = 0.6
        sig.level = 0.05
            power = 0.1685815
    alternative = two.sided
NOTE: n is number in *each* group
```

The power of the test is only 0.1685815 . If we want power $\beta=0.9$, then the calculation

```
power.prop.test(p1 = .5, p2 = .6, power = .9)
    Two-sample comparison of proportions power calculation
            \(\mathrm{n}=518.0372\)
            p1 \(=0.5\)
            \(\mathrm{p} 2=0.6\)
        sig.level \(=0.05\)
            power \(=0.9\)
        alternative \(=\) two.sided
NOTE: \(n\) is number in *each* group
```

gives that we must have at least 518 variables in each group.

## Chapter 18

## Linear regression models

### 18.1 Introduction

Linear regression models were described in section 15.1 on p. 129. In this chapter we introduce some special cases. At the beginning we shall assume that $e_{1}, \ldots, e_{n}$ are independent random variables with distribution $\mathrm{N}\left(0, \sigma^{2}\right)$.

### 18.2 Basic regression models

### 18.2.1 Line with zero intercept

Consider the model

$$
Y_{i}=\beta x_{i}+e_{i}, \quad i=1, \ldots, n .
$$

If we write this model in the form (15.1), then we can see that the vector $\boldsymbol{\beta}$ has only one component $\beta$ and it holds $\boldsymbol{X}=\left(x_{1}, \ldots, x_{n}\right)^{\prime}$. It follows from theorem 15.1 on p. 130 that the estimator of the parameter $\beta$ is

$$
b=\frac{\sum x_{i} Y_{i}}{\sum x_{i}^{2}}
$$

Using the second formula in theorem 15.3 on p. 130 we have

$$
s^{2}=\frac{R}{n-1}=\frac{\sum Y_{i}^{2}-b \sum x_{i} Y_{i}}{n-1} .
$$

Usually, we test the hypothesis $H_{0}: \beta=0$. We use theorem 15.7 on p. 131. If $H_{0}$ holds, then the variable

$$
T=\frac{b}{s} \sqrt{\sum x_{i}^{2}}
$$

has the distribution $\mathrm{t}_{n-1}$. If $|T| \geq t_{n-1}(\alpha)$, we reject $H_{0}$.
Example 18.1 Bend $Y_{i}$ (in $\mathrm{mm} \times 10^{-2}$ ) of plastic material was measured in dependence on pressure $x_{i}$ (in $\mathrm{kp} / \mathrm{cm}^{2}$ ). The results are introduced in tab. 18.1, see fig. 18.1.

It is known that in this range of values $x_{i}$ the bend is linearly dependent on pressure. This linear function has zero intercept. We obtain

$$
b=7.857, \quad s^{2}=4.7143, \quad T=69.041
$$

Table 18.1: Bend of material in dependence on pressure

| Pressure $x_{i}$ | 2 | 4 | 6 | 8 | 10 | 12 |
| :--- | ---: | ---: | ---: | ---: | ---: | ---: |
| Bend $Y_{i}$ | 14 | 35 | 48 | 61 | 80 | 93 |

The value of $T$ exceeds the critical value $t_{5}(0.05)=2.571$, and so we reject hypothesis $H_{0}$. The calculation is as follows.

```
tlak <- 2*1:6
pruhyb <- c(14, 35, 48, 61, 80, 93)
```

$\mathrm{g}<-\operatorname{lm}($ pruhyb $\sim$ tlak -1)
summary (g)

Call:

```
lm(formula = pruhyb * tlak - 1)
```

Residuals:


Residual standard error: 2.171 on 5 degrees of freedom Multiple R-squared: 0.999, Adjusted R-squared: 0.9987
F-statistic: 4767 on 1 and 5 DF , p-value: 1.207e-08
confint (g)
$2.5 \% ~ 97.5 \%$
tlak 7.5646018 .149685
plot(pruhyb ~ tlak, las=1, xlab="pressure", ylab="bend")
abline (g)

### 18.2.2 Regression line

Consider the model

$$
\begin{equation*}
Y_{i}=\beta_{0}+\beta_{1} x_{i}+e_{i}, \quad i=1, \ldots, n . \tag{18.1}
\end{equation*}
$$

We have $\boldsymbol{\beta}=\left(\beta_{0}, \beta_{1}\right)^{\prime}$ and

$$
\boldsymbol{X}=\left(\begin{array}{cc}
1 & x_{1} \\
\ldots & . \\
1 & x_{n}
\end{array}\right), \quad \boldsymbol{X}^{\prime} \boldsymbol{X}=\left(\begin{array}{cc}
n & \sum x_{i} \\
\sum x_{i} & \sum x_{i}^{2}
\end{array}\right), \quad \boldsymbol{X}^{\prime} \boldsymbol{Y}=\binom{\sum Y_{i}}{\sum x_{i} Y_{i}}
$$

Denote

$$
\bar{Y}=\frac{1}{n} \sum Y_{i}, \quad \bar{x}=\frac{1}{n} \sum x_{i} .
$$



Figure 18.1: Bend of material in dependence on pressure

We obtain estimators

$$
b_{1}=\frac{\sum x_{i} Y_{i}-n \bar{x} \bar{Y}}{\sum x_{i}^{2}-n \bar{x}^{2}}, \quad b_{0}=\bar{Y}-b_{1} \bar{x}, \quad s^{2}=\frac{\sum Y_{i}^{2}-b_{0} \sum Y_{i}-b_{1} \sum x_{i} Y_{i}}{n-2} .
$$

We show an interpretation of $b_{1}$. Assume that $x_{i} \neq \bar{x}$ holds for all $i$. Then

$$
b_{1}=\frac{\sum_{i}\left(x_{i}-\bar{x}\right)\left(Y_{i}-\bar{Y}\right)}{\sum_{j}\left(x_{j}-\bar{x}\right)^{2}}=\sum_{i} \frac{\left(x_{i}-\bar{x}\right)^{2}}{\sum_{j}\left(x_{j}-\bar{x}\right)^{2}} \frac{Y_{i}-\bar{Y}}{x_{i}-\bar{x}}=\sum_{i} w_{i} \operatorname{tg} \alpha_{i},
$$

where weight $w_{i}$ is

$$
w_{i}=\frac{\left(x_{i}-\bar{x}\right)^{2}}{\sum_{j}\left(x_{j}-\bar{x}\right)^{2}}
$$

and $\alpha_{i}$ is the angle between horizontal line and the line joining points $\left(x_{i}, Y_{i}\right)$ and $(\bar{x}, \bar{Y})$. Sum of the weights $w_{i}$ is one. Thus the regression line is weighted average of all lines which go through points $\left(x_{i}, Y_{i}\right)$ and their center of gravity $(\bar{x}, \bar{Y})$.

For testing $H_{0}: \beta_{1}=0$ calculate

$$
T_{1}=\frac{b_{1}}{s} \sqrt{\sum x_{i}^{2}-n \bar{x}^{2}} .
$$

If $\left|T_{1}\right| \geq t_{n-2}(\alpha)$, then $H_{0}$ will be rejected.
Let $\boldsymbol{c}=(1, x)^{\prime}$, where $x$ is a given number. We verify that

$$
\boldsymbol{c}^{\prime}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{c}=\frac{1}{n}+\frac{(x-\bar{x})^{2}}{\sum x_{i}^{2}-n \bar{x}^{2}} .
$$

Theorem 15.8 on p. 132 implies that the interval with endpoints

$$
\begin{equation*}
b_{0}+b_{1} x \mp t_{n-2}(\alpha) s \sqrt{\frac{1}{n}+\frac{(x-\bar{x})^{2}}{\sum x_{i}^{2}-n \bar{x}^{2}}} \tag{18.2}
\end{equation*}
$$

with probability $1-\alpha$ covers the value $\beta_{0}+\beta_{1} x$ (and so it is confidence interval for $\beta_{0}+\beta_{1} x$ with confidence coefficient $1-\alpha$ ). Formula (18.2) defines a hyperbola and thus a confidence band. The band ensures that a value $\beta_{0}+\beta_{1} x$ will be covered with probability $1-\alpha$ but not the line $y=\beta_{0}+\beta_{1} x$. Such a confidence band can be also derived. Instead of $t_{n-2}(\alpha)$ number $\sqrt{2 F_{2, n-2}(\alpha)}$ must be used.

Now, we calculate prediction interval and prediction confidence band. Assume that a new observation $Y_{0}$ corresponds to the row $\boldsymbol{x}_{0}^{\prime}=\left(1, x_{0}\right)$. We get

$$
\boldsymbol{x}_{0}^{\prime}\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1} \boldsymbol{x}_{0}+1=\frac{1}{n}+\frac{\left(x_{0}-\bar{x}\right)^{2}}{\sum x_{i}^{2}-n \bar{x}^{2}}+1
$$

Formula (15.6) on p. 135 defines interval with endpoints

$$
b_{0}+b_{1} x_{0} \mp t_{n-k}(\alpha) s \sqrt{1+\frac{1}{n}+\frac{\left(x_{0}-\bar{x}\right)^{2}}{\sum x_{i}^{2}-n \bar{x}^{2}}}
$$

It is confidence interval for $Y_{0}$ with confidence coefficient $1-\alpha$. If $x$ varies continuously, we get prediction confidence band.

Example 18.2 (Continuation of example 6.3, p. 61.) Concentration of the milk acid in the blood of mothers (values $x_{i}$ ) and their newborn children (values $Y_{i}$ ) was measured. The results are introduced in tab. 6.1 and in tab. 18.2. We assume that the concentration of the milk acid in blood of new born children depends linearly on the concentration in blood of mother.

Table 18.2: Concentration of milk acid

| $x_{i}$ | 40 | 64 | 34 | 15 | 57 | 45 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $Y_{i}$ | 33 | 46 | 23 | 12 | 56 | 40 |

We insert data and calculate basic characteristics.

```
matky <- c(40,64,34, 15,57,45)
deti <- c(33,46,23,12,56,40)
g <- lm(deti ~ matky)
summary(g)
Call:
lm(formula = deti * matky)
Residuals:
\begin{tabular}{rrrrrr}
1 & 2 & 3 & 4 & 5 & 6 \\
0.1358 & -7.3677 & -4.7384 & 0.4936 & 8.6125 & 2.8642
\end{tabular}
Coefficients:
    Estimate Std. Error t value Pr(>|t|)
(Intercept) -1.3082 7.3615 -0.178 0.86759
matky 0.8543 0.1623 5.265 0.00623 **
```

```
Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ', 1
Residual standard error: 6.312 on 4 degrees of freedom
Multiple R-Squared: 0.8739, Adjusted R-squared: 0.8424
F-statistic: 27.72 on 1 and 4 DF, p-value: 0.006232
confint(g)
    2.5 % 97.5 %
(Intercept) -21.7469727 19.130521
matky 0.4038278 1.304795
```

The results are presented graphically in fig. 18.2.

```
pred.frame <- data.frame(matky=seq(15, 65, by=0.5))
pred.matky <- pred.frame$matky
pp <- predict(g, int="p", newdata=pred.frame)
pc <- predict(g, int="c", newdata=pred.frame)
plot(matky, deti, xlim=c(15,65), xlab="mothers",
    ylab="children", ylim=range(0,70,deti, pp, na.rm=T), pch=16, las=1)
abline(g)
matlines(pred.matky, pc, lty=c(1,2,2), col="black")
matlines(pred.matky, pp, lty=c(1,3,3), col="black")
```



Figure 18.2: Concentration of milk acid

We have got $b_{0}=-1.3082, b_{1}=0.8543$. Estimator $b_{1}$ is significant, its $p$-value is 0.00623 . Confidence bands are presented in fig. 18.2. Confidence interval for $\beta_{1}$ is (0.40, 1.30).

Asymptotic properties of estimators can be derived without assumption of normality. It suffices to assume that $e_{1}, \ldots, e_{n}$ are random independent variables with zero expectation and equal variance $\sigma^{2}>0$.

Theorem 18.3 Let exist numbers $c_{0}, c_{1}$ such that for $n \rightarrow \infty$ it holds

$$
\frac{1}{n} \sum_{i=1}^{n} x_{i} \rightarrow c_{0}, \quad \frac{1}{n} \sum_{i=1}^{n} x_{i}^{2} \rightarrow c_{1},
$$

and $c_{1}-c_{0}^{2}>0$. Then $b_{0}$ and $b_{1}$ are consistent estimators of parameters $\beta_{0}$ and $\beta_{1}$. If additionally $\mathrm{E}\left(Y_{i}-\mathrm{E} Y_{i}\right)^{4} \leq D$ holds for some $D>0$, then $s^{2}$ is consistent estimator of parameter $\sigma^{2}$.

Proof see Dupač, Hušková (1999), p. 141.
Theorem 18.4 Assume that the assumptions of theorem 18.3 are fulfilled. Moreover, assume that

$$
\limsup _{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^{n}\left|x_{i}\right|^{3}<\infty
$$

Then each of variables

$$
\frac{b_{0}-\beta_{0}}{\sqrt{\operatorname{var} b_{0}}}, \quad \frac{b_{1}-\beta_{1}}{\sqrt{\operatorname{var} b_{1}}}
$$

has asymptotically distribution $\mathrm{N}(0,1)$.
Proof see Dupač, Hušková (1999), str. 143.

### 18.2.3 Quadratic regression

Under this name we understand the model

$$
\begin{equation*}
Y_{i}=\beta_{0}+\beta_{1} x_{i}+\beta_{2} x_{i}^{2}+e_{i}, \quad i=1, \ldots, n . \tag{18.3}
\end{equation*}
$$

Here we have

$$
\boldsymbol{X}=\left(\begin{array}{ccc}
1 & x_{1} & x_{1}^{2} \\
\ldots & \cdots & \cdots \\
1 & x_{n} & x_{n}^{2}
\end{array}\right), \quad \boldsymbol{X}^{\prime} \boldsymbol{X}=\left(\begin{array}{ccc}
n & \sum x_{i} & \sum x_{i}^{2} \\
\sum x_{i} & \sum x_{i}^{2} & \sum x_{i}^{3} \\
\sum x_{i}^{2} & \sum x_{i}^{3} & \sum x_{i}^{4}
\end{array}\right), \quad \boldsymbol{X}^{\prime} \boldsymbol{Y}=\left(\begin{array}{c}
\sum Y_{i} \\
\sum x_{i} Y_{i} \\
\sum x_{i}^{2} Y_{i}
\end{array}\right) .
$$

Estimator $\boldsymbol{b}=\left(b_{0}, b_{1}, b_{2}\right)^{\prime}$ of vector $\boldsymbol{\beta}=\left(\beta_{0}, \beta_{1}, \beta_{2}\right)^{\prime}$ can be obtained by solving system of equations

$$
\boldsymbol{X}^{\prime} \boldsymbol{X} b=\boldsymbol{X}^{\prime} \boldsymbol{Y}
$$

Then we obtain

$$
s^{2}=\frac{1}{n-3}\left(\sum Y_{i}^{2}-b_{0} \sum Y_{i}-b_{1} \sum x_{i} Y_{i}-b_{2} \sum x_{i}^{2} Y_{i}\right) .
$$

Denote

$$
\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1}=\left(\begin{array}{lll}
v_{00} & v_{01} & v_{02} \\
v_{10} & v_{11} & v_{12} \\
v_{20} & v_{21} & v_{22}
\end{array}\right)
$$

Very often we test the hypothesis $H_{0}: \beta_{2}=0$. This is a test if the dependence $Y_{i}$ on $x_{i}$ is linear. If $H_{0}$ holds then it follows from theorem 15.7 that

$$
T_{2}=\frac{b_{2}}{\sqrt{s^{2} v_{22}}} \sim \mathrm{t}_{n-3} .
$$

In case $\left|T_{2}\right| \geq t_{n-3}(\alpha)$ the hypothesis $H_{0}$ is rejected.
Consider test of hypothesis $H_{0}^{\prime}: \beta_{1}=\beta_{2}=0$. If $H_{0}^{\prime}$ holds, then $Y_{i}$ does not depend on $x_{i}$. Alternative hypothesis is that $Y_{i}$ depends on $x_{i}$ either linearly or quadratically. For testing $H_{0}^{\prime}$ we use theorem 15.12. We know that residual sum of squares is $R=(n-3) s^{2}$. Here $k=3$ (matrix $\boldsymbol{X}$ has three columns and rank 3). If $H_{0}^{\prime}$ holds, we have submodel

$$
Y_{i}=\beta_{0}+e_{i}
$$

Least squares estimator of the parameter $\beta_{0}$ is $\bar{Y}$, so that

$$
R_{1}=\sum\left(Y_{i}-\bar{Y}\right)^{2}=\sum Y_{i}^{2}-n \bar{Y}^{2} .
$$

We have two independent linear bindings $\left(\beta_{1}=0, \beta_{2}=0\right)$, so that $k-l=t=2$. Thus

$$
F=\frac{\left(R_{1}-R\right) / 2}{R /(n-3)} \sim \mathrm{F}_{2, n-3} .
$$

If $F \geq F_{2, n-3}(\alpha)$, we reject $H_{0}^{\prime}$.
Example 18.5 In tab. 18.3 we have measurements of density of water $\rho$ in dependence on temperature. Temperature is introduced in degrees of Celsius, density in $\mathrm{kg} / \mathrm{dm}^{3}$. See fig. 18.3.

Table 18.3: Density of water

| $t$ | $\rho$ | $t$ | $\rho$ | $t$ | $\rho$ |
| ---: | :---: | :---: | :---: | ---: | :---: |
| 0 | 1,000 | 40 | 0,993 | 80 | 0,973 |
| 10 | 1,000 | 50 | 0,987 | 90 | 0,964 |
| 20 | 0,997 | 60 | 0,983 | 100 | 0,958 |
| 30 | 0,996 | 70 | 0,978 |  |  |

We calculate

```
teplota <- 10*0:10
hustota <- c(1, 1, 0.997, 0.996, 0.993, 0.987,
0.983, 0.978, 0.973, 0.964, 0.958)
g <- lm(hustota ~ teplota + I(teplota^2))
summary (g)
Call:
lm(formula = hustota ` teplota + I(teplota^2))
Residuals:
\begin{tabular}{rrrrr} 
Min & \(1 Q\) & Median & \(3 Q\) & Max \\
\(-1.114 e-03\) & \(-5.753 e-04\) & \(-6.853 e-05\) & \(6.727 e-04\) & \(1.052 \theta-03\)
\end{tabular}
Coefficients:
    Estimate Std. Error t value Pr(>|t|)
(Intercept) 1.000e+00 6.870e-04 1456.302 < 2e-16 ***
teplota -6.312e-05 3.196e-05 -1.975 0.0837 .
I(teplota~2) -3.660e-06 3.078e-07 -11.888 2.3e-06 ***
```



Figure 18.3: Density of water in dependence on temperature

```
---
Signif. codes: 0 *** 0.001 ** 0.01 * 0.05 . 0.1 1
Residual standard error: 0.0009017 on 8 degrees of freedom
Multiple R-squared: 0.997, Adjusted R-squared: 0.9962
F-statistic: 1316 on 2 and 8 DF, p-value: 8.428e-11
```

Program for figure is
pred.frame <- data.frame(teplota=seq(0, 100, by=5))
pred.hustota <- predict(g, newdata=pred.frame)
new <- pred.frame\$teplota
plot(teplota, hustota, ylim=range(hustota, pred.hustota), las=1)
matlines(new, pred.hustota)

Since $F$ is significant, we proved that density of water depends on its temperature. The coefficient by quadratic component is significant, we reject hypothesis that the dependence is linear.

### 18.2.4 Two independent variables

Consider the model

$$
Y_{i}=\beta_{0}+\beta_{1} x_{i}+\beta_{2} z_{i}+e_{i}, \quad i=1, \ldots, n
$$

so that

$$
\begin{gathered}
\boldsymbol{X}=\left(\begin{array}{ccc}
1 & x_{1} & z_{1} \\
\ldots & \cdots & \cdots \\
1 & x_{n} & z_{n}
\end{array}\right), \\
\boldsymbol{X}^{\prime} \boldsymbol{X}=\left(\begin{array}{ccc}
n & \sum x_{i} & \sum z_{i} \\
\sum x_{i} & \sum x_{i}^{2} & \sum x_{i} z_{i} \\
\sum z_{i} & \sum x_{i} z_{i} & \sum z_{i}^{2}
\end{array}\right), \quad \boldsymbol{X}^{\prime} \boldsymbol{Y}=\left(\begin{array}{c}
\sum Y_{i} \\
\sum x_{i} Y_{i} \\
\sum z_{i} Y_{i}
\end{array}\right) .
\end{gathered}
$$

Estimator $\boldsymbol{b}=\left(b_{0}, b_{1}, b_{2}\right)^{\prime}$ of vector $\boldsymbol{\beta}=\left(\beta_{0}, \beta_{1}, \beta_{2}\right)^{\prime}$ can be calculated from the system of normal equation

$$
\boldsymbol{X}^{\prime} \boldsymbol{X} \boldsymbol{b}=\boldsymbol{X}^{\prime} \boldsymbol{Y}
$$

Using formulas

$$
R=\sum Y_{i}^{2}-b_{0} \sum Y_{i}-b_{1} \sum x_{i} Y_{i}-b_{2} \sum z_{i} Y_{i}, \quad s^{2}=\frac{R}{n-3}
$$

we obtain residual sum of squares $R$ and residual variance $s^{2}$. Elements of the matrix $\left(\boldsymbol{X}^{\prime} \boldsymbol{X}\right)^{-1}$ will be again denoted $v_{i j}, i, j=0,1,2$. If we want to test $H_{0}: \beta_{2}=0$, we calculate

$$
T_{2}=\frac{b_{2}}{\sqrt{s^{2} v_{22}}}
$$

In the case that $\left|T_{2}\right| \geq t_{n-3}(\alpha)$ we reject $H_{0}$ and it is proved that $Y_{i}$ depends on $z_{i}$. Similarly, for testing $H_{0}^{\prime}: \beta_{1}=0$ calculate

$$
T_{1}=\frac{b_{1}}{\sqrt{s^{2} v_{11}}}
$$

and $H_{0}^{\prime}$ will be rejected, when $\left|T_{1}\right| \geq t_{n-3}(\alpha)$. If $H_{0}^{\prime}$ is rejected, the dependence $Y_{i}$ on $x_{i}$ is proved.

Consider testing hypothesis $H_{0}^{*}: \beta_{1}=\beta_{2}=0$. We start with calculation

$$
R_{1}=\sum Y_{i}^{2}-n \bar{Y}^{2}
$$

General theory gives that the variable

$$
F=\frac{\left(R_{1}-R\right) / 2}{R /(n-3)}
$$

has distribution $\mathrm{F}_{2, n-3}$ when $H_{0}^{*}$ holds. If $F \geq F_{2, n-3}(\alpha)$, we reject $H_{0}^{*}$. This will prove that $Y_{i}$ depends either on $x_{i}$ or on $z_{i}$ or on both $x_{i}$ and $z_{i}$.

Example 18.6 (Continuation of example 6.3, p. 61.)
Remember that in year 1957 statisticians investigated expenses $Y_{i}$ for food and drinks in households in dependence on number $X_{i}$ of people in the household and on net earnings $Z_{i}$. The data concerning 7 randomly chosen households are given in Tab. 6.2. Assume that the dependence of expenses on remaining two variables is linear and calculate regression analysis. The program is

```
vyd <- c(4,3,4,1,6,4,5)
velik <- c(4, 2, 4, 1,5,3,4)
prijem <- c(10,8,12,3,15,12,13)
potr <- data.frame(vyd,velik,prijem)
g <- lm(vyd ~ velik + prijem)
summary(g)
Call:
lm(formula = vyd ~ velik + prijem)
Residuals:
```



Statistic F is significant. Expenses for food depend on number of people in the household and on income. However, influence of number of people is not significant. The number of data is very small.

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## Author Index

Agresti A., 94
Anděl J., 10, 24, 28, 61-63, 89, 104, 106
Andersen S. L., 144
Angus J. E., 17
Barr D. R., 13, 73
Bennett B. M., 77
Bhapkar V. P., 148
Box G. E. P., 144
Brown L., 125
Brown, M. B., 144
Campbell D. B., 73
Conover W. J., 73, 144
Cramér H., 59, 60, 89
D'Agostino R. B., 123
Dalgaard P., 107
Davison T., 73
Deshpande J. V., 148
Domaǹski C., 109
Dupač V., 168
Eberhardt K. R., 122
Edwards A. W. F., 94
Fan Y, 58
Farnsworth D. L., 75
Fisher R. A., 43, 94
Fliegner M. A., 122
Forsythe A. B., 144
Gart J. J., 123
Glaser R. E., 144
Gnedenko B. V., 72
Goodman L. A., 94
Hájek J., 79, 109, 147
Hátle J., 127, 157
Haunsperger D. B., 148, 149
Hayter A. J., 140
Hilferty M. M., 43

Hodges J. L., 81
Hollander M., 81
Holm S., 155
Hooker R. H., 30
Hušková M., 168
Hyndman R. J., 58
Iman R. L., 72
James G. S., 145
Kendall M. G., 30, 43, 87, 92, 95, 101
Kiefer J., 109
Konishi S., 43
Krauth J., 106
Krejn M. T., 14
Laga J., 72, 109
Layard M. W. J., 144
Lehmann E. L., 53, 81
Levene H., 144
Li X., 125
Likeš J., 72, 109, 127, 157
Lilliefors H. W., 72
Ling R. F., 83
Manoukian E. B., 144
Mantel N., 73
McNemar Q., 104
Miller R. G., 147
Nagarsenker P. B., 144
Nam J.-M., 123
Naus J. I., 109
Neményi P., 147
Newcombe R., 124
Noether G. E., 126
Nudelman A. A., 14
O'Cinneide C. A., 18
Oprian C. A., 73
Osborn J. F., 123

Peizer D. B., 83
Pratt J. W., 83
Rao C. R., 14, 43, 89
Ripley B. D., 57
Saari D. G., 148, 149
Sachs L., 101
Santer T. J., 123
Shao J., 15
Simonoff J. S., 84
Smirnov N. V., 109
Snell M. K., 123
Stoops G., 13
Stuart A., 43, 106
Šidák Z., 79, 109, 147
van der Waerden B. L., 101
Venables W. N., 57
Verzani J., 57
Walsh J. E., 80
Welch B. L., 113, 145
Williams D., 52, 53
Wilson E. B., 43
Winterbottom A., 43
Wolf E. H., 109
Wolfe D. A., 81
Yule G. U., 30, 87, 92, 95

## Topic Index

$2 \times 2$ contingency table, 123
$\chi_{1}^{2}, 34$
t distribution, 40, 74
$H$ test, 147
$p$-value, 69
$z$ transformation, 43
absolute moment, 11
adjusted coefficient of determination, 62
alternative hypothesis, 67
balanced classification, 160
balanced model, 140
Bartlett test, 143
Bernoulli distribution, 52, 54
best critical set, 68
best linear unbiased estimator, 133
bias, 51
biased estimator, 51
binomial distribution, 30, 42, 54, 76, 83, 121
BLUE, 133
boxplot, 107
Brandt-Snedecor formula, 153
Cauchy distribution, 13, 40
central moment, 11
Clopper-Pearson confidence interval, 86
coefficient of multiple correlation, 27
conditional density, 24
conditional distribution function, 23
conditional maximum likelihood estimator, 94
confidence coefficient, 65
confidence interval, 166
confidence interval based on score test, 124
confidence interval recentred, 125
consistent estimator, 54
contingency table, 90, 122
continuous distribution, 11, 19
convolution of densities, 37
convolution theorem, 37
Cook statistics, 132
corrected statistic, 147
correlation coefficient, 23, 26, 58
correlation matrix, 26
correlation matrix of random vectors, 26
covariance, 20
covariance matrix, 21
critical set, 67
critical value, 74
degenerated distribution, 14
delta method, 126
density, 11
discrete distribution, 11
distribution, 10
distribution F, 40
distribution $\chi_{n}^{2}, 38,39,43$
distribution Fisher-Snedecor, 40
distribution function of the random vector, 19
elementary event, 9
empirical distribution function, 57, 71
empirical frequencies, 87
empirical quantile, 57
error of the first kind, 67
error of the second kind, 67
estimator, 46
extrapolation, 134
first quartile, 58
Fisher, 43
Fisher transformation, 60
geometric distribution, 52, 54
Glivenko-Cantelli theorem, 72
histogram, 71, 107
Hodges-Lehmann estimator, 80
Holm method, 155
homogeneity of marginal probabilities, 105
hypothesis of homogeneity, 121, 152
hypothesis of symmetry, 103
characteristic function, 57
idempotent matrix, 31
independent events, 22
independent variables, 22
independent vectors, 22
influences, 132
interquartile range, 58
interval $q, 85$
interval estimator, 51
Kolmogorov-Smirnov test, 119
Kruskal-Wallis test, 144, 146
kurtosis, 12, 60
least squares method, 129
level of test, 68
Levene test, 116, 144
leverages, 132
linear model, 129
log-normal distribution, 13
lower quartile, 58
Lymski borelioza, 84
Mann-Whitney test, 119
marginal density, 19
marginal distribution function, 19
marginal frequencies, 90
marginal probabilities, 90
maximum likelihood method, 69
McNemar test, 103
mean value, 10
measurable mapping, 10
measurable space, 9
median, 17, 58, 76, 77, 79
method of minimal $\chi^{2}, 88$
modified method of minimum $\chi^{2}, 88$
moment, 11
multidimensional normal distribution, 38
multidimensional sign test, 77
multinomial distribution, 30, 90
Newcomb confidence interval, 124
NNLO, 145
non-central t distribution, 157
non-central hypergeometric distribution, 94
normal distribution, 10, 14, 33, 38, 51
normal equations, 130
normalization transformation, 43
normed residuals, 132
nuisance parameter, 65
null hypothesis, 67
odds ratio, 93
one-sample Kolmogorov-Smirnov test, 71
one-sample Wilcoxon test, 77, 100
one-sided confidence interval, 74
one-sided sign test, 77
one-sided test, 74
one-way analysis of variance, 137, 146
ordered random sample, 46
paired $t$ test, 99
paired sign test, 100
parametric space, 51,67
partial correlation coefficient, 29
percentile, 17
pivotal statistics, 65, 67
point estimator, 51
Poisson distribution, 42, 53, 85
pooled sample, 117, 146
power of test, 157
power of the test, 67
prediction confidence band, 166
prediction interval, 166
probability, 9
probability measure, 9
pseudomedian, 80
quadratic regression, 168
quantile function, 16
quantiles, 16
random event, 9
random matrix, 19
random variable, 10
random vector, 19
range, 47, 139, 148
rank, 48
rectangular distribution, 13, 16, 55
regression model, 129
regular normal distribution, 35
residual sum of squares, 130

Residual sum of squares, 138
residual variance, $25,27,131,138$
rugplot, 71
sample coefficient of determination, 62
sample coefficient of multiple correlation, 61 sample coefficient of partial correlation, 62
sample correlation coefficient, 43
sample correlation matrix, 61
sample mean, 45
sample median, 57
sample quantile, 58
sample variance, 52
score confidence interval, 85
score interval, 85
scores, 117
sequence of moments, 14
series of moments, 15
shift, 119
sign test, 76, 83
simple hypothesis, 67
simple random sample, 45
Simpson paradox , 95
simultaneous density, 19
simultaneous distribution function, 19
singular normal distribution, 35
size of the sample, 45
skewness, 12, 60
Smirnov theorem, 108
space of elementary events, 9
Spearman correlation coefficient, 100
Spearman correlation coefficient korrected, 101
square-root transformation, 42
standard confidence interval, 84,85
standard deviation, 12
standard normal distribution, 14
statistics, 51
step function, 11
stripchart, 71, 107
Stuart test, 105
Student distribution, 40, 74
Student non-central distribution, 40
studentized range, 139
submodel, 135
symmetric distribution, 80
table of analysis of variance, 138
test $\chi^{2}, 87$
test $t$ two-sample, 112
test independence, 90
test of homogeneity, 151
testing homogeneity, 121
the length of the confidence interval, 66
theoretical frequencies, 87
theoretical odds ratio, 93
third quartile, 58
tie, 119
total sum of squares, 138
transformation, 33
transformation stabilizing variance, 41, 60
truncated Poisson distribution, 53
Tukey theorem, 139
Tukey method, 138-140
two independent variables, 171
two-dimensional normal distribution, 36, 43
two-sample Wilcoxon test, 146
twodimensional normal distribution, 59
unbiased estimator, 46, 51, 131
unconditional maximum likelihood estimator, 94
uncorrelated variables, 23
upper quartile, 58
Vandermond convolutory formula, 96
variance, 12
variance matrix, 20
vector of errors, 129
vector of residuals, 132
Wald confidence interval, 84, 124
Walsh mean, 80
weighted average, 133
Welch test, 112
Welch two-sample test, 113
Wilcoxon two-sample test, 112, 117
Wilson confidence interval, 85, 124

